## (104 Drive

## P19000 Series

Control of drives in industrial applications High-performance vector control inverter



Nameplate instruction:

| inverter model | C |  |
| :---: | :---: | :---: |
|  | TYPE | PI9100 7R5G3 |
| input rating $\longrightarrow$ | SOURCE | $3 ¢ 380 \mathrm{~V} 50-60 \mathrm{~Hz}$ |
| output rating $\longrightarrow$ | OUTPUT | 7.5KW 17A $0.00-400.0 \mathrm{~Hz}$ |
| Serial No. \& Bar Code $\longrightarrow$ |  | ZPB1A0100001 |

## Model Description:



## (In ${ }^{4}$ Drive

## More stable deconven out

## This is Pi8000

Technical Features:

5.Built in simple PLC function , 16 sections speed is available.

9.Reliable insulation design, ensure the safety of inverter

2.Mode of speed control: Senseless Vector Control, Sensor Close Loop Vector Control, V/F control

6.Multi-language OLED could display 3 parameter groups at the same time

10.Support the standard Modbus communication protocol

3.Vector control in asynchronous and permanent synchronous motor is available feature motor parameter auto-tuning.

7.Rotating freely with "one key shuttle keyboard"

11.Strengthened coating, adapt to tough environment

$4.150 \%$ torque when at low speed ( 0.5 ) running in the sensorless vector control mode.

8.Optimized ventilation design


EMC

## Standard specification:

|  | Item | Specification |
| :---: | :---: | :---: |
| Power | Voltage and frequency levels | Single-phase $220,50 / 60 \mathrm{~Hz}$ Three-phase $220 \mathrm{~V}, 50 / 60 \mathrm{~Hz}$ <br> Single-phase $380,50 / 60 \mathrm{~Hz}$ Three-phase $480 \mathrm{~V}, 50 / 60 \mathrm{~Hz}$ <br> Three-phase $690 \mathrm{~V}, 50 / 60 \mathrm{~Hz}$ |
|  | Allowable fluctuation | Voltage: $\pm 15 \%$ Frequency: $\pm 5 \%$ |
| Control system | Control system | High performance vector control inverter based on DSP |
|  | Output frequency | Vector control: 0 to 300 Hz V/F control:0 to 3200 Hz |
|  | Control method | V/F control, vector control W/O PG, vector control W/PG |
|  | Automatic torque boost function | Realize low frequency ( 1 Hz ) and large output torque control under the V/F control mode. |
|  | Acceleration/deceleration control | Straight or S-curve mode. Four times available and time range is 0.0 to 6500.0 s . |
|  | V/F curve mode | Linear,square root/m-th power, custom V/F curve |
|  | Over load capability | G type:rated current 150\%-1 minute, rated current $180 \%-2$ seconds |
|  |  | F type:rated current 120\%-1 minute, rated current 150\%-2 seconds |
|  | Maximum frequency | Vector control:0 to 300 Hz V/F control:0 to 3200 Hz |
|  | Carrier Frequency | 0.5 to 15 kHZ ;automatically adjust carrier frequency according to the load characteristics. |
|  | Input frequency resolution | Digital setting: 0.01 Hz Analog setting: maximum frequency $\times 0.025 \%$ |
|  | Start torque | G type: $0.5 \mathrm{~Hz} / 150 \%$ (vector control W/O PG) F type: $0.5 \mathrm{~Hz} / 100 \%$ (vector control W/O PG) |
|  | Speed range | 1:100 (vector control W/O PG) 1:1000 (vector control W/PG) |
|  | Steady-speed precision | Vector control W/O PG: $\leqslant \pm 0.5 \%$ (rated synchronous speed) <br> Vector control W/PG: $\leqslant \pm 0.02 \%$ (rated synchronous speed) |
|  | Speed control accuracy | Vector control W/O PG $\leqslant \pm 0.3 \%$ ( rated synchronous speed ) |
|  | Torque response | $\leqslant 40 \mathrm{~ms}$ (vector control W/O PG) $\leqslant 5 \mathrm{~ms}$ ( W/PG ) |
|  | Torque boost | Automatic torque boost; manual torque boost( $0.1 \%$ to $30.0 \%$ ) |
|  | DC braking | DC braking frequency: 0.0 Hz to max. frequency, braking time: 0.0 to 36.0 seconds, braking current value: $0.0 \%$ to $100.0 \%$ |
|  | Jogging control | Jog Frequency Range: 0.00 Hz to max. frequency; Jog Ac/deceleration time: 0.0 s to 3600.0 s |
|  | Multi-speed operation | Achieve up to 16-speed operation through the control terminal |
|  | Built-in PID | Easy to realize closed-loop control system for the process control. |
|  | Automatic voltage regulation(AVR) | Automatically maintain a constant output voltage when the voltage of electricity grid changes |
|  | Torque limit and control | "Excavator" feature - torque is automatically limited during the operation to prevent frequent overcurrent trip;the closed-loop vector mode is used to control torque. |
| Personalization function | Self-inspection of peripherals after power-on | After powering on, peripheral equipment will perform safety testing, such as ground, short circuit,etc. |
|  | Common DC bus function | Multiple inverters can use a common DC bus. |
|  | Cycle-by-cycle current limiting | The current limiting algorithm is used to reduce the inverter overcurrent probability, and improve whole unit anti-interference capability. |
|  | Timing control | Timing control function: time setting range(0h to 65535h). |

## Standard specification:

| Item |  |  | Specification |
| :---: | :---: | :---: | :---: |
| Running | input signal | Running method | Keyboard/terminal/communication |
|  |  | Frequency setting | 10 frequency settings available, including adjustable DC(0 to 10V), adjustable DC(0 to 20 mA ), panel potentiometer, etc. |
|  |  | Start signal | Rotate forward/reverse |
|  |  | Multi-speed | At most 16-speed can be set(run by using the multi-function terminals or program) |
|  |  | Emergency stop | Interrupt controller output |
|  |  | Wobbulate run | Process control run |
|  |  | Fault reset | When the protection function is active, you can automatically or manually reset the fault condition. |
|  |  | PID feedback signal | Including DC(0 to 10V), DC(0 to 20mA) |
|  | output signal | Running status | Motor status display, stop, ac/deceleration, constant speed, program running status. |
|  |  | Fault output | Contact output - AC 250V 5A, DC 30V 5A |
|  |  | Analog output | Two-way analog output, 16 signals can be selected such as frequency,current,voltage and other, output signal range ( 0 to $10 \mathrm{~V} / 0$ to 20 mA ). |
|  |  | Output signal | At most 3-way output, there are 40 signals each way |
|  | Run function |  | Limit frequency,jump frequency, frequency compensation, auto-tuning, PID control |
|  | DC current braking |  | Built-in PID regulates braking current to ensure sufficient braking torque under no overcurrent condition. |
|  | Running command channel |  | Three channels: operation panel, control terminals and serial communication port. They can be switched through a variety of ways. |
|  | Frequency source |  | Total 5 frequency sources: digital, analog voltage, analog current, multi-speed and serial port. They can be switched through a variety of ways. |
|  | Input terminals |  | 6 digital input terminals, compatible with active PNP or NPN input mode, one of them can be for high-speed pulse input(0 to 100 KHZ square wave); 2 analog input terminals for voltage or current input. |
|  | Output terminals |  | 2 digital output terminals, one of them can be for high-speed pulse output( 0 to 100 KHZ square wave); one relay output terminal; 2 analog output terminals respectively for optional range ( 0 to 20 mA or 0 to 10 V ), they can be used to set frequency, output frequency, speed and other physical parameters. |
| Protection function | Inverter protection |  | Overvoltage protection, undervoltage protection, overcurrent protection, overload protection, overheat protection, overcurrent stall protection, overvoltage stall protection, losting-phase protection (optional), external fault, communication error, PID feedback signal abnormalities, PG failure and short circuit to ground protection. |
|  | IGBT temperature display |  | Displays current temperature IGBT |
|  | Inverter fan control |  | Can be set |
|  | Instantaneous power-down restart |  | Less than 15 milliseconds: continuous operation. More than 15 milliseconds: automatic detection of motor speed, instantaneous power-down restart. |
|  | Speed start tracking method |  | The inverter automatically tracks motor speed after it starts |
|  | Parameter protection function |  | Protect inverter parameters by setting administrator Password and decoding |
| display | LED/OLED <br> display <br> keyboard | Running information | Monitoring objects including : running frequency, set frequency, actual motor current, DC bus voltage, output voltage, actual motor speed, cumulative running time, IGBT temperature, PID reference value, PID feedback value, input terminal status, output terminal status, analog AI1 value, analog AI2 value, current stage of multi-speed, torque set value. |
|  |  | Error message | At most save 3 error message, and the time, type, voltage, current, frequency and work status can be queried when the failure is occurred. |
|  | LED display |  | Display parameters |
|  | OLED display |  | Optional, prompts operation content in Chinese/Englishtext. |
|  | Copy parameter |  | Quickly copy parameters by using the special keyboard(only for OLED) |
|  | Key lock and function selection |  | Lock part or all of keys, define the function scope of some keys to prevent misuse. |
| Communication | RS485/R | 232 | The optional completely isolated RS485/RS232 communication module can communicate with the host computer. |
| Environment | Environment temperature |  | -10 cto $40^{\circ} \mathrm{C}$ (temperature at $40^{\circ} \mathrm{C}$ to $50^{\circ} \mathrm{C}$, please derating for use) |
|  | Storage temperature |  | $-20^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ |
|  | Environment humidity |  | Less than $90 \%$ R.H, does not exceed $90 \%$ R.H |
|  | Height and vibration |  | Below 1000 m , below $5.9 \mathrm{~m} / \mathrm{s}^{2}(=0.6 \mathrm{~g}$ ) |
|  | Application sites |  | Indoor where no sunlight or corrosive, explosive gas and water vapor, dust, flammable gas, oil mist, water vapor, drip or salt, etc. |
|  | Altitude |  | Below 1000 m |
|  | Pollution degree |  | 2 |
| Product standard | Product adopts safety standards. |  | IEC61800-5-1:2007 |
|  | Product adopts EMC standards. |  | IEC61800-3:2005 |
|  | Cooling method |  | Forced air cooling and natural air cooling |

## Technical specifications:

| Inverter model | input voltage | rated output power | rated input current | rated output current | match motor | Housing No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| PI9100-0R4G2 | $\begin{gathered} 3 \text { phase } 220 \mathrm{~V} \\ \pm 15 \% \end{gathered}$ | 0.4 | 3.4 | 2.1 | 0.4 | 9 S 2 |
| PI9100-0R7G2 |  | 0.75 | 5 | 3.8 | 0.75 | 9S2 |
| PI9100-1R5G2 |  | 1.5 | 5.8 | 5.1 | 1.5 | 9S2 |
| PI9100-2R2G2 |  | 2.2 | 10.5 | 9 | 2.2 | 953 |
| PI9100-3R7G2 |  | 3.7 | 14.6 | 13 | 3.7 | 9S3 |
| PI9200-5R5G2 |  | 5.5 | 26 | 25 | 5.5 | 9L1 |
| PI9200-7R5G2 |  | 7.5 | 35 | 32 | 7.5 | 9L1 |
| P19200-011G2 |  | 11 | 46.5 | 45 | 11 | 9L1 |
| P19200-015G2 |  | 15.0 | 62 | 60 | 15.0 | 9L2 |
| PI9200-018G2 |  | 18.5 | 76 | 75 | 18.5 | 9L2 |
| P19200-022G2 |  | 22.0 | 91 | 90 | 22.0 | 9L3 |
| PI9200-030G2 |  | 30.0 | 112.0 | 110 | 30.0 | 9L3 |
| P19200-037G2 |  | 37.0 | 157 | 152 | 37.0 | 9L3 |
| P19200-045G2 |  | 45.0 | 180 | 176 | 45.0 | 9L4 |
| P19200-055G2 |  | 55.0 | 214 | 210 | 55.0 | 9L4 |
| PI9200-075G2 |  | 75 | 307 | 304 | 75 | 9L4 |
| P19100-0R7G3 | $\begin{gathered} 3 \text { phase } 380 \mathrm{~V} \\ \pm 15 \% \end{gathered}$ | 0.75 | 3.4 | 2.1 | 0.75 | 9 S 2 |
| P19100-1R5G3 |  | 1.5 | 5.0 | 3.8 | 1.5 | 9S2 |
| P19100-2R2G3 |  | 2.2 | 5.8 | 5.1 | 2.2 | 9 S 2 |
| P19100-3R7G3 |  | 3.7 | 10.5 | 9 | 3.7 | 9S3 |
| P19100-5R5G3/ P19100-5R5F3 |  | 5.5 | 14.6 | 13 | 5.5 | 9S3/9S3 |
| P19100-7R5G3/ P19100-7R5F3 |  | 7.5 | 20.5 | 17 | 7.5 | 9S4/9S4 |
| P19200-011G3/P19200-011F3/ P19200-015F3 |  | 11/11/15 | 26/26/35 | 25/25/32 | 11/11/15 | 9L1/9L1/9L1 |
| P19200-015G3/ P19200-018F3 |  | 15/18.5 | 35/38.5 | 32/37 | 15/18.5 | 9L1/9L1 |
| P19200-018G3/ PI9200-022F3 |  | 18.5/22 | 38.5/46.5 | 37/45 | 18.5/22 | 9L2/9L2 |
| P19200-022G3/ P19200-030F3 |  | 22/30 | 46.5/62 | 45/60 | 22/30 | 9L2/9L2 |
| P19200-030G3/ PI9200-037F3 |  | 30/37 | 62/76 | 60/75 | 30/37 | 9L3/9L3 |
| P19200-037G3/ P19200-045F3 |  | 37/45 | 76/91 | 75/90 | 37/45 | 9L3/9L3 |
| P19200-045G3/ P19200-055F3 |  | 45/55 | 91/112 | 90/110 | 45/55 | 9L4/9L4 |
| PI9200-055G3/ Pl9200-075F3 |  | 55/75 | 112/157 | 110/150 | 55/75 | 9L4/9L4 |
| PI9200-075G3/ PI9200-090F3 |  | 75/90 | 157/180 | 150/176 | 75/90 | 9L4/9L4 |
| PI9200-090G3/ PI9200-110F3 |  | 90/110 | 180/214 | 176/210 | 90/110 | 9L5/9L5 |
| PI9200-110G3/ PI9200-132F3 |  | 110/132 | 214/256 | 210/253 | 110/132 | 9L5/9L5 |
| PI9200-132G3/ PI9200-160F3 |  | 132/160 | 256/307 | 253/304 | 132/160 | 9L6/9L6 |
| PI9200-160G3/PI9200-187F3 |  | 160/187 | 307/345 | 304/340 | 160/187 | 9L6/9L6 |
| PI9300-187G3/ P19300-200F3 |  | 187/200 | $345 / 385$ | 340/380 | 187/200 | $9 \mathrm{C} 1 / 9 \mathrm{C} 1$ |
| PI9300-187G3/ P19300-200F3 |  | 187/200 | 345/385 | 340/380 | 187/200 | 9C2/9C2 |
| PI9300-200G3/ PI9300-220F3 |  | 200/220 | 385/430 | 380/426 | 200/220 | $9 \mathrm{C} 1 / 9 \mathrm{C} 1$ |
| Pl9300-200G3/ PI9300-220F3 |  | 200/220 | 385/430 | 380/426 | 200/220 | 9C2/9C2 |
| PI9300-220G3 |  | 220 | 430 | 426 | 220 | 9C1 |
| PI9300-220G3/ PI9300-250F3 |  | 220/250 | 430/468 | 426/465 | 220/250 | 9C2/9C2 |
| P19300-250G3/ PI9300-280F3 |  | 250/280 | 468/525 | 465/520 | 250/280 | 9C3/9C3 |
| P19300-280G3/ P19300-315F3 |  | 280/315 | 525/590 | 520/585 | 280/315 | 9C3/9C3 |
| P19300-315G3/ Pl9300-355F3 |  | 315/355 | 590/665 | 585/650 | 315/355 | 9C3/9C3 |
| P19300-355G3/ PI9300-400F3 |  | 355/400 | 665/785 | 650/725 | 355/400 | 9C3/9C3 |

## Technical specifications:

| Inverter model | input voltage | rated output power | rated input current | rated output current | match motor | Housing No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| P19100-0R7G4 | $\begin{gathered} 3 \text { phase480V } \\ \pm 15 \% \end{gathered}$ | 0.75 | 3.4 | 2.1 | 0.75 | 9S2 |
| PI9100-1R5G4 |  | 1.5 | 5.0 | 3.8 | 1.5 | 9S2 |
| P19100-2R2G4 |  | 2.2 | 5.8 | 5.1 | 2.2 | 9 S 2 |
| PI9100-3R7G4 |  | 3.7 | 10.5 | 9 | 3.7 | 9S3 |
| P19100-5R5G4/ P19100-5R5F4 |  | 5.5 | 14.6 | 13 | 5.5 | 9S3/9S3 |
| P19100-7R5G4/ P19100-7R5F4 |  | 7.5 | 20.5 | 17 | 7.5 | 9S4/9S4 |
| P19200-011G4/P19200-011F4/P19200-015F4 |  | 11/11/15 | 26/26/35 | 25/25/32 | 11/11/15 | 9L1/9L1/9L1 |
| P19200-015G4/ P19200-018F4 |  | 15/18.5 | 35/38.5 | 32/37 | 15/18.5 | 9L1/9L1 |
| P19200-018G4/ P19200-022F4 |  | 18.5/22 | 38.5/46.5 | $37 / 45$ | 18.5/22 | 9L2/9L2 |
| P19200-022G4/ P19200-030F4 |  | 22/30 | 46.5/62 | 45/60 | 22/30 | 9L2/9L2 |
| P19200-030G4/ P19200-037F4 |  | 30/37 | 62/76 | $60 / 75$ | 30/37 | 9L3/9L3 |
| P19200-037G4/ P19200-045F4 |  | $37 / 45$ | 76/91 | 75/90 | $37 / 45$ | 9L3/9L3 |
| P19200-045G4/ P19200-055F4 |  | 45/55 | 91/112 | 90/110 | 45/55 | 9L4/9L4 |
| P19200-055G4/ P19200-075F4 |  | 55/75 | 112/157 | 110/150 | 55/75 | 9L4/9L4 |
| P19200-075G4/ P19200-090F4 |  | 75/90 | 157/180 | 150/176 | 75/90 | 9L4/9L4 |
| P19200-090G4/ PI9200-110F4 |  | 90/110 | 180/214 | 176/210 | 90/110 | 9L5/9L5 |
| P19200-110G4/ Pl9200-132F4 |  | 110/132 | 214/256 | 210/253 | 110/132 | 9L5/9L5 |
| P19200-132G4/ P19200-160F4 |  | 132/160 | 256/307 | 253/304 | 132/160 | 9L6/9L6 |
| P19200-160G4/PI9200-187F4 |  | 160/187 | 307/345 | 304/340 | 160/187 | 9L6/9L6 |
| P19300-187G4/ Pl9300-200F4 |  | 187/200 | 345/385 | 340/380 | 187/200 | $9 \mathrm{C} 1 / 9 \mathrm{C} 1$ |
| P19300-187G4/ P19300-200F4 |  | 187/200 | 345/385 | 340/380 | 187/200 | 9C2/9C2 |
| P19300-200G4/ Pl9300-220F4 |  | 200/220 | 385/430 | 380/426 | 200/220 | $9 \mathrm{C} 1 / 9 \mathrm{C} 1$ |
| P19300-200G4/ P19300-220F4 |  | 200/220 | 385/430 | 380/426 | 200/220 | $9 \mathrm{C} 2 / 9 \mathrm{C} 2$ |
| P19300-220G4 |  | 220 | 430 | 426 | 220 | $9 \mathrm{C1}$ |
| P19300-220G4/ P19300-250F4 |  | 220/250 | 430/468 | 426/465 | 220/250 | 9C2/9C2 |
| P19300-250G4/ P19300-280F4 |  | 250/280 | 468/525 | 465/520 | 250/280 | 9С3/9С3 |
| P19300-280G4/ P19300-315F4 |  | 280/315 | 525/590 | 520/585 | 280/315 | 9С3/9С3 |
| P19300-315G4/ P19300-355F4 |  | 315/355 | 590/665 | 585/650 | 315/355 | 9С3/9С3 |
| P19300-355G4/ P19300-400F4 |  | 355/400 | 665/785 | 650/725 | 355/400 | 9C3/9C3 |
| P19200-055G6/ P19200-075F6 | $\begin{gathered} 3 \text { phase690V } \\ \pm 15 \% \end{gathered}$ | 55/75 | 70/90 | 62/85 | 55/75 | 9L4/9L4 |
| P19200-075G6/ P19200-090F6 |  | 75/90 | 90/105 | 85/102 | 75/90 | 9L4/9L4 |
| P19200-090G6/ P19200-110F6 |  | 90/110 | 105/130 | 102/125 | 90/110 | 9L5/9L5 |
| PI9200-110G6/ PI9200-132F6 |  | 110/132 | 130/170 | 125/150 | 110/132 | 9L5/9L5 |
| PI9200-132G6/ PI9200-160F6 |  | 132/160 | 170/200 | 150/175 | 132/160 | 9L6/9L6 |
| PI9200-160G6/PI9200-187F6 |  | 160/187 | 200/210 | 175/198 | 160/187 | 9L6/9L6 |
| PI9300-187G6/ PI9300-200F6 |  | 187/200 | 210/235 | 198/215 | 187/200 | 9C2/9C2 |
| P19300-200G6/P19300-220F6 |  | 200/220 | 235/247 | 215/245 | 200/220 | 9C2/9C2 |
| Pl9300-220G6/ P19300-250F6 |  | 220/250 | 247/265 | 245/260 | 220/250 | $9 \mathrm{C} 2 / 9 \mathrm{C} 2$ |
| P19300-250G6/ P19300-280F6 |  | 250/280 | 265/305 | 260/299 | 250/280 | $9 \mathrm{C} 3 / 9 \mathrm{C} 3$ |
| P19300-280G6/ PI9300-315F6 |  | 280/315 | 305/350 | 299/330 | 280/315 | 9C3/9C3 |
| PI9300-315G6/ PI9300-355F6 |  | 315/355 | 350/382 | 330/374 | 315/355 | 9С3/9С3 |
| P19300-355G6/ PI9300-400F6 |  | 355/400 | 382/435 | 374/410 | 355/400 | 9С3/9С3 |
| PI9300-400G6/ P19300-450F6 |  | 400/450 | 435/490 | 410/465 | 400/450 | 9С3/9С3 |
| P19300-450G6/ PI9300-500F6 |  | 450/500 | 490/595 | 465/550 | 450/500 | 9С3/9C3 |
| PI9300-500G6 |  | 500 | 595 | 550 | 500 | 9 C 3 |
| P19300-550G6 |  | 550 | 605 | 590 | 550 | 9 C 3 |

## Fast return on investment, Low Maintenance cost.

## Remarkable enhancement on reliability and continuously running

## Energy-saving:

Advanced energy saving technology
Use energy saving control of frequency converter to realize high efficient running of asynchronous motor

Saving much more energy on synchronous motor
The energy saving control of the inverter combine with high efficient synchronous motor together can gain super energy saving compare to asynchronous motor


Pi9000 Energy-saving effect sample
100 sets , 4 KW fan service in air condition application. Electricity price is 0.11 USD/KWH, Service
time 365 days per year ime :365 days per year.
A asynchronous motor + frequency inverter control
Energy consurionat 1 1003 100 KWH Cost of energy about 211,428 USD.
B synchronous motor + frequency inverter control Energy consumption about $1,754,600 \mathrm{KWH}$ Cost of energy about 194,929USD.
energy saving per year
energy saving: about $148,500 \mathrm{KWH}$. Saving cost of energy about 16,499USD.

## Dinvironmental resistance:

Corrosion resistance, resistance to dust, resistance to vibration and resistance to environment, the strengthening of the product and meanwhile with dust drip-proof type taking protection structure.

## Pass ROSH

Standard product pass ROHS( European specific harmful substance use restrictions).

## Reduce noise

Use Swing PWN to inhibition of electromagnetic interference and reduce the harsh noise

Compare


Suppress the high order harmonic in grid. Built in DC reactor use for suppress high order harmonic ( Optional from 22 KW to 160 KW , standard built in from 187KW and above)

total harmonic distortion 88\%

With reactor

total harmonic distortion 40\%

## (045 Drive



Specifications ( plastic housing: 9S2/9S3/9S4 )


9S2


9S3


9S4


| Model | Power(KW) | Voltage(V) | Current(A) | Shape dimensions(L*W*Hmm) |  |  | Installation dimensions(a*b*dmm) |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 9S2 | $0.4 \sim 1.5$ | 3 phase 220V <br> 3 phase 380V | 2.1~5.1 | 185 | 120 | 178.5 | 174 | 108 | $\varnothing 5.3$ |
|  | $0.75{ }^{\sim} 2.2$ |  | $2.1 \sim 5.1$ |  |  |  |  |  |  |
| 9S3 | $2.2 \sim 3.7$ | 3 phase 220V | 9~13 | 220 | 150 | 185.5 | 209 | 138 | $\varnothing 5.3$ |
|  | $4 \sim 5.5$ | 3 phase 380V | 9~13 |  |  |  |  |  |  |
| 9S4 | 7.5 | 3 phase 380V | 17 | 285 | 180 | 200 | 272 | 167 | $\varnothing 5.5$ |

## Specification:

(wall-mounted metal housing, wring layout from left to right 9L1—9L6 )



## Specification:

(floor type with metal housing, wring layout from left to right 9C1-9C3)



## Installation:

## Installation direction and Vacancy

The inverter shall be installed in the room where it is well ventilated, the wall-mounted installation shall be adopted, and the inverter must keep enough space around adjacent items or baffle (wall). As shown below figure:


## Environment:

Working conditions should be in comply with the regulations of IEC60721-3-3 level 3k3 and GB/T3859,1 section 2.

| environment temperature | $-10^{\circ} \mathrm{C}-40^{\circ} \mathrm{C}$ (when temperature is between $40-50^{\circ} \mathrm{C}$, please consider degrading .) |
| :--- | :--- |
| Storage temperature | $-20^{\circ} \mathrm{C}-65^{\circ} \mathrm{C}$ |
| Humidity | below $90 \% \mathrm{RH}$ |
| Height and Vibration | below 1000 m , below $5.9 \mathrm{~m} / \mathrm{s} 2($ equals 0.6 g$)$ |
| Application field | indoor, no solar radiation, no corrosive or explosive gas or steam, no dust or combustible gas, oil, dropping water, salt. |
| Altitude | below 1000 m. |
| Class of pollution | 2 |

## Mechanical Installation:

Install on solid indoor basement, there should not be severe impact on ventilation or cooling system in the installation area or additional enclosure. Air-conditioner can be allocated to enhance CDM/BDM. Other installation condition should take special consideration, and manufacturer should offer technical explanation and consulting advices. For fixed devices, vibration should maintain within the maximum of IEC60721 class 3M1.

## Wiring

Frequency inverter wiring are divided into main circuit and control circuit two parts. Customers must follow the wiring diagram in the below correctly

## Wiring diagram: 11 kW and below



## Wiring diagram: $11 \mathrm{KW}-15 \mathrm{KW}$



## Wiring diagram : $18.5 \mathrm{KW}-355 \mathrm{KW}$



## Terminals Description:



Note: The above power classifications are for G type inverter.



## $45 \mathrm{KW}-250 \mathrm{KW}$ (380V) Main Circuit Terminals (Up input down output)



## Terminal Function

| Terminal | Name | Functions |
| :---: | :---: | :---: |
| $\begin{aligned} & \text { R/L1 } \\ & \text { S/L2 } \\ & \text { T/L3 } \end{aligned}$ | Inverter input terminals | Connect to three-phase power supply, single-phase connects to R, T |
| $\Theta / E$ | Grounding terminal | Connect to ground |
| $\mathrm{P}+$, RB | Braking resistor terminals | Connect to braking resistor |
| $\begin{aligned} & \mathrm{U} / \mathrm{T} 1 \\ & \mathrm{~V} / \mathrm{T} 2 \\ & \mathrm{~W} / \mathrm{T} 3 \end{aligned}$ | Output terminals | Connect to three-phase motor |
| $\mathrm{P}+$, $\mathrm{P}-$ | DC bus output terminals | Connect to braking unit |
| P, P+ | DC reactor terminals | Connect to DC reactor(remove the shorting block) |

## Terminals Description:

9KLCB Control circuit terminal

## Description of control circuit terminals

| Category | Symbol | Name | Function |
| :---: | :---: | :---: | :---: |
| Power supply | +10V-GND | External + 10V power supply | Output +10V power supply, maximum output current: 10 mA <br> Generally it is used as power supply of external potentiometer, potentiometer resistance range: $1 \mathrm{k} \Omega$ to $5 \mathrm{k} \Omega$ |
|  | +24V-COM | External +24 V power supply | Output +24 V power supply, generally it is used as power supply of digital input and output terminals and external sensor. Maximum output current: 200 mA |
|  | PLC | External power input terminal | When external signal is used to drive, please unplug J5 jumpers , PLC must be connected to external power supply, and to +24 V (default). |
| Analog input | Al1-GND | Analog input terminal 1 | 1.Input range:( DC 0 V to $10 \mathrm{~V} / 4 \mathrm{~mA}$ to 20 mA ), depends on the selected J 3 jumper on control panel. <br> 2. Input impedance: $22 \mathrm{k} \Omega$ with voltage input, $500 \Omega$ with current input. |
|  | Al2-GND | Analog input terminal 2 | 1. Input range:( DC 0 V to $10 \mathrm{~V} / 4 \mathrm{~mA} 20 \mathrm{~mA}$ ), depends on the selected J 4 jumper on control panel. <br> 2.Input impedance: $22 \mathrm{k} \Omega$ with voltage input, $500 \Omega$ with current input. |
| Digital input | Di1 | Digital input 1 | 1.Opto-coupler isolation, compatible with bipolar input |
|  | DI2 | Digital input 2 | 2.Input impedance: $2.4 \mathrm{k} \Omega$ |
|  | DI3 | Digital input 3 | 3.Voltage range with level input: 9 V to 30 V |
|  | DI4 | Digital input 4 |  |
|  | DI5 |  | 4. below 11KW: (DI1 to DI6)drive manner is controlled by $\mathrm{J5}$, when external power supply is |
|  | DI6 | Digital input 6 | used to drive, please unplug J 5 jumpers , |
|  | DI7 |  | 5. below 11KW: (DI1 to DI4)drive manner is controlled by J6, (DI5 to DI8)drive manner is controlled |
|  | DI8 | Digital input 8 | by J 5 , when external power supply is used to drive, please unplug J 5 jumpers . |
|  | DI5 | High-speed pulse input terminals | DI5 can also be used as high-speed pulse input channels. Maximum input frequency: 100 kHz |
| Analog output | DA1-GND | Analog output 1 | The selected J2 jumper on control panel determines voltage or current output. Output voltage range: 0 V to 10 V , output current range: 0 mA to 20 mA |
|  | DA1-GND | Analog output 2 | The selected J 1 jumper on control panel determines voltage or current output. Output voltage range: 0 V to 10 V , output current range: 0 mA to 20 mA |
| Digital output | SPA-COM | Digital output 1 | o-coupler isolation, bipolar open collector output |
|  | SPB-COM | Digital output 2 | Output voltage range: 0 V to 24 V , output current range: 0 mA to 50 mA |
|  | SPB-COM | High-speed pulse output | Subject to function code(U5.00)"SPB terminal output mode selection" As a high-speed pulse output, the highest frequency up to 100 kHz ; |
| relay output | T/A1-T/C1 | Normally open terminal |  |
|  | T/B1-T/C1 | Normally closed terminal | Contactor drive capacity. AC250V, 3A, COSø =0.4. |
| Auxiliary interface | J12 | 485 card interface | 26 pin terminal |
|  | J13 | PG card interface | 12 pin terminal |

## ОмOTECH

INDUSTRIES

## Peripheral equipment :

| Purpose | Name | Specification |
| :---: | :---: | :---: |
|   To protect frequency inverter connection, <br> please set wiring breaker or leakage <br> Protect frequency <br> inverter wiring <br> Wrotector by the side of power supply. <br> Please use preventing ultra-harmonics   <br> leakage protector   <br> leage protector.   |  |  |
| Prevent braking resistor burning-out | AC contactor | To prevent braking resistor burning-out when connecting, please set AC contactor, meanwhile, please connect surge absorber on the coil. |
| Preventing switching surge leaking out | Surge absorber | Surge absorber absorbing electromagnetic contactor and control relay switching surge, please install surge absorber on the electromagnetic contactor and control relay of frequency inverter. |
| Insulation input/ output signal | isolator | Due to frequency inverter insulation input/output signal, isolator can reduce inductive interference effectively |
| Improve frequency inverter input power factor | DC reactor/AC reactor | Apply to improve frequency inverter input power factor, please set DC reactor or AC reactor, when using large capacity power supply (above 600kW) |
| Reduce noise disturbance | Input noise filter | Input wiring can reduce noise flow into frequency inverter input power supply system. Please install the filter close to frequency inverter. |
|  | Output noise filter | From frequency inverter output wiring reduce noise, please install the filter close to frequency inverter. |
| Machine stop running on setting time | Braking resistor | Braking unit will consume machine regenerated energy, which will reduce decrease time |
|  | Braking unit | Braking unit and braking resistor combined using on machine, this will reduce motor decrease time. |
| Control frequency inverter operation from outside | Operator(small plastic -made device) | Control frequency setting and operation/stop operation by analog quantity instructions from distance. |
|  | Operator (standard nickel clad made) | Control frequency setting and operation/stop operation by analog quantity instructions from distance. |
| Ensure frequency inverter sudden power failure compensation | Sudden power failure/ compensate unit | To control power supply sudden failure compensation. |
| Setting and monitoring frequency and voltage from outside | Frequency meter |  |
|  | Frequency setting device | Outside setting and monitoring frequency |
|  | Frequency setting device knob |  |
|  | Output voltmeter | Outside setting output volt device is PWM frequency inverter specialized voltmeter. |
| Adjust frequency instruction input and frequency meter, ampere meter full scale | Frequency instruction using thyrecotor baseboard | Install and control circuit terminal, input frequency instruction. |
|  | Frequency meter full scale adjust resistor | Adjust frequency meter and ampere meter full scale. |



## Various of expansion cards:

PI9000 is equipped with a variety of universal encoder expansion card (PG card), as an optional accessory, it is necessary part for the inverter closed-loop vector control, please select PG card according to the form of encoder output, the specific models are as follows:

| Options | Description | Others |
| :---: | :---: | :---: | :---: |
| PI9000_PG1 | Differential input PG card, without frequency dividing output | Terminal wiring |
| PI9000_PG3 | UVW differential input PG card, without frequency dividing output | Terminal wiring |
| PI9000_PG4 | Rotational transformer PG card | Terminal wiring |
| PI9000_PG5 | OC input PG card, with 1:1 frequency dividing output | Terminal wiring |

PI9000_PC1 the user programmable card is one integrated PLC function expansion card. The user can install the expansion card to make PI9000 series frequency inverter support simple PLC (User programmable) function. In addition, the card has integrated interface of the extended IO and universal communication.

| Item | Specification | Description |
| :---: | :---: | :---: |
| Input terminal | 5 road digital signal input |  |
|  | 1 road analog voltage signal input | With isolation, support - $10 \mathrm{v} \sim 10 \mathrm{v}$ voltage input signal |
| Output terminal | 2 road relay signal output |  |
|  | 1 road analog signal output |  |
| Communication | RS-485 communication interface |  |

## Braking unit and brake resistor:

Braking unite is mainly used in motor controlled by frequency inverter, which applied to and brand frequency inverter for the drop speed, brake positioning, hoisting and declining.

The inverter-controlled motor in rapid speed decrease and dropping in the operation, because of the load inertia, the kinetic energy will transferred into electrical energy and will be stored in the DC bus which will cause the jump of over-voltage or fault. Braking unit through the automatic detection of the DC bus voltage and self-switching, the renewable energy will be released into the braking resistor which ensures the drive to smooth control of the motor at various operating condition.


## AC Reactor:

AC reactor can inhibit higher harmonic of frequency inverter input current, it can effective to improve inverter of power factor. Suggest that should use AC reactor in the following cases:
The ratio of the power supply capacity of frequency inverter used in and the frequency inverter capacity for more than 10:1.

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