

A **Nidec** Group Company

Nidec
Motors & Actuators

All for dreams™

TURN ADJUST
tilt **RAISE**
OPEN ROTATE
MOVE
close **SPIN**

DRIVE TECHNOLOGY 2011/12

THE NIDEC MOTORS & ACTUATORS DC MOTOR RANGE

MOTORS WITHOUT GEARING

GMP



➤ **Smaller diameter motors with single & double output shafts**

➤ Nominal torque 0.05 – 0.1 Nm
➤ No load speed 2700 – 3250 min⁻¹

**GMK
GML**



➤ **Higher torque single output shaft motors**

➤ Nominal torque 0.12 – 0.4 Nm
➤ No load speed 2200 – 5250 min⁻¹

MOTORS WITH SPUR GEAR

**GMAG
GMPI**



➤ **Motors that can address all your in-line drive requirements where you need higher torque, lower speed rotation**

➤ Nominal torque 0.2 – 4 Nm
➤ No load speed 17 – 200 min⁻¹

MOTORS WITH WORM GEAR

**GMPD
GMPG**



➤ **Low/medium torque with perpendicular output shafts**

➤ Nominal torque 0.5 – 4 Nm
➤ No load speed 21 – 540 min⁻¹

GMPS



➤ **Actuators fitted with a lead-screw to drive your linear motion needs**

➤ Nominal axial force 1 – 2 kN
➤ No load speed 6 mm/s

**DCK31
DCK35**



➤ **Cost competitive medium torque range worm drive motors**

➤ Nominal torque 3 – 6 Nm
➤ No load speed 14 – 270 min⁻¹

**SWMK
SW2K
SW2L**



➤ **Weight optimized medium torque range**

➤ Nominal torque 0.8 – 8 Nm
➤ No load speed 48 – 350 min⁻¹

**SWMV
SWMG**



➤ **Powerful medium & high torque worm gear motors**

➤ Nominal torque 3 – 20 Nm
➤ No load speed 27 – 220 min⁻¹



⇨ IMPORTANT EXPLANATORY INFORMATION	2
⇨ DC MOTORS WITHOUT GEARING	6
SERIES 0220 (GMP)	7
SERIES 0272 (GMK)	17
SERIES 0273 (GML)	25
⇨ DC MOTORS WITH SPUR GEAR	34
SERIES 0202 (GMAG)	35
SERIES 0231 (GMPI)	41
⇨ DC MOTORS WITH WORM GEAR	48
SERIES 0320 (GMPD)	49
SERIES 0225 (GMPG)	67
SERIES 0223 (SWMP)	79
SERIES 0321 (GMPS)	91
SERIES 0266 (DCK31)	101
SERIES 0268 (DCK35)	133
SERIES 0270 (SWMK)	149
SERIES 0277 (SW2K)	163
SERIES 0278 (SW2L)	181
SERIES 0291 (SWMV)	191
SERIES 0292 (SWMG)	199
⇨ INDEX	204



Subject to change and error, also of a technical nature. Therefore use only product drawings for design purposes. These are available from your representative.

The catalog illustrations do not all correspond to DIN requirements. The operating values indicated are valid for 20°C ambient temperature. In all cases the motors should

be tested for their suitability in the customer's particular application. Specific motor designs for special customers. Motors in this catalog are not intended for the consumer. In accordance with EU regulations, these products do not require CE certification marking. Some motors have customer specific designs. They require new tooling for new designs.

TERMS, SYMBOLS AND UNITS ACCORDING TO DIN

Symbol	Unit	Term
U_N	[V]	Rated voltage
n_o	[min ⁻¹]	No-load speed ± 10%
M_N	[Nm]	Nominal torque at the output shaft
M_A	[Nm]	Starting torque
i		Gear ratio
J_R	[kgm ²] x 10 ⁻⁶	Armature load inertia
R	[mΩ]	Armature resistance, 2/4 commutator bars
L	[mH]	Armature inductance, 2/4 commutator bars

Drawing	dimensional drawing
Shaft	dimensions of shaft ends
Wiring diagram	motor wiring diagram
Connection	dimensions and positions of motor connections
Materials	BRZ = bronze, KST = plastic, ST = steel, HGW = resinbonded fabric



Direction of rotation
when looking onto
motor shaft

The curves show the speed and the current as a function of the torque. These are average values at room temperature. Divergences of ± 10 % are possible in the series.



CCW



CW

Preferred direction of rotation:
Worm gear motors have a preferred direction of rotation, indicated in the drawings by a larger arrow. If the motor rotates against the preferred rotation direction, power decreases by approx. 10 %.



CONVERSION OF TORQUE VALUES

(VALUES ROUNDED FOR PRACTICAL USE)

	Nm	Ncm	pcm	kpcm	kpm	oz in	in lbs	ft lbs
Nm	1	100	10.2×10^3	10.2	0.102	141.6	8.85	0.738
Ncm	10^{-2}	1	102	1.02×10^{-2}	1.02×10^{-3}	1.42	8.85×10^{-2}	7.38×10^{-3}
pcm	9.8×10^{-5}	9.8×10^{-3}	1	10^{-3}	10^{-5}	1.39×10^{-2}	8.68×10^{-4}	7.23×10^{-5}
kpcm	9.8×10^{-2}	9.8	1000	1	10^{-2}	13.9	0.868	7.23×10^{-2}
kpm	9.8	980	10^5	100	1	1390	86.8	7.23
oz in	7.06×10^{-3}	0.706	72	7.2×10^{-2}	7.2×10^{-4}	1	6.25×10^{-2}	5.2×10^{-3}
in lbs	0.113	11.3	1152	1.15	1.15×10^{-2}	16	1	8.3×10^{-2}
ft lbs	1.36	135.58	13,825	13.8	0.138	192	12	1

CONVERSION OF FORCES

(VALUES ROUNDED FOR PRACTICAL USE)

	N	kp	p	oz	lbf
N	1	0.102	102	3.6	0.225
kp	9.8	1	1000	35.27	2.2
p	9.8×10^{-3}	10^{-3}	1	3.53×10^{-2}	2.2×10^{-3}
oz	0.278	2.83×10^{-2}	28.35	1	6.25×10^{-2}
lbf	4.45	0.445	453.6	16	1

CONVERSION OF POWER

(VALUES ROUNDED FOR PRACTICAL USE)

	kW	PS	HP	kpm/s	kcal/s
kW	1	1.36	1.34	102	0.239
PS	0.735	1	0.986	75	0.176
HP	0.746	1.01	1	76	0.178
kpm/s	9.8×10^{-3}	1.33×10^{-2}	1.32×10^{-2}	1	2.34×10^{-2}
kcal/s	4.2	5.7	5.6	427	1

CONVERSION OF TEMPERATURES

t_c [°C] Celsius	t_f [°F] Fahrenheit	T_K [K] Kelvin	T_R [°R] Rankine
$t_c = \frac{5}{9} (t_f - 32)$	$t_f = \frac{9}{5} t_c + 32$	$T_K = t_c + 273$	$T_R = \frac{9}{5} (t_c + 273)$
$t_c = \frac{5}{9} T_R - 273$		$T_K = \frac{5}{9} T_R$	
		$T_K = \frac{5}{9} (t_f + 255)$	

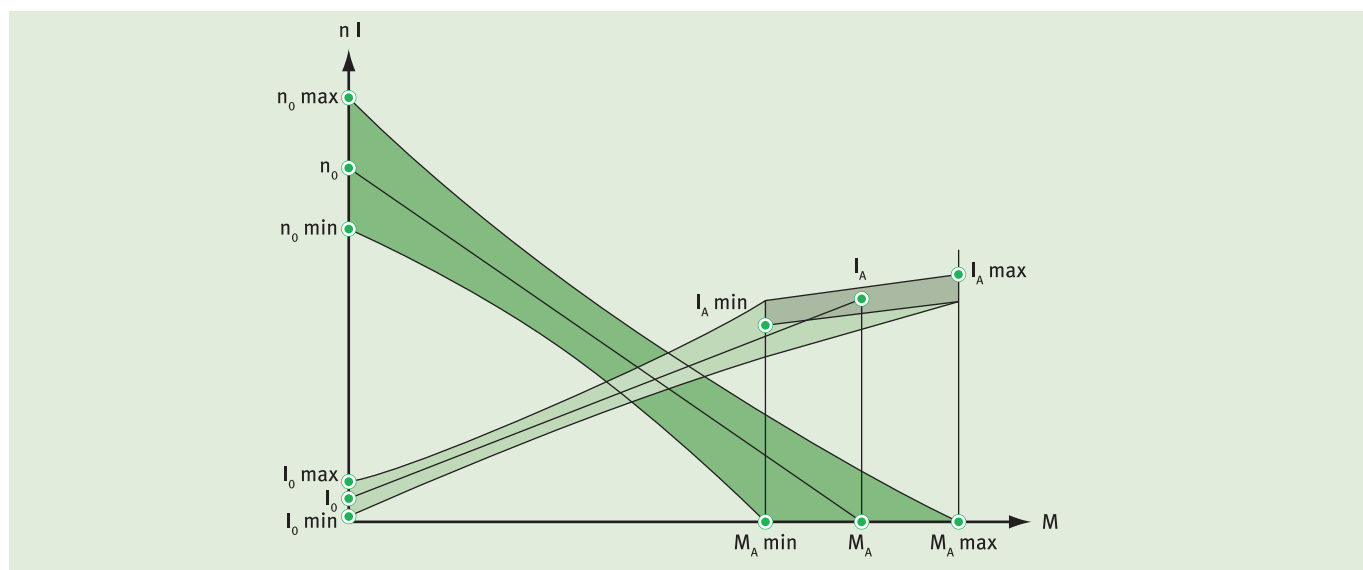


TOLERANCE ZONES TO ISO/R 286

(DIN 7150, 7151, 7152, 7154, 7155)

1,1 H 13:	+0.140 / 0 mm	5,1 H 11:	+0.075 / 0 mm	9 k 5:	+0.007 / +0.001mm
1,6 H 13:	+0.140 / 0 mm	5,1 H 12:	+0.120 / 0 mm	9,4 h 11:	0 / -0.090 mm
2,5 H 12:	+0.100 / 0 mm	5,5 h 11:	0 / -0.075 mm	9,5 js 11:	+0.045 / -0.045 mm
2,7 H 12:	+0.100 / 0 mm	5,5 H 13:	+0.180 / 0 mm	9,6 h 11:	0 / -0.090 mm
3 H 9:	+0.025 / 0 mm	5,8 g 6:	-0.004 / -0.012 mm	9,75 g 5:	-0.006 / -0.014 mm
3 H 12:	+0.100 / 0 mm	5,9 c 9:	-0.070 / -0.100 mm	10 f 6:	-0.013 / -0.022 mm
3 N 9:	-0.004 / -0.029 mm	5,9 h 10:	0 / -0.048 mm	10 f 7:	-0.013 / -0.028 mm
3 P 8:	-0.006 / -0.020 mm	6 f 9:	-0.010 / -0.040 mm	10 f 8:	-0.013 / -0.035 mm
3 P 9:	-0.006 / -0.031 mm	6 fg 9:	-0.006 / -0.014 mm	10 g 5:	-0.005 / -0.011 mm
3 P 10:	-0.006 / -0.046 mm	6 h 6:	0 / -0.008 mm	10 g 6:	-0.005 / -0.014 mm
3,1 JS 10:	+0.024 / -0.024 mm	6 h 8:	0 / -0.018 mm	10 h 5:	0 / -0.006 mm
3,5 H 12:	+0.120 / 0 mm	6 h 9:	0 / -0.030 mm	10 h 7:	0 / -0.015 mm
3,6 H 11:	+0.075 / 0 mm	6 m 6:	+0.012 / +0.004 mm	10 h 9:	0 / -0.036 mm
4 C 10:	+0.118 / -0.070 mm	6,3 H 12:	+0.150 / 0 mm	11 d 10:	-0.050 / -0.120 mm
4 h 6:	0 / -0.008 mm	6,5 H 8:	+0.022 / 0 mm	11,2 e 10:	-0.032 / -0.102 mm
4 h 8:	0 / -0.018 mm	6,8 h 8:	0 / -0.022 mm	11,5 h 11:	0 / -0.110 mm
4 h 9:	0 / -0.030 mm	7 h 8:	0 / -0.022 mm	12 f 7:	-0.016 / -0.034 mm
4 h 10:	0 / -0.048 mm	7,6 h 11:	0 / -0.090 mm	12 g 5:	-0.006 / -0.014 mm
4 h 11:	0 / -0.075 mm	8 f 6:	-0.013 / -0.022 mm	12 h 6:	0 / -0.011 mm
4 H 12:	+0.120 / 0 mm	8 g 6:	-0.005 / -0.014 mm	12 h 7:	0 / -0.018 mm
4 P 9:	-0.012 / -0.042 mm	8 g 7:	-0.005 / -0.020 mm	12 h 9:	0 / -0.036 mm
4,1 h 10:	0 / -0.048 mm	8 g 9:	-0.005 / -0.041 mm	12 h 11:	0 / -0.110 mm
4,1 H 11:	+0.075 / 0 mm	8 h 9:	0 / -0.036 mm	13,4 h 11:	0 / -0.110 mm
4,2 H 7:	+0.012 / 0 mm	8 H 9:	+0.036 / 0 mm	14 f 6:	-0.016 / -0.027 mm
4,2 H 12:	+0.120 / 0 mm	8 h 10:	0 / -0.058 mm	14 f 7:	-0.016 / -0.034 mm
4,5 H 13:	+0.180 / 0 mm	8 h 11:	0 / -0.090 mm	14 H 7:	+0.018 / 0 mm
5 c 11:	-0.070 / -0.145 mm	8 k 5:	+0.007 / +0.001 mm	15 f 7:	-0.016 / -0.034 mm
5 h 6:	0 / -0.008 mm	8,5 h 9:	0 / -0.036 mm	15,2 h 11:	0 / -0.110 mm
5 h 9:	0 / -0.030 mm	8,7 h 11:	0 / -0.090 mm	16 f 6:	-0.016 / -0.027 mm
5 h 10:	0 / -0.048 mm	9 D 9:	+0.076 / +0.040 mm	18 H 8:	+0.027 / 0 mm
5 h 12:	0 / -0.120 mm	9 h 6:	0 / -0.009 mm	20 h 9:	0 / -0.052 mm
5 P 9:	-0.012 / -0.042 mm	9 h 11:	0 / -0.090 mm	26 g 6:	-0.007 / -0.020 mm

TOLERANCE ZONES



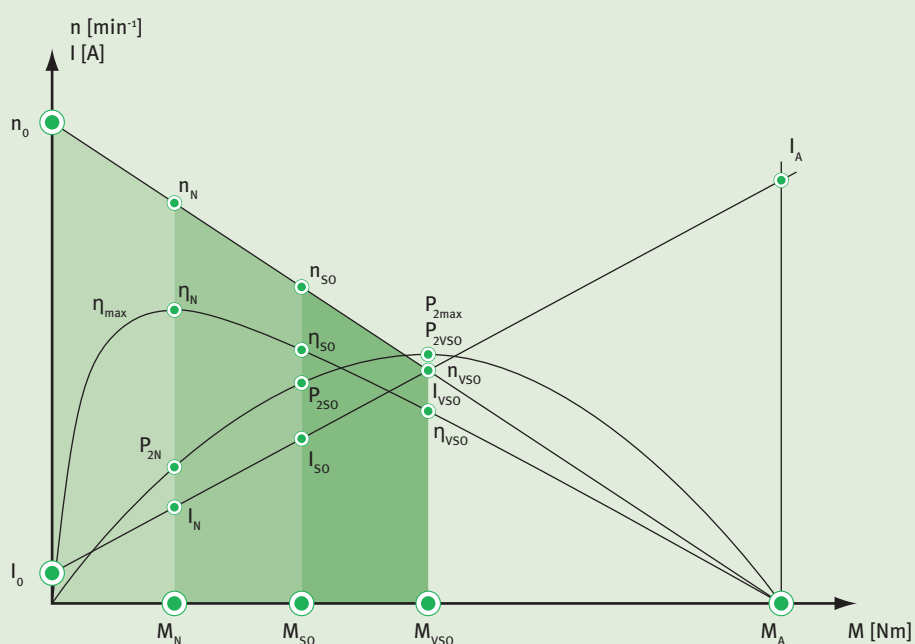


CHARACTERISTIC CURVES

CR	Continuous running	n_0	No-load speed in min^{-1}
SO	Short operation	n_N	Rated speed in min^{-1}
VSO	Very short operation	n_{SO}	Speed for short operation in min^{-1}
P	Power in W	n_{VSO}	Speed for very short operation in min^{-1}
P_{2N}	Nominal output power in W	I	Current in A
$P_{2\max}$	Maximum output power in W	I_0	No-load current in A
P_{2SO}	Output power for short operation in W	I_A	Starting current in A
P_{2VSO}	Output power for very short operation in W	I_N	Rated current in A
M	Torque in Nm	I_{SO}	Current for short operation in A
M_A	Starting torque in Nm	I_{VSO}	Current for very short operation in A
M_N	Nominal output torque in Nm	η	Efficiency in %
M_{SO}	Output torque for short operation in Nm	η_N	Rated efficiency in %
M_{VSO}	Output torque for very short operation in Nm	η_{SO}	Efficiency for short operation in %
n	Rotational speed in min^{-1}	η_{VSO}	Efficiency for very short operation in %

RANGE OF OPERATION

- Continuous running
- Short operation
- Very short operation





NIDEC MOTORS & ACTUATORS ⇄ MOTOR SERIES

0220 (GMP)

⇄ DC MOTORS WITHOUT GEARING



⇄ TECHNICAL DESCRIPTION

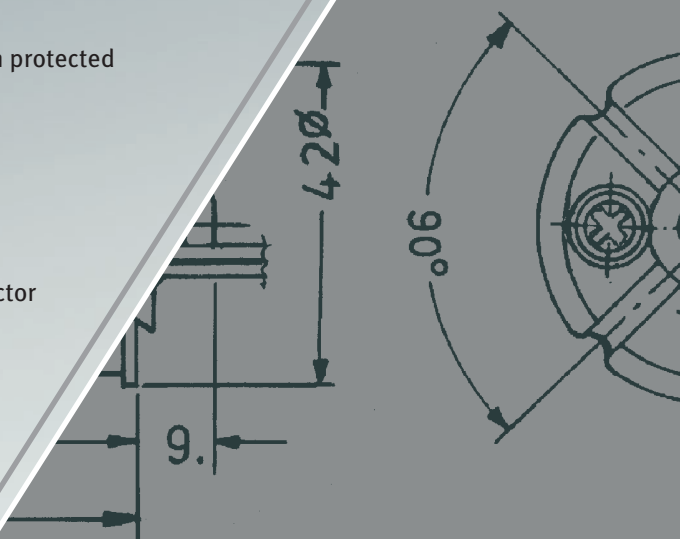
Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	—
Gear housing:	—
Gear wheel material:	—
Lubrication:	—
Mechanical interface:	steel shaft
Electric interface:	connector or leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

⇄ INDUSTRIAL APPLICATION

Linear drives, machine construction

⇄ AUTOMOTIVE APPLICATION

Seat track drive



Series GMP

Motor type 402 944

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	0.08
No-load speed [min^{-1}]	n_0	2,700.0
Nominal power [W]	P_N	16.2
Nominal current [A]	I_N	2.0
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

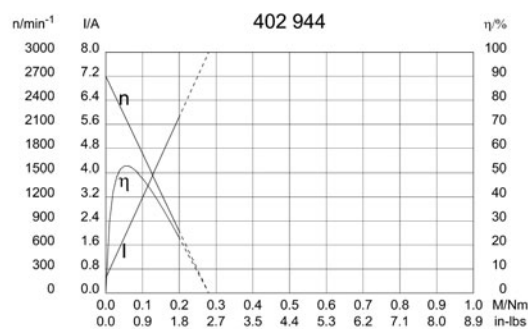
Pulses	0
Output channels	0

Other data

Gear ratio	
Gear wheel material	
Suppression components	7,5 μ H
Enclosure class	IP 30
Weight [kg]	0.550

Remarks:

Characteristic curves

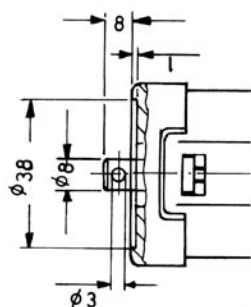


Motor picture

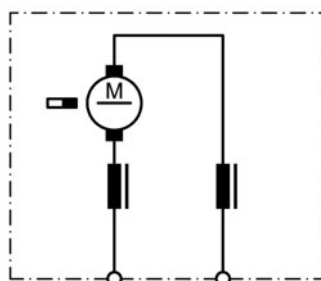


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

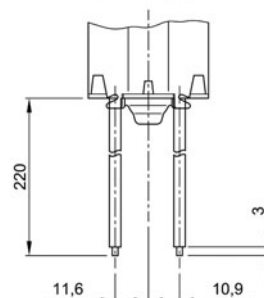
W 7



S 27



K 163



Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Ball

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.08
No-load speed [min^{-1}]	n_0	2,800.0
Nominal power [W]	P_N	17.6
Nominal current [A]	I_N	1.0
Nominal force [kN]	F_N	0.00
Duty cycle	s3	

Sensor data

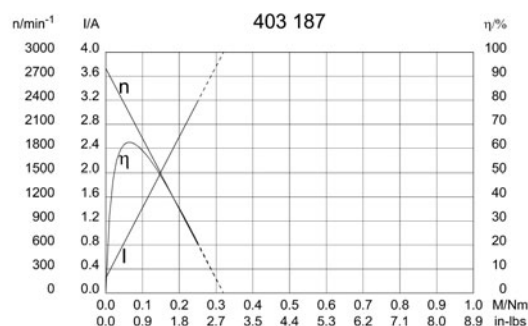
Pulses	0
Output channels	0

Other data

Gear ratio	
Gear wheel material	
Suppression components	7.5 μ H, 47nF
Enclosure class	IP 30
Weight [kg]	0.550

Remarks:

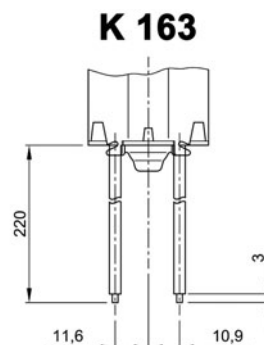
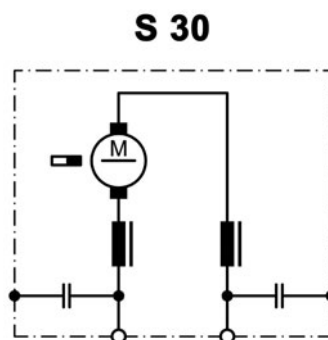
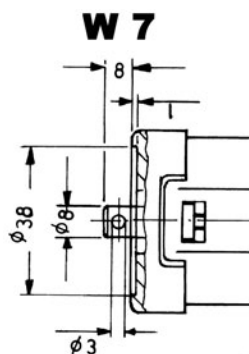
Characteristic curves



Motor picture



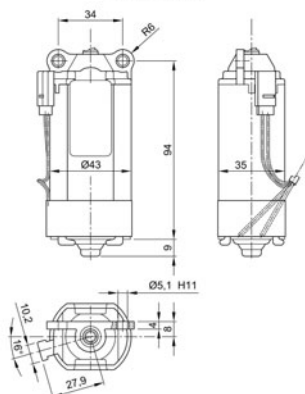
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

0220 D



Motor picture



Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	0.05
No-load speed [min^{-1}]	n_0	3,250.0
Nominal power [W]	P_N	14.0
Nominal current [A]	I_N	3.5
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

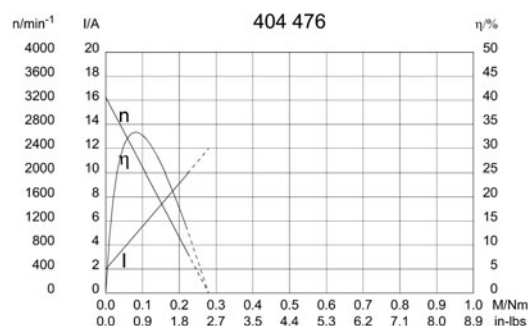
Pulses	2
Output channels	1

Other data

Gear ratio	
Gear wheel material	
Suppression components	7,5 μ H
Enclosure class	IP 40
Weight [kg]	0.520

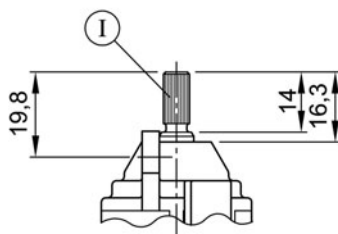
Remarks:

Characteristic curves



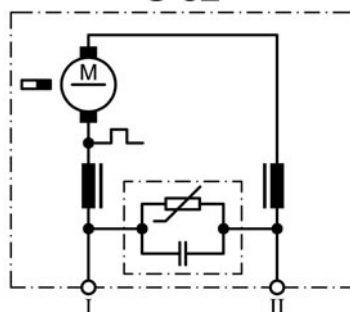
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 256



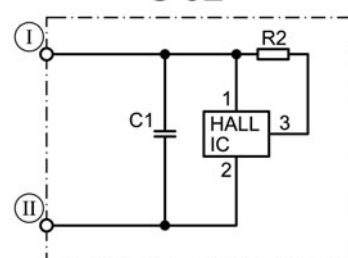
I Tapered splines 5 x 6 DIN 5481

S 82



I Terminal 1, green
 II Terminal 2, black

S 92



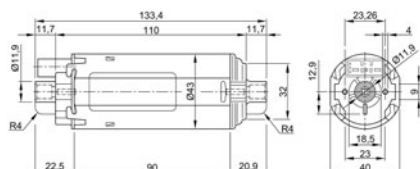
I Terminal 3, +, red
 II Terminal 4, -, brown

- I Terminal 1, motor, green
- II Terminal 2, motor, black
- III Terminal 3, Hall-IC + , red
- IV Terminal 4, Hall-IC - , brown

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

0220 F



Motor picture



Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	0.10
No-load speed [min^{-1}]	n_0	2,700.0
Nominal power [W]	P_N	21.2
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

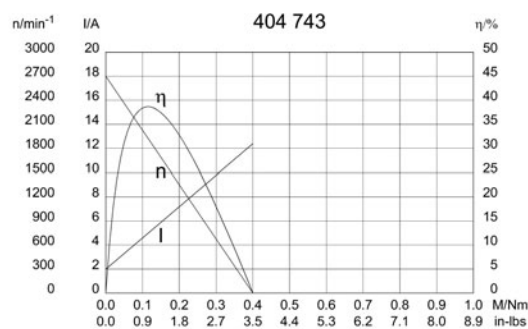
Pulses	0
Output channels	0

Other data

Gear ratio	
Gear wheel material	
Suppression components	2,5 μ H, 47nF ()
Enclosure class	IP 40
Weight [kg]	0.560

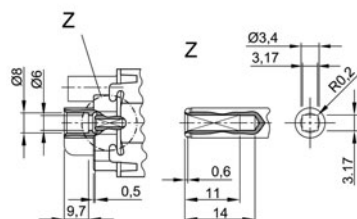
Remarks:

Characteristic curves

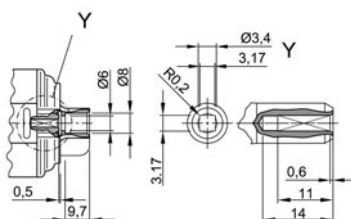


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

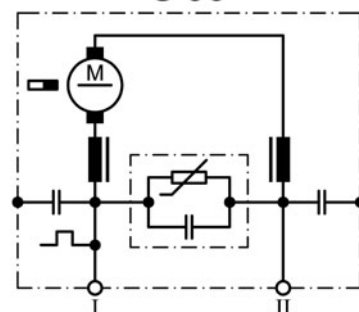
W 266



W 267



S 93

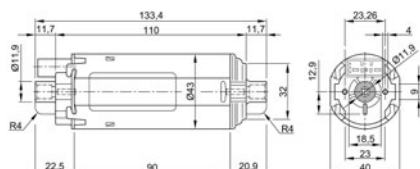


I Terminal 1
 II Terminal 5

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

0220 F



Motor picture



Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	0.10
No-load speed [min^{-1}]	n_0	2,700.0
Nominal power [W]	P_N	21.2
Nominal current [A]	I_N	4.5
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

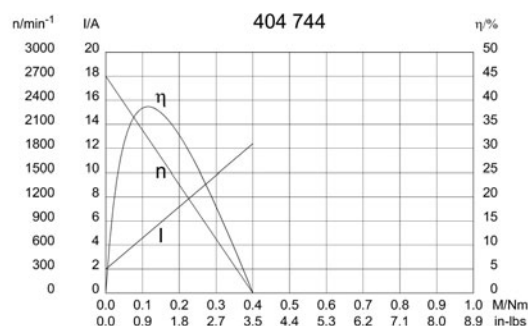
Pulses	1
Output channels	1

Other data

Gear ratio	
Gear wheel material	
Suppression components	2,5μH, 47nF
Enclosure class	IP 40
Weight [kg]	0.560

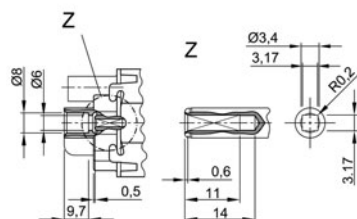
Remarks:

Characteristic curves

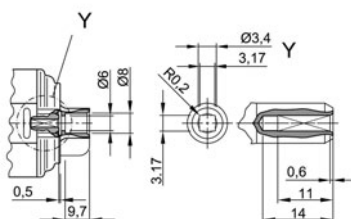


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

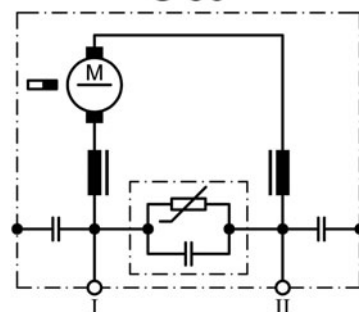
W 266



W 267



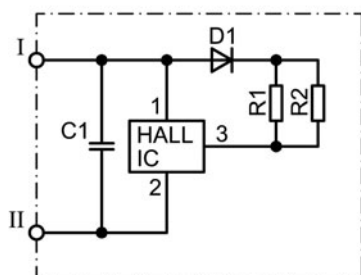
S 86



I Terminal 1
 II Terminal 5

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

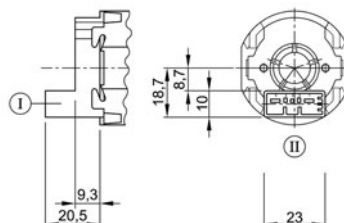
S 85



I Terminal 4, Hall-IC +

II Terminal 2, Hall-IC -

K 220



Connector TYCO C-208-15621 (Z) mating with:

Connector housing 1379217-3 & cover

1379218-2

www.tycoelectronics.com

Notes

Notes

[illegible]

0272 (GMK)

⇄ DC MOTORS WITHOUT GEARING



⇄ TECHNICAL DESCRIPTION

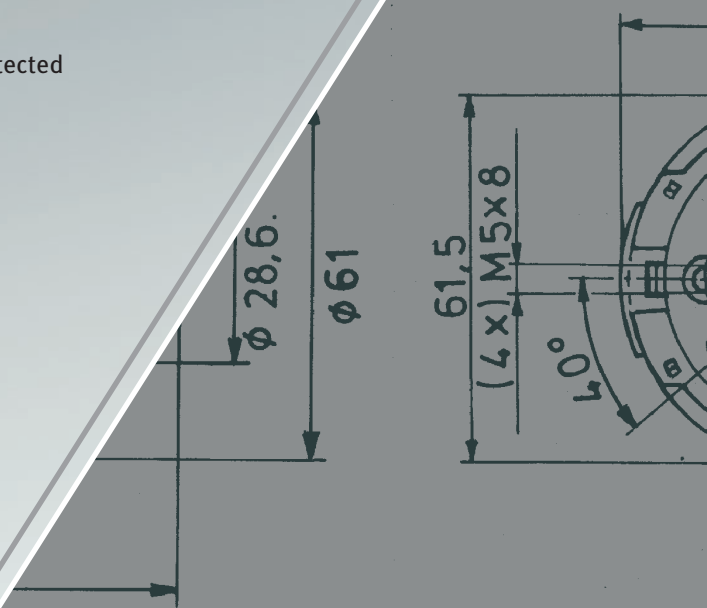
Motorhousing:	deep drawn & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	–
Gear housing:	–
Gear wheel material:	–
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

⇄ INDUSTRIAL APPLICATION

Linear drives

⇄ AUTOMOTIVE APPLICATION

Electric torque management,
Automated manual transmission



Series GMK
Motor type 404 284

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.19
No-load speed [min^{-1}]	n_0	3,100.0
Nominal power [W]	P_N	52.7
Nominal current [A]	I_N	5.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

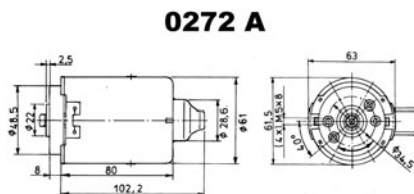
Pulses	0
Output channels	0

Other data

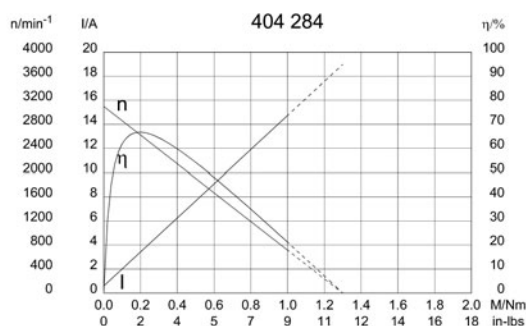
Gear ratio	
Gear wheel material	
Suppression components	5μH
Enclosure class	IP 30
Weight [kg]	0.900

Remarks: 1 start worm

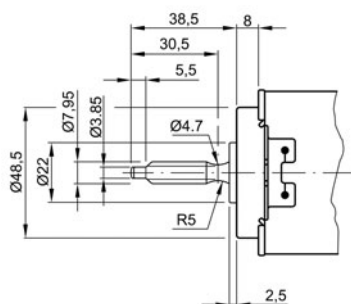
Characteristic curves



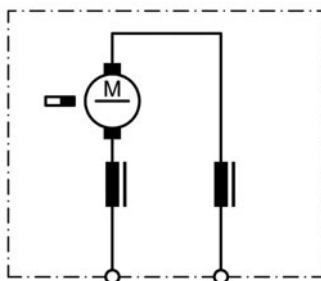
Motor picture



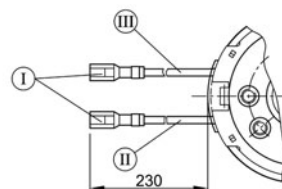
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 220

S 27



K 180



no of starts 1, lead angle 9°, pressure angle 10°, module 1, pitch 3,14159 mm (0,124")

I Blade terminal receptacles 2,8 x 0,8 DIN 46 247
II green
III red

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.12
No-load speed [min^{-1}]	n_0	5,250.0
Nominal power [W]	P_N	58.8
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

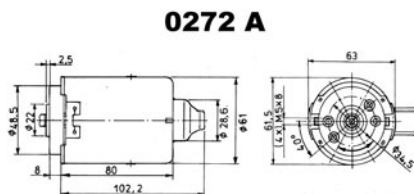
Pulses	0
Output channels	0

Other data

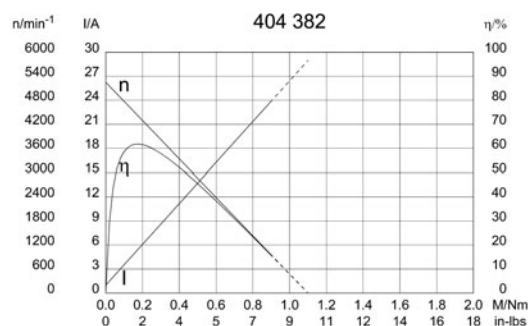
Gear ratio	
Gear wheel material	
Suppression components	5 μ H, 1nF
Enclosure class	IP 30
Weight [kg]	0.900

Remarks:

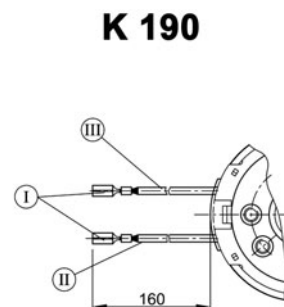
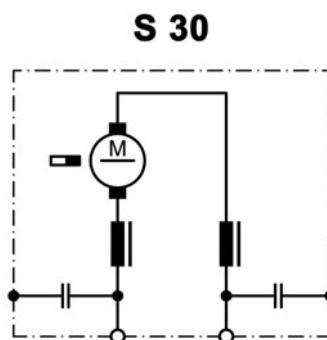
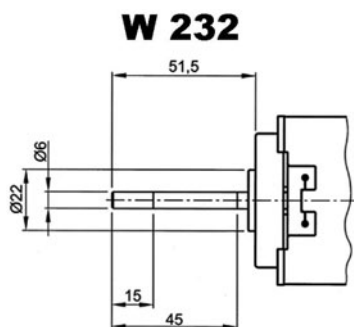
Characteristic curves



Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



- I Receptacles for tabs 2,8 x 0,8 DIN 46 247
- II black
- III red

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.12
No-load speed [min^{-1}]	n_0	3,800.0
Nominal power [W]	P_N	43.9
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

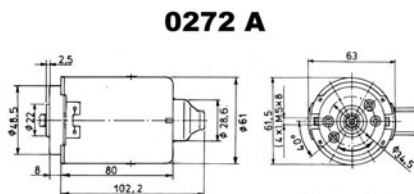
Pulses	0
Output channels	0

Other data

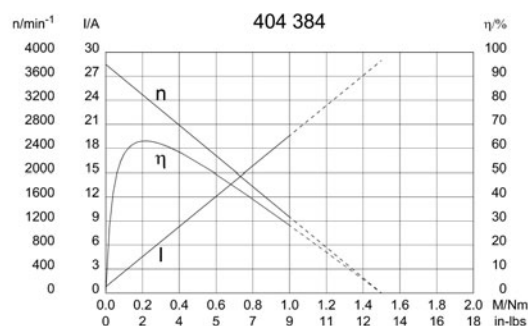
Gear ratio	
Gear wheel material	
Suppression components	5 μ H, 1nF
Enclosure class	IP 30
Weight [kg]	0.900

Remarks: 4 start worm

Characteristic curves

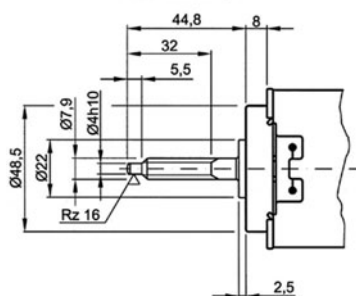


Motor picture

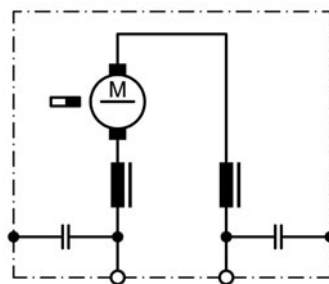


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

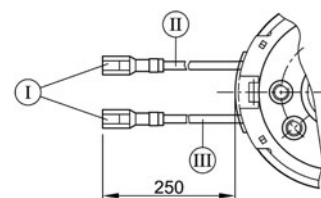
W 218



S 30



K 189



no of starts 4 ,lead angle 30°31'35", pressure angle: 15°, pitch 11.6707 mm (0.459"), module 0,8

I Receptacle for tabs 2,8 x 0,8 DIN 46 247
 II red
 III black

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	0.35
No-load speed [min^{-1}]	n_0	3,000.0
Nominal power [W]	P_N	79.2
Nominal current [A]	I_N	9.0
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

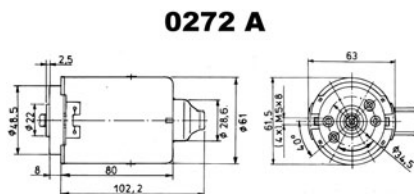
Pulses	0
Output channels	0

Other data

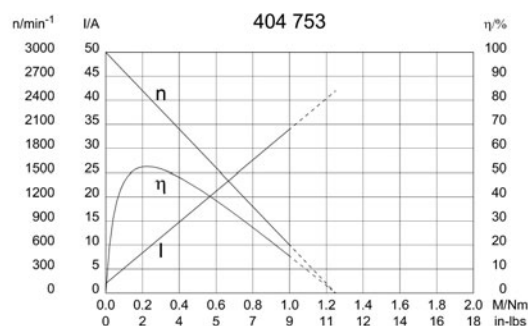
Gear ratio	
Gear wheel material	
Suppression components	5 μ H, 10nF
Enclosure class	IP 30
Weight [kg]	0.900

Remarks:

Characteristic curves

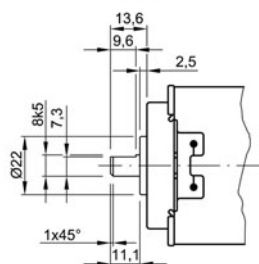


Motor picture

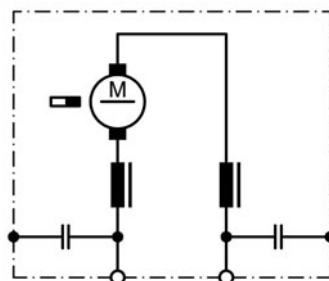


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

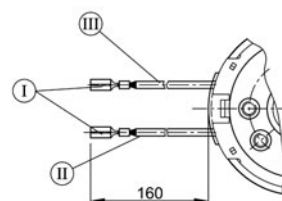
W 280



S 30



K 190



- I Receptacles for tabs 2,8 x 0,8 DIN 46 247
- II black
- III red

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.30
No-load speed [min^{-1}]	n_0	2,200.0
Nominal power [W]	P_N	53.2
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

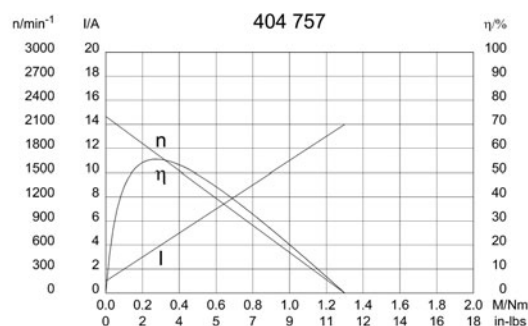
Pulses	0
Output channels	0

Other data

Gear ratio	
Gear wheel material	
Suppression components	5 μ H, 10nF
Enclosure class	IP 30
Weight [kg]	0.890

Remarks:

Characteristic curves

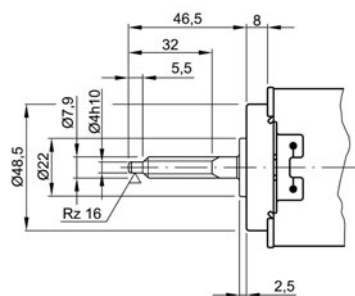


Motor picture

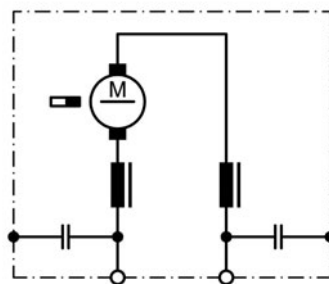


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

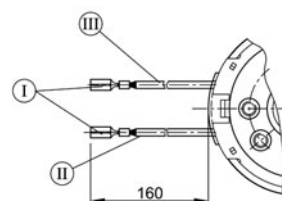
W 281



S 30



K 190



no of starts 2 , lead angle 19°48'54", pressure
 angle 15°, pitch 3,141 mm (0,124"), module 1

I Receptacles for tabs 2,8 x 0,8 DIN 46 247
 II black
 III red

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.15
No-load speed [min^{-1}]	n_0	2,200.0
Nominal power [W]	P_N	30.9
Nominal current [A]	I_N	2.5
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

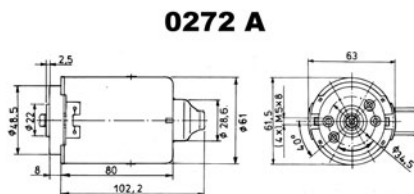
Pulses	0
Output channels	0

Other data

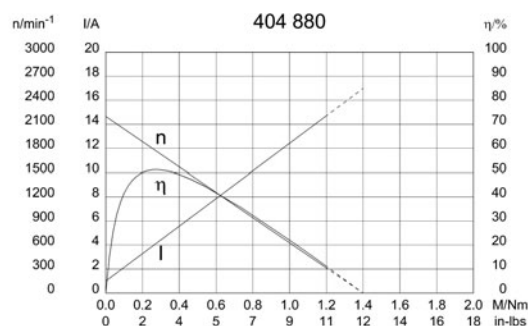
Gear ratio	
Gear wheel material	
Suppression components	5 μ H
Enclosure class	IP 30
Weight [kg]	0.900

Remarks: 3 start worm

Characteristic curves

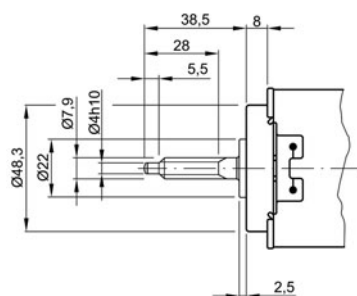


Motor picture

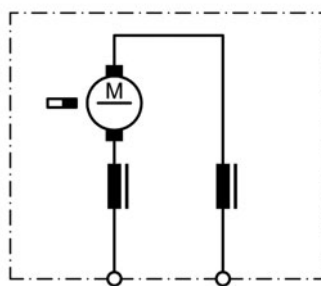


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

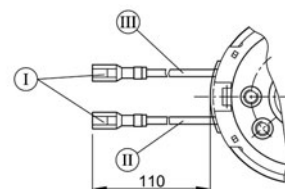
W 300



S 27



K 264



no of starts 3, lead angle 30°33'44", pressure angle 15°, module 1, pitch 3,141 mm (0,124")

I Receptacle for tabs 2,8 x 0,8 DIN 46 247
 II green
 III red

[illegible]



NIDEC MOTORS & ACTUATORS ⇄ MOTOR SERIES

0273 (GML)

⇄ DC MOTORS WITHOUT GEARING



⇄ TECHNICAL DESCRIPTION

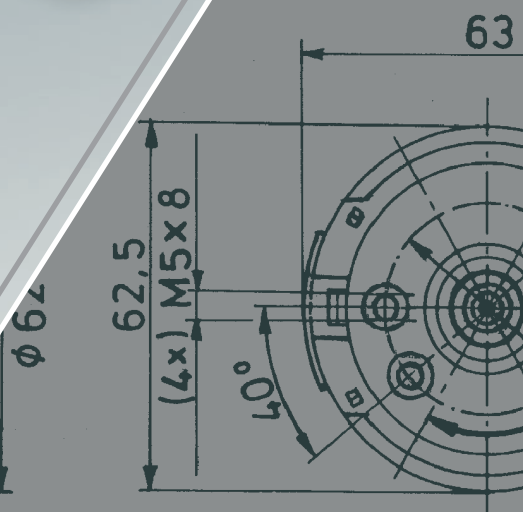
Motorhousing:	deep drawn & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	–
Gear housing:	–
Gear wheel material:	–
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	leads with connector
Sensor:	–
Thermal protection:	optional
EMC suppression:	optional

⇄ INDUSTRIAL APPLICATION

Linear drives

⇄ AUTOMOTIVE APPLICATION

Electric torque management,
Automated manual transmission



Series GML

Motor type 404 469

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	36
Nominal torque [Nm]	M_N	0.20
No-load speed [min^{-1}]	n_0	4,100.0
Nominal power [W]	P_N	79.7
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

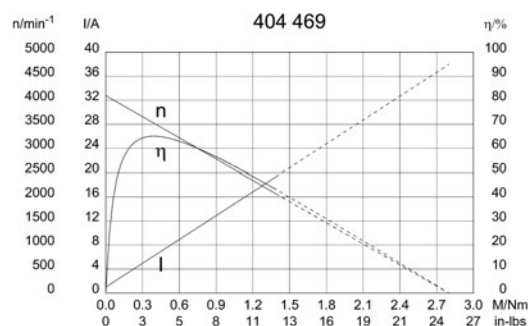
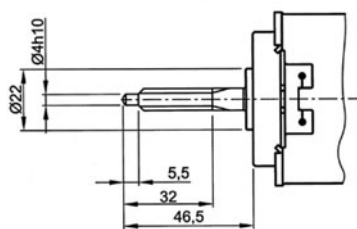
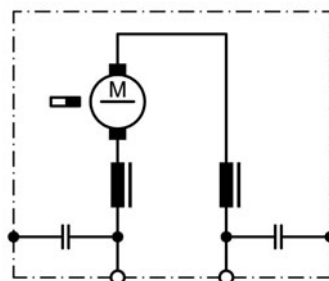
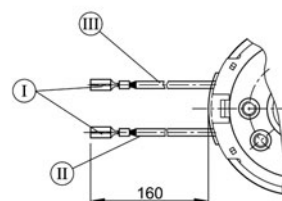
Sensor data

Pulses	0
Output channels	0

Other data

Gear ratio	
Gear wheel material	
Suppression components	5 μ H, 10nF
Enclosure class	IP 30
Weight [kg]	1.150

Remarks:

Characteristic curves**Motor picture****Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)****W 233****S 30****K 190**

no of starts 2, lead angle 19°48'54", pressure angle 15°, module 1, pitch 3,141 mm (0,124")

I Receptacles for tabs 2,8 x 0,8 DIN 46 247
 II black
 III red

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.30
No-load speed [min^{-1}]	n_0	4,000.0
Nominal power [W]	P_N	107
Nominal current [A]	I_N	7.5
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

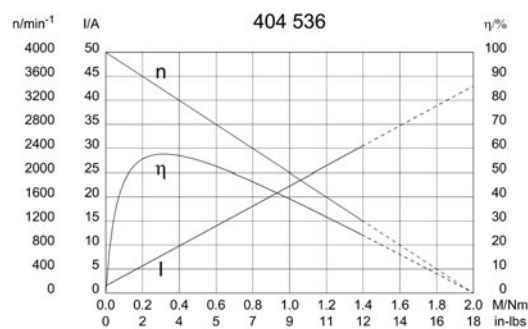
Pulses	0
Output channels	0

Other data

Gear ratio	
Gear wheel material	
Suppression components	5 μ H, 10nF
Enclosure class	IP 30
Weight [kg]	1.150

Remarks:

Characteristic curves

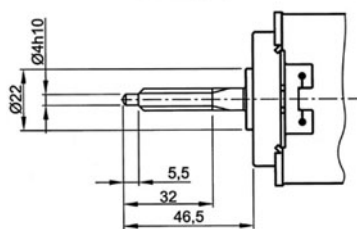


Motor picture

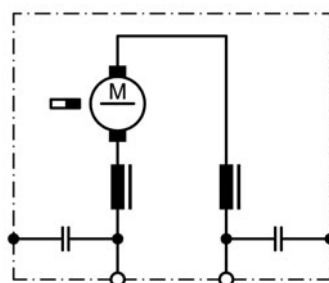


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

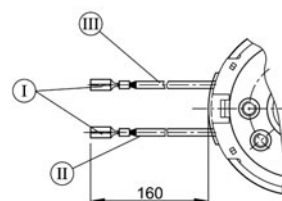
W 233



S 30



K 190



no of starts 2, lead angle 19°48'54", pressure angle 15°, module 1, pitch 3,141 mm (0,124")

I Receptacles for tabs 2,8 x 0,8 DIN 46 247
 II black
 III red

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	0.20
No-load speed [min^{-1}]	n_0	3,750.0
Nominal power [W]	P_N	67.3
Nominal current [A]	I_N	7.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

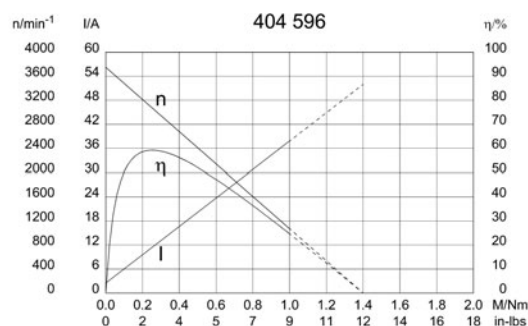
Pulses	0
Output channels	0

Other data

Gear ratio	
Gear wheel material	
Suppression components	5 μ H, 10nF
Enclosure class	IP 30
Weight [kg]	1.150

Remarks:

Characteristic curves

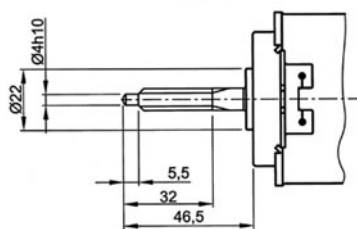


Motor picture

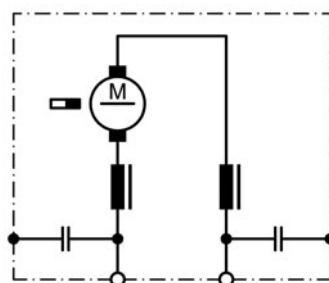


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

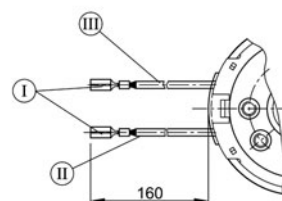
W 233



S 30



K 190



no of starts 2, lead angle 19°48'54", pressure angle 15°, module 1, pitch 3,141 mm (0,124")

I Receptacles for tabs 2,8 x 0,8 DIN 46 247
 II black
 III red

Series GML

Motor type 404 621

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	0.20
No-load speed [min^{-1}]	n_0	1,900.0
Nominal power [W]	P_N	32.6
Nominal current [A]	I_N	6.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

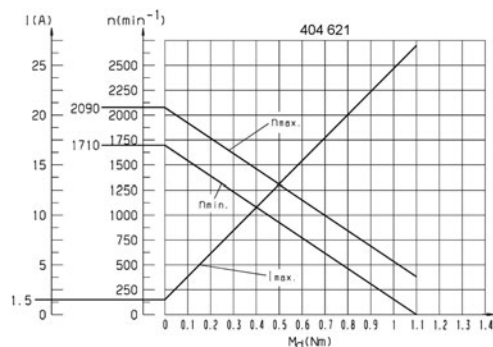
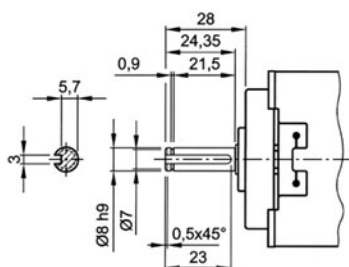
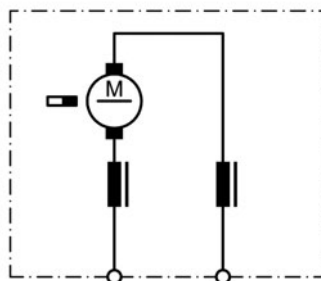
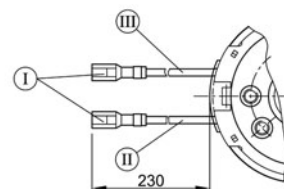
Sensor data

Pulses	0
Output channels	0

Other data

Gear ratio	Gearless
Gear wheel material	
Suppression components	5.0 μ H
Enclosure class	IP30
Weight [kg]	1.150

Remarks:

Characteristic curves**Motor picture****Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)****S 27****K 180**

- I Blade terminal receptacles 2,8 x 0,8 DIN 46 247
- II green
- III red

Series GML

Motor type 404 890

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.50
No-load speed [min^{-1}]	n_0	2,500.0
Nominal power [W]	P_N	96.5
Nominal current [A]	I_N	7.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

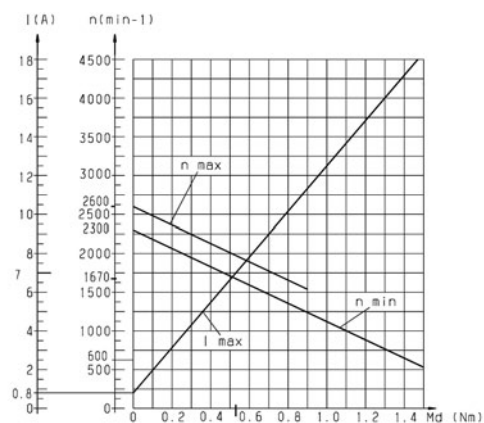
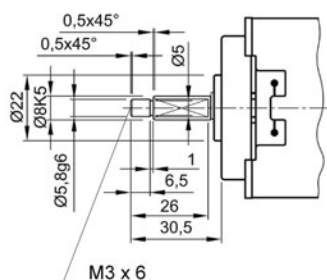
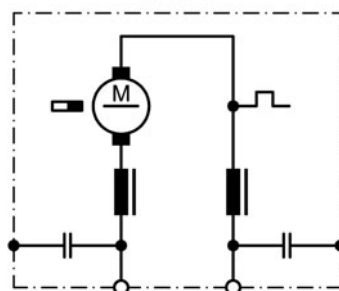
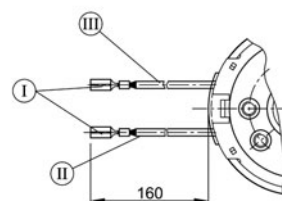
Sensor data

Pulses	0
Output channels	0

Other data

Gear ratio	Gearless
Gear wheel material	
Suppression components	5.0 μ H, 1nF
Enclosure class	IP30
Weight [kg]	1.150

Remarks:

Characteristic curves**Motor picture****Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)****S 74****K 190**

- I Receptacles for tabs 2,8 x 0,8 DIN 46 247
- II black
- III red

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.30
No-load speed [min^{-1}]	n_0	3,800.0
Nominal power [W]	P_N	105
Nominal current [A]	I_N	5.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

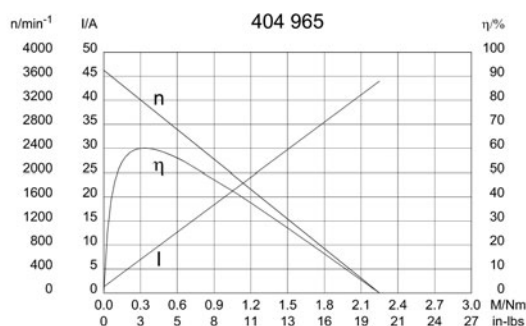
Pulses	0
Output channels	0

Other data

Gear ratio	
Gear wheel material	
Suppression components	5 μ H, 10nF
Enclosure class	IP 30
Weight [kg]	1.100

Remarks:

Characteristic curves

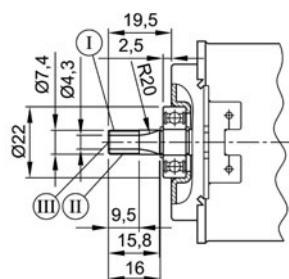


Motor picture

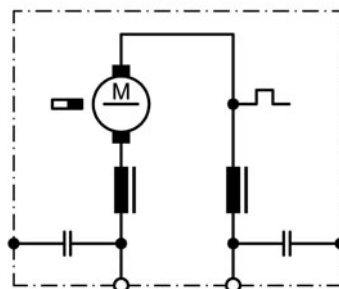


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

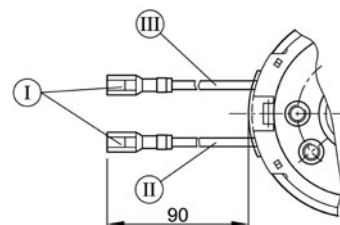
W 325



S 74



K 317



no of starts 7, lead angle 20°, pressure angle 20°, module 0,7, pitch 2,1991 mm (0,087"), induction hardened surface,

I Receptacle for tabs 6,3 x 0,8
 G&H 35040.213.011
 II red
 III green

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	0.30
No-load speed [min^{-1}]	n_0	3,730.0
Nominal power [W]	P_N	99.2
Nominal current [A]	I_N	16.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

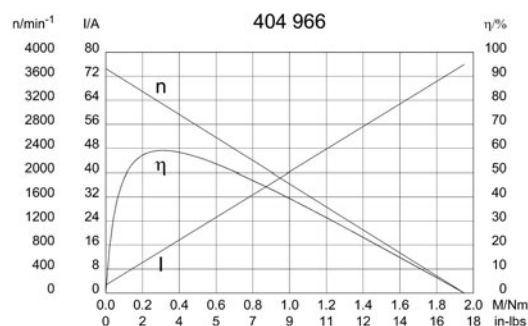
Pulses	0
Output channels	0

Other data

Gear ratio	
Gear wheel material	
Suppression components	5 μ H, 10nF
Enclosure class	IP 30
Weight [kg]	1.100

Remarks:

Characteristic curves

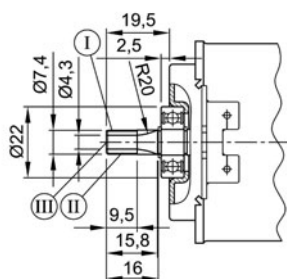


Motor picture

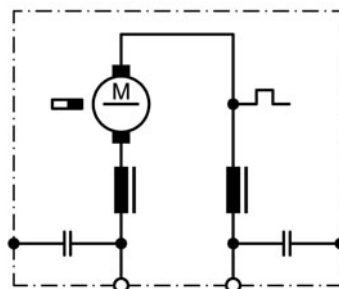


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

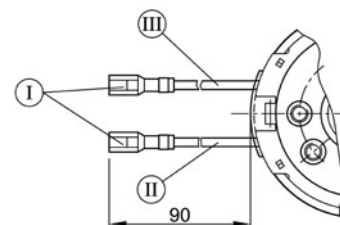
W 325



S 74



K 317



no of starts 7, lead angle 20°, pressure angle 20°, module 0,7, pitch 2,1991 mm (0,087"), induction hardened surface,

I Receptacle for tabs 6,3 x 0,8
 G&H 35040.213.011
 II red
 III green

Series GML
Motor type 404 967

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data

Rated voltage [V]	U_N	36
Nominal torque [Nm]	M_N	0.30
No-load speed [min^{-1}]	n_0	3,900.0
Nominal power [W]	P_N	109
Nominal current [A]	I_N	7.5
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

Pulses	0
Output channels	0

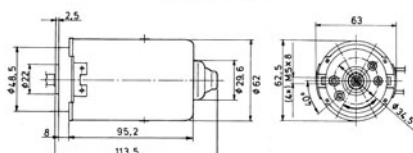
Other data

Gear ratio	
Gear wheel material	
Suppression components	5μH, 10nF
Enclosure class	IP 30
Weight [kg]	1.100

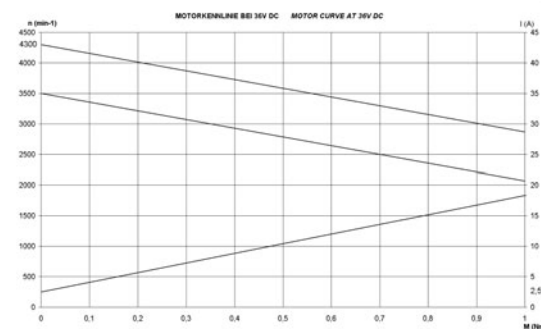
Remarks:

Characteristic curves

0273 A

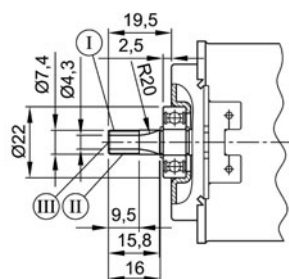


Motor picture

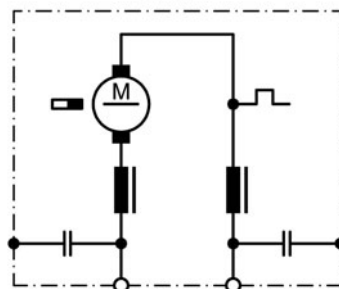


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

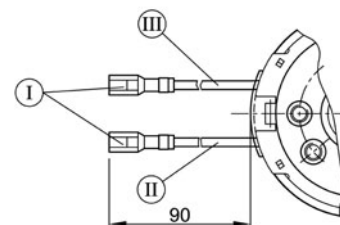
W 325



S 74



K 317



no of starts 7, lead angle 20°, pressure angle 20°, module 0,7, pitch 2,1991 mm (0,087"), induction hardened surface.

I Receptacle for tabs 6,3 x 0,8
G&H 35040.213.011

II red

III green

[illegible]



NIDEC MOTORS & ACTUATORS •••• MOTOR SERIES

0202 (GMAG)

•••• DC MOTORS WITH SPUR GEAR

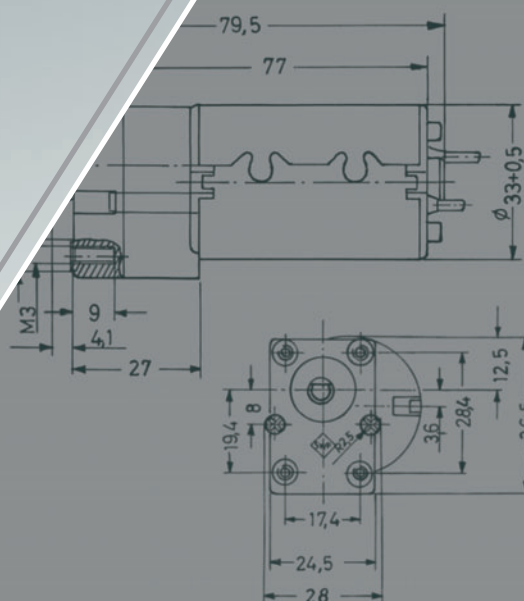


•••• TECHNICAL DESCRIPTION

Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	spur gear
Gear housing:	plastic
Gear wheel material:	steel or plastic
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	tinned leads or with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

•••• APPLICATION

Automatic machines, Constructional engineering
Business machines, Laboratory appliances
Medical appliances, Traffic & communications
technology, Photographic/optical equipment

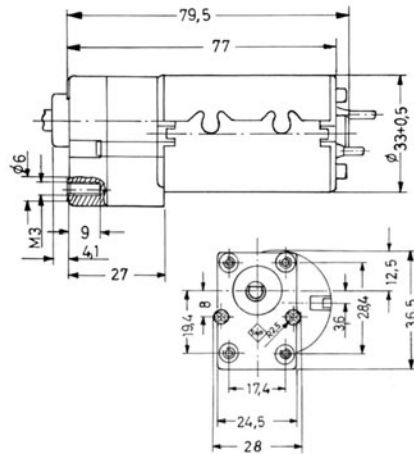


Series GMAG

Motor type 402 757

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Motor picture



Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	0.24
No-load speed [min^{-1}]	n_0	17.0
Nominal power [W]	P_N	0.37
Nominal current [A]	I_N	0.0
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

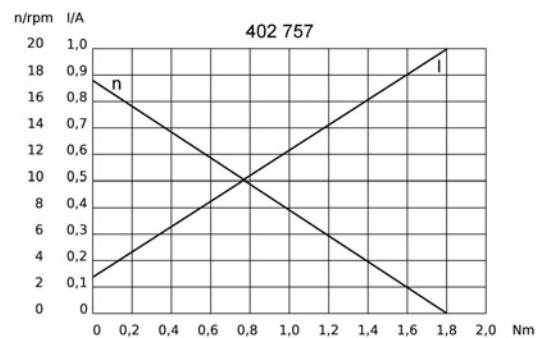
Pulses	0
Output channels	0

Other data

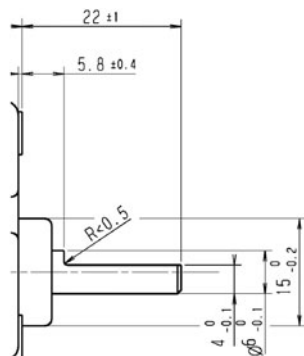
Gear ratio	109/1
Gear wheel material	
Suppression components	
Enclosure class	IP40
Weight [kg]	0.180

Remarks:

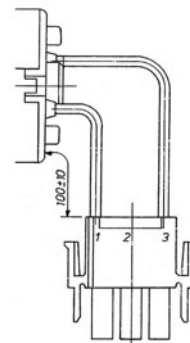
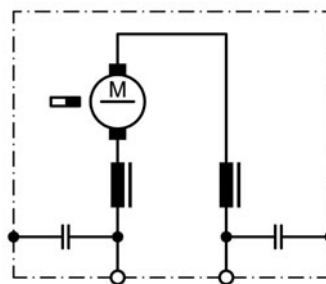
Characteristic curves



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30

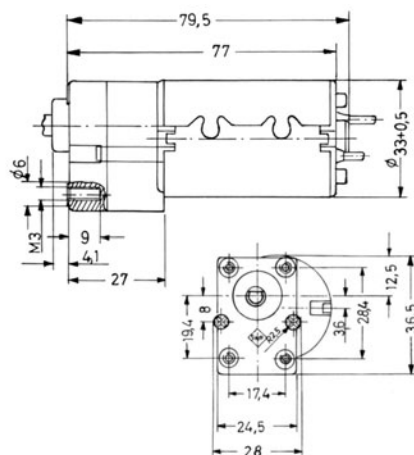


Series GMAG

Motor type 402 781

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.50
No-load speed [min^{-1}]	n_0	55.0
Nominal power [W]	P_N	2.56
Nominal current [A]	I_N	0.5
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

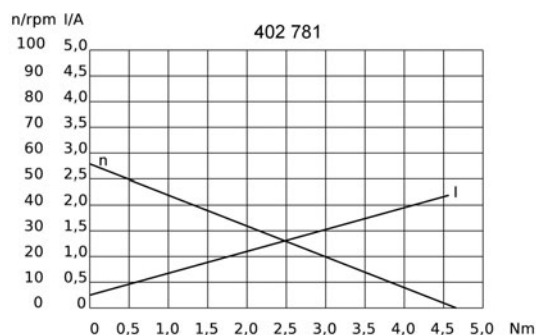
Pulses	0
Output channels	0

Other data

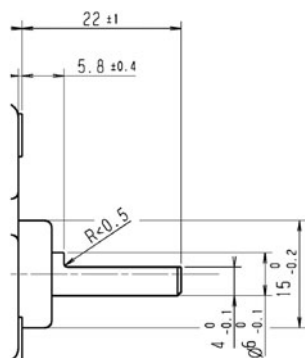
Gear ratio	109/1
Gear wheel material	
Suppression components	
Enclosure class	IP40
Weight [kg]	0.180

Remarks:

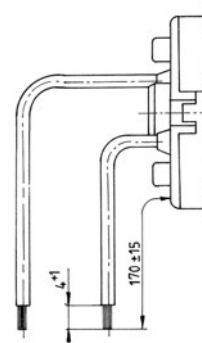
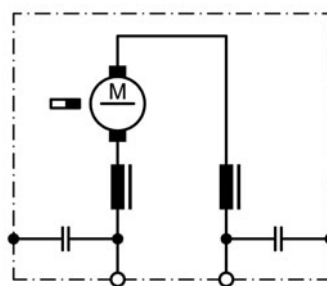
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30

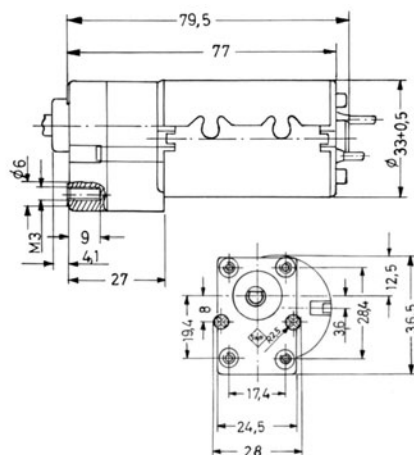


Series GMAG

Motor type 402 907

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.04
No-load speed [min^{-1}]	n_0	300.0
Nominal power [W]	P_N	1.07
Nominal current [A]	I_N	0.2
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

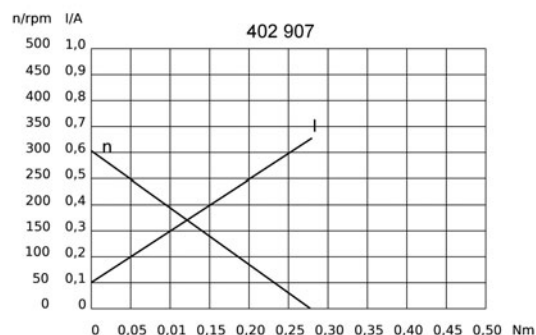
Pulses	0
Output channels	0

Other data

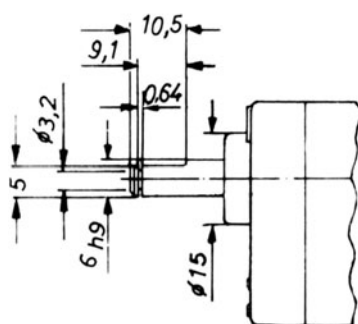
Gear ratio	9.7/1
Gear wheel material	
Suppression components	
Enclosure class	IP40
Weight [kg]	0.180

Remarks:

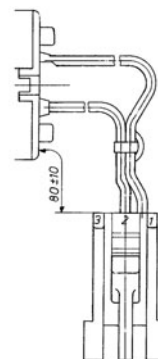
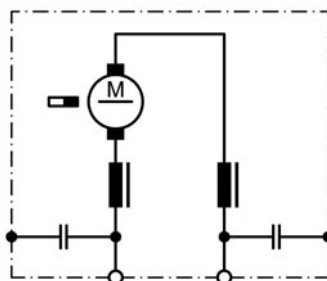
Characteristic curves



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30



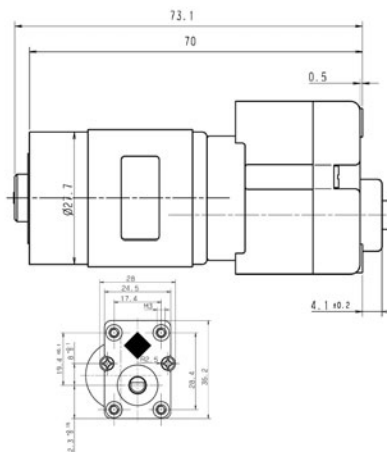
Connector Burndy
 Pins: SWM 1EF TV2
 Housing: SMS 2p-1

Series GMAG

Motor type 404 326

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.20
No-load speed [min^{-1}]	n_0	135.0
Nominal power [W]	P_N	2.26
Nominal current [A]	I_N	0.3
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

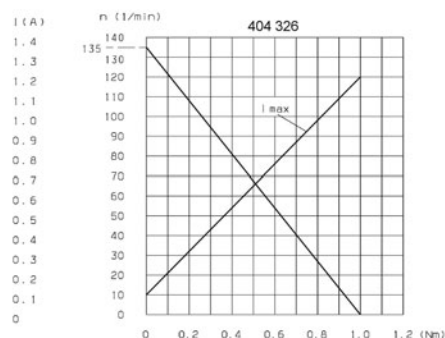
Pulses	0
Output channels	0

Other data

Gear ratio	43/1
Gear wheel material	
Suppression components	
Enclosure class	IP40
Weight [kg]	0.180

Remarks:

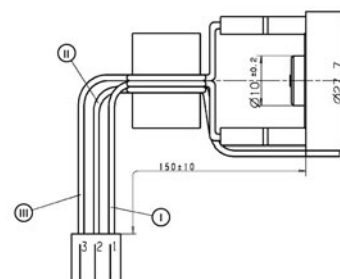
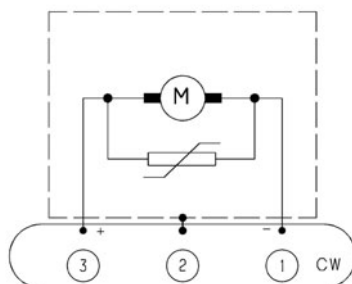
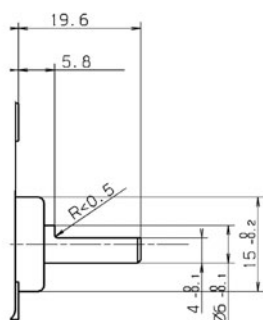
Characteristic curves



Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



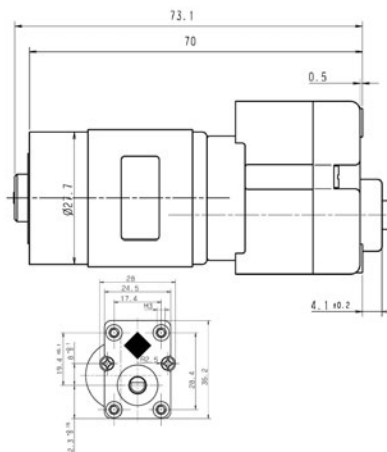
Housing: AMP-Nr.: 1-480 700-0
 Pins: AMP-Nr.: 350 570-1
 I: black
 II: yellow/green
 III: red

Series GMAG

Motor type 404 327

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.50
No-load speed [min^{-1}]	n_0	65.0
Nominal power [W]	P_N	2.84
Nominal current [A]	I_N	0.4
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

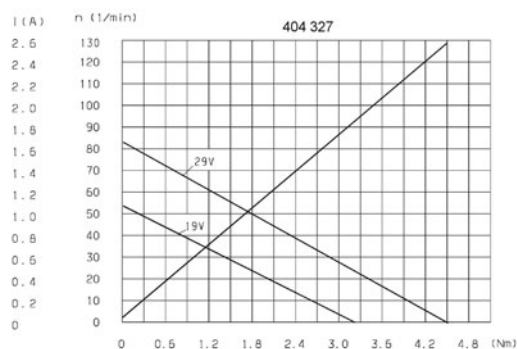
Pulses	0
Output channels	0

Other data

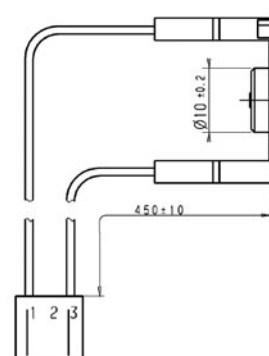
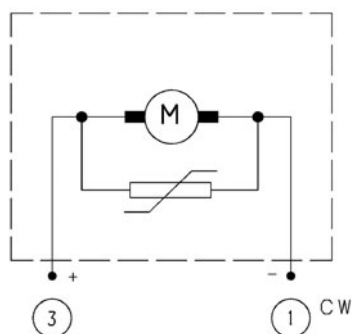
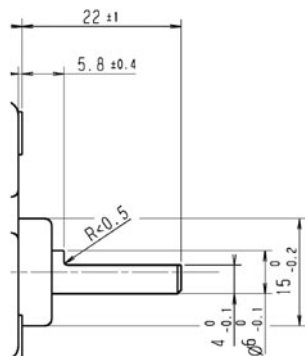
Gear ratio	109/1
Gear wheel material	
Suppression components	
Enclosure class	IP40
Weight [kg]	0.180

Remarks:

Characteristic curves



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



Housing: AMP-Nr. 1-480 700-0
 Pins: AMP-Nr. 350 687-1

0231 (GMPI)

 DC MOTORS WITH SPUR GEAR



TECHNICAL DESCRIPTION

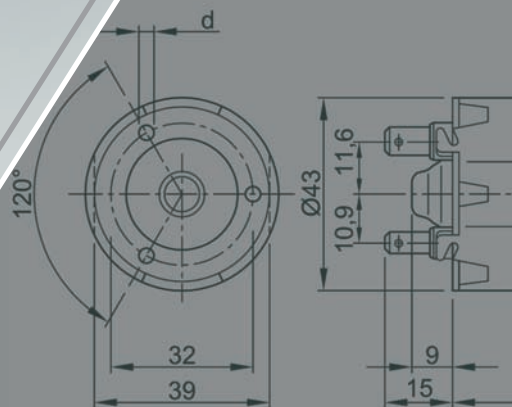
Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	spur gear
Gear housing:	plastic
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	connector or leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

INDUSTRIAL APPLICATION

Linear actuators, home automation

AUTOMOTIVE APPLICATION

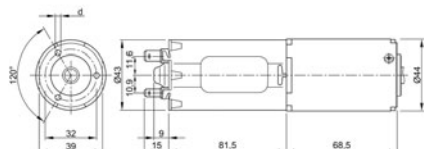
Spoiler adjustment



Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

0231 A



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	210.0
Nominal power [W]	P_N	72.0
Nominal current [A]	I_N	7.0
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

Pulses	0
Output channels	0

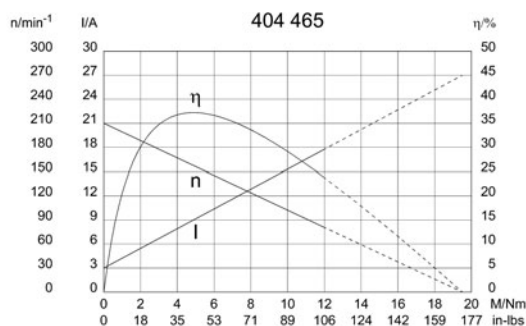
Other data

Gear ratio	39.7/1
Gear wheel material	plastic
Suppression components	7,5 μ H, 1nF
Enclosure class	IP30
Weight [kg]	0.630

Remarks: d = 3,3mm, for selftapping screw 4mm (shape Remform)

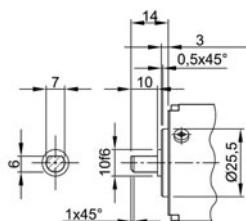
Characteristic curves

Motor picture

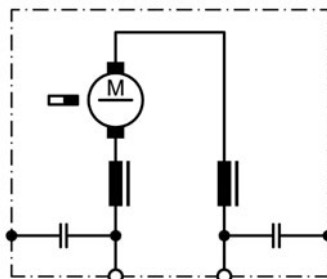


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

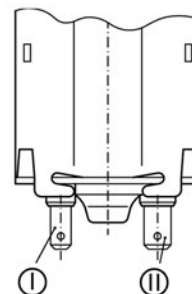
W 268



S 30



K 117

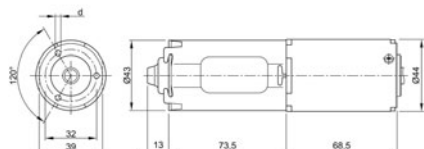


- I Blade terminal ends 4,8 x 0,8 DIN 46 244
- II Blade terminal ends 6,3 x 0,8 DIN 46 244

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

0231 C



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	1.50
No-load speed [min^{-1}]	n_0	178.0
Nominal power [W]	P_N	20.0
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

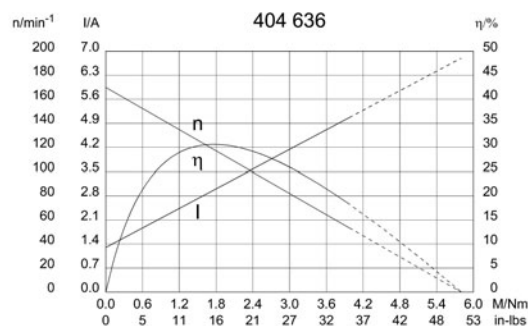
Pulses	20
Output channels	2

Other data

Gear ratio	20/1
Gear wheel material	plastic
Suppression components	4 μ H, 1nF
Enclosure class	IP 30
Weight [kg]	0.750

Remarks: d = 3,3mm, for self-cutting screw 4mm (shape Remform)

Characteristic curves

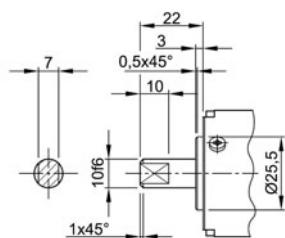


Motor picture

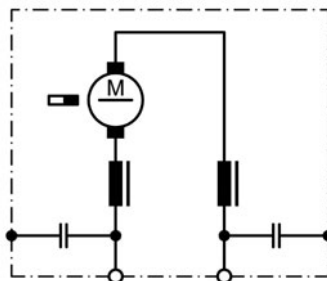


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

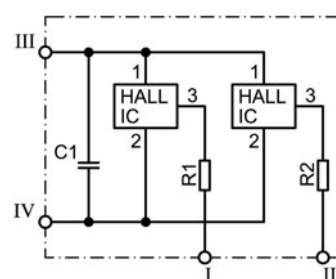
W 249



S 30



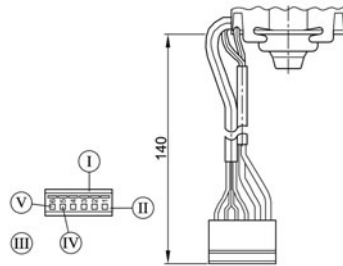
S 109



- I Terminal 1, OUT A1, grey
- II Terminal 2, OUT A2, black
- III Terminal 3, +, white
- IV Terminal 4, -, red

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

K 244



Crimp housing 0009501061 (3,96mm,0,156"),

Crimp terminals 008701031 mating with **PCB headers** 0026481066

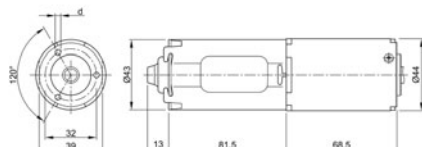
1 **grey** encoder out ch1, 2 **black** encoder out

ch2, **3 white** encoder +, **4 red** encoder -, **5 violet** motor, **6 blue** motor
www.molex.com

Notes

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	sleeve bearing

0231 B



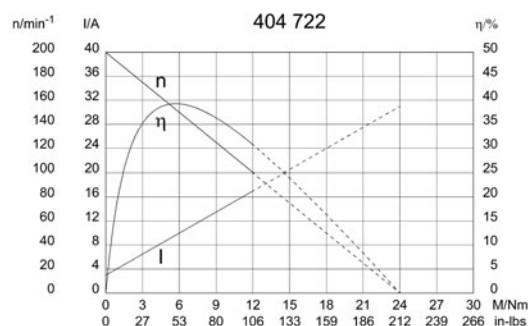
Performance data		
Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	200.0
Nominal power [W]	P_N	69.8
Nominal current [A]	I_N	8.0
Nominal force [kN]	F_N	0.00
Duty cycle		s2

Sensor data	
Pulses	39
Output channels	2

Other data	
Gear ratio	39.7/1
Gear wheel material	plastic
Suppression components	4,0 μ H, 1nF
Enclosure class	IP 30
Weight [kg]	0.650

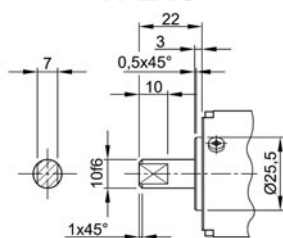
Remarks: d = 3,3mm, for self-cutting screw 4mm

Motor picture

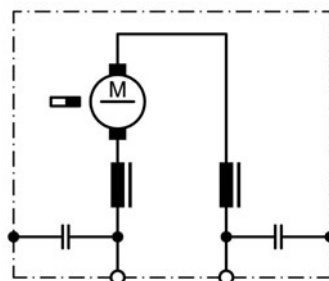


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

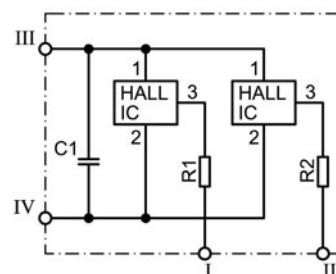
W 249



S 30



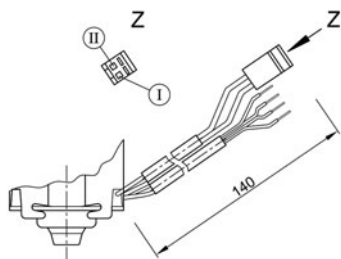
S 109



- I Terminal 1, OUT A1, grey
- II Terminal 2, OUT A2, black
- III Terminal 3, +, white
- IV Terminal 4, -, red

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

K 216



- I Terminal 1, motor, violet
- II Terminal 2, motor, blue

Notes

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve



Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	10.0
No-load speed [min^{-1}]	n_0	40.0
Nominal power [W]	P_N	34.4
Nominal current [A]	I_N	8.0
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

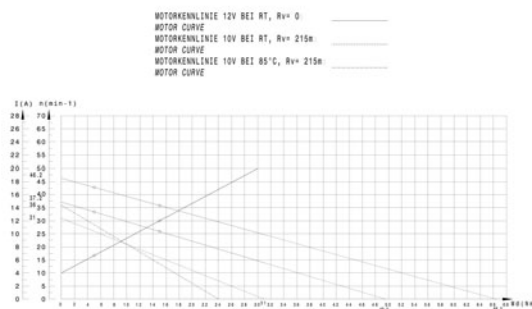
Pulses	116
Output channels	1

Other data

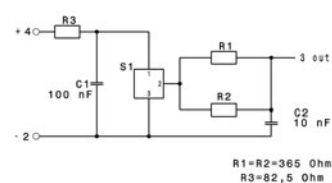
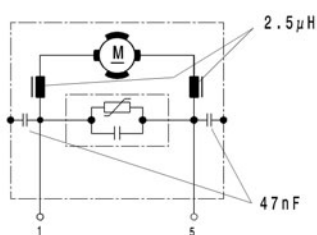
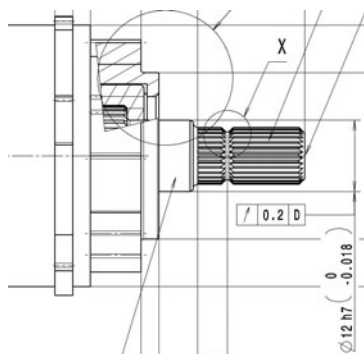
Gear ratio	116/1
Gear wheel material	plastic
Suppression components	2,5 μ H, 47nF, ()
Enclosure class	IP 30
Weight [kg]	0.800

Remarks:

Motor picture

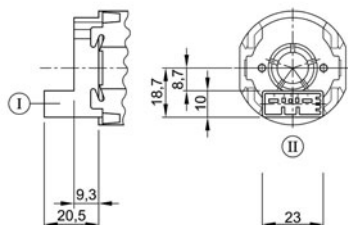


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

K 220



Connector TYCO C-208-15621 (Z) mating with:
Connector housing 1379217-3 & cover
 1379218-2
www.tycoelectronics.com

Notes



NIDEC MOTORS & ACTUATORS ⇄ MOTOR SERIES

0320 (GMPD)

⇄ DC MOTORS WITH WORM GEAR



⇄ TECHNICAL DESCRIPTION

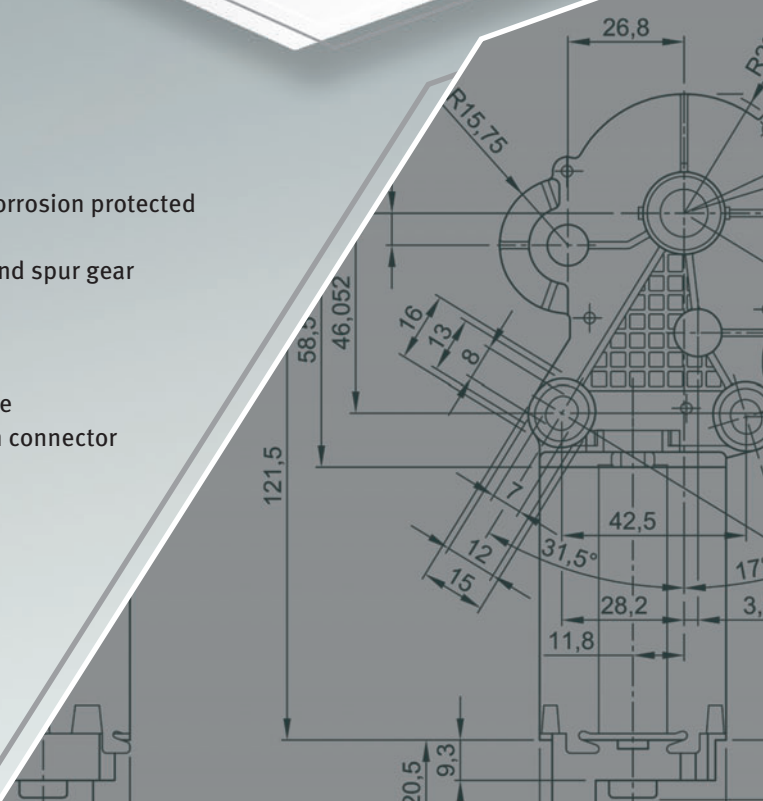
Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	combination of worm and spur gear
Gear housing:	plastic
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	hollow shaft with profile
Electric interface:	connector or leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

⇄ INDUSTRIAL APPLICATION

Machine construction

⇄ AUTOMOTIVE APPLICATION

Seat Recline Adjustment



Series GMPD

Motor type 404 682

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	40.0
Nominal power [W]	P_N	14.8
Nominal current [A]	I_N	3.5
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

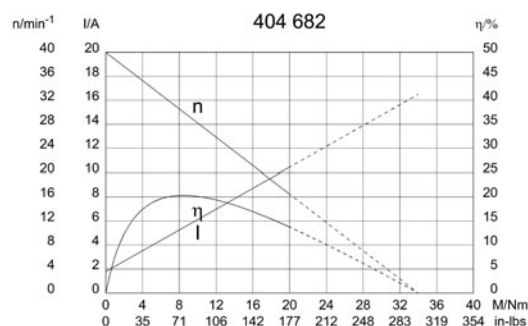
Pulses	0
Output channels	0

Other data

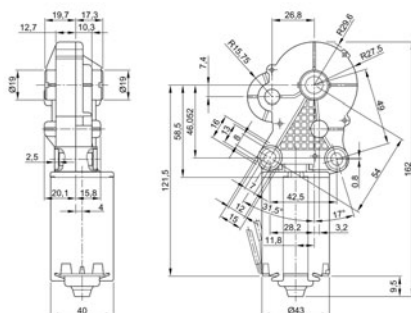
Gear ratio	210/1
Gear wheel material	plastic
Suppression components	7,5 μ H, 1nF
Enclosure class	IP 40
Weight [kg]	0.440

Remarks:

Characteristic curves



0320 AR

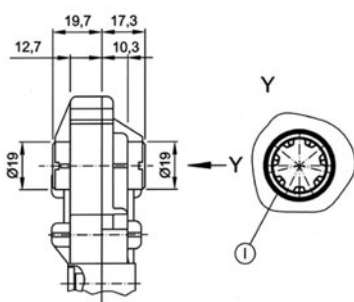


Motor picture

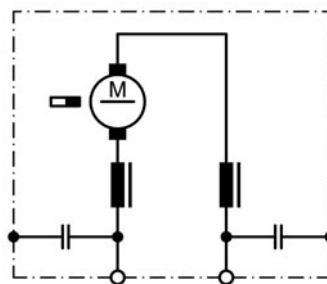


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

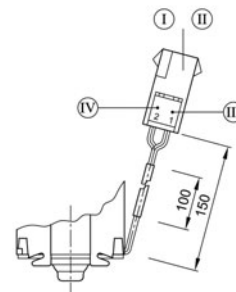
W 224



S 30



K 206



I through Profile KRC 316928 AEIZ 01

tap housing 365057-3, timer contacts 928781-5

mating with receptacle housing 365058-3,

timer contacts 927768-1

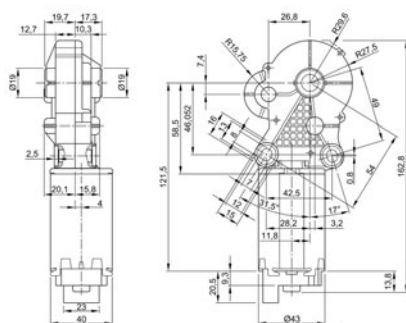
1 black motor, 2 blue motor

Series GMPD
Motor type 404 747

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

0320 BR



Motor picture



Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	3.00
No-load speed [min^{-1}]	n_0	21.0
Nominal power [W]	P_N	5.59
Nominal current [A]	I_N	3.5
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

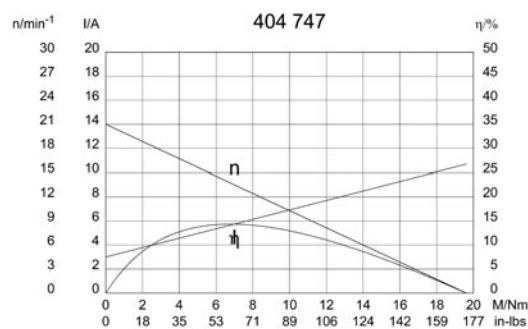
Pulses	0
Output channels	0

Other data

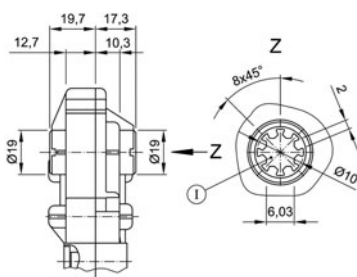
Gear ratio	210/1
Gear wheel material	plastic
Suppression components	5,5μH, 47nF, (0,47μF)
Enclosure class	IP 40
Weight [kg]	0.440

Remarks:

Characteristic curves

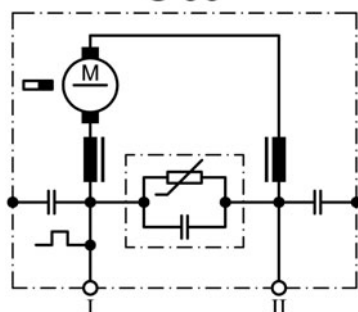


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 270

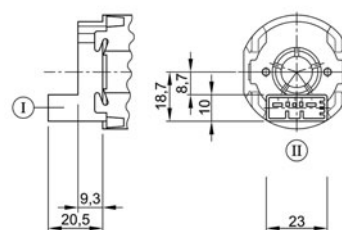
I through profile

S 93



- I Terminal 1
- II Terminal 5

K 220



Connector TYCO C-208-15621 (Z) mating with:
Connector housing 1379217-3 & cover
 1379218-2
www.tycoelectronics.com

Series GMPD

Motor type 404 748

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	3.00
No-load speed [min^{-1}]	n_0	21.0
Nominal power [W]	P_N	5.59
Nominal current [A]	I_N	3.5
Nominal force [kN]	F_N	0.00
Duty cycle		s3

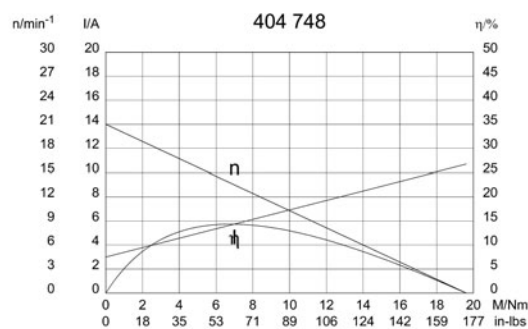
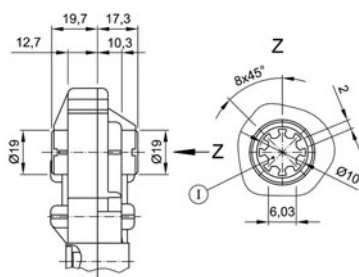
Sensor data

Pulses	210
Output channels	1

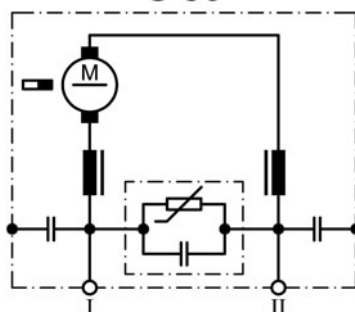
Other data

Gear ratio	210/1
Gear wheel material	plastic
Suppression components	5,5 μ H, 47nF, (0,47 μ F)
Enclosure class	IP 40
Weight [kg]	0.440

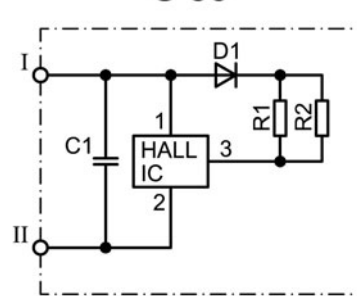
Remarks:

Characteristic curves**Motor picture****Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)****W 270**

I through profile

S 86

I Terminal 1
 II Terminal 5

S 85

I Terminal 4, Hall-IC +
 II Terminal 2, Hall-IC -

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	22.0
Nominal power [W]	P_N	7.54
Nominal current [A]	I_N	1.8
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

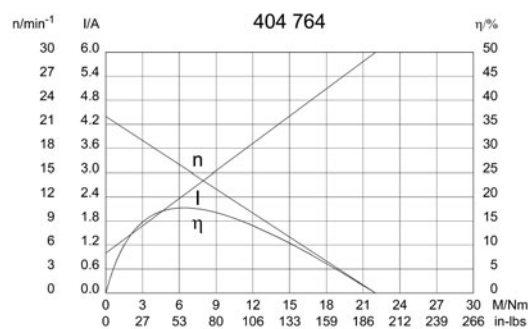
Pulses	0
Output channels	0

Other data

Gear ratio	210/1
Gear wheel material	plastic
Suppression components	7,5 μ H, 47nF, (0,47 μ F)
Enclosure class	IP 40
Weight [kg]	0.440

Remarks:

Characteristic curves

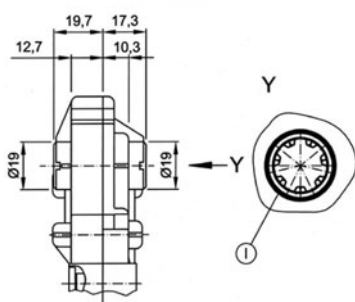


Motor picture

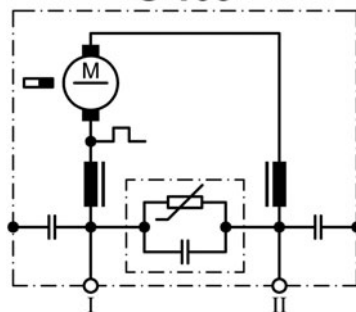


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

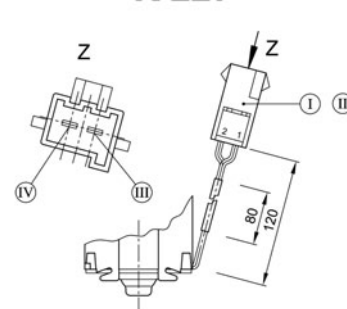
W 224



S 103



K 227



I through Profile KRC 316928 AEIZ 01

I Terminal 1, black
 II Terminal 2, blue

tap housing 365057-1, timer contacts 928781-5
 mating with receptacle housing 365058-1,
 timer contacts 927768-1
 1 black motor, 2 blue motor

Series GMPD

Motor type 404 904

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	21.0
Nominal power [W]	P_N	3.95
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle		s3

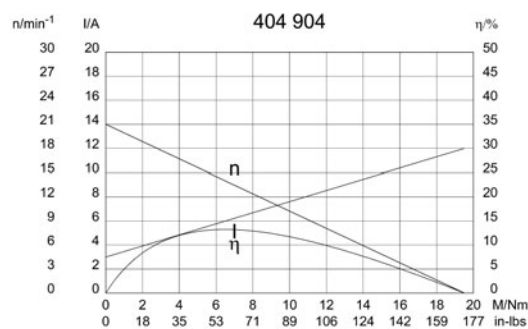
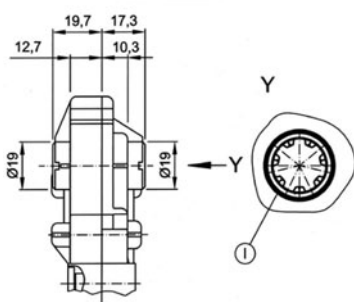
Sensor data

Pulses	0
Output channels	0

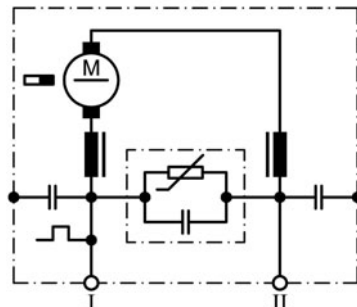
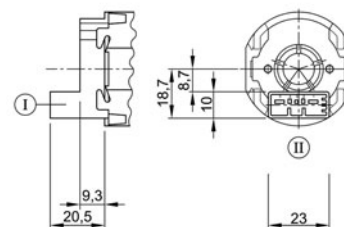
Other data

Gear ratio	210/1
Gear wheel material	plastic
Suppression components	5,5 μ H, 47nF
Enclosure class	IP 40
Weight [kg]	0.440

Remarks:

Characteristic curves**Motor picture****Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)****W 224**

I through Profile KRC 316928 AEIZ 01

S 93I Terminal 1
II Terminal 5**K 220**

Connector TYCO C-208-15621 (Z) mating with:
Connector housing 1379217-3 & cover
 1379218-2
www.tycoelectronics.com

Series GMPD

Motor type 404 905

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	21.0
Nominal power [W]	P_N	3.95
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle		s2

Sensor data

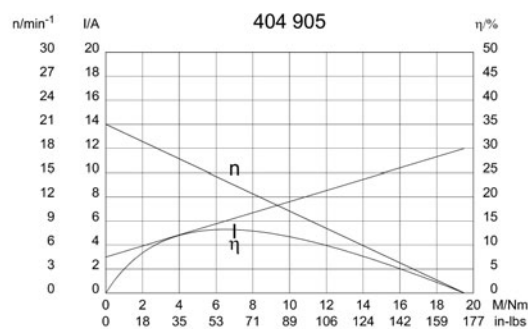
Pulses	210
Output channels	1

Other data

Gear ratio	210/1
Gear wheel material	plastic
Suppression components	5,5 μ H, 47nF
Enclosure class	IP 40
Weight [kg]	0.440

Remarks:

Characteristic curves

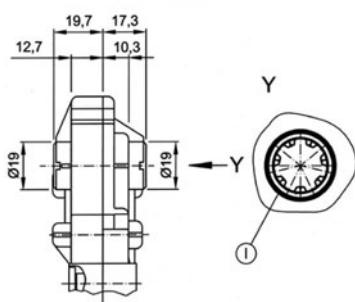


Motor picture



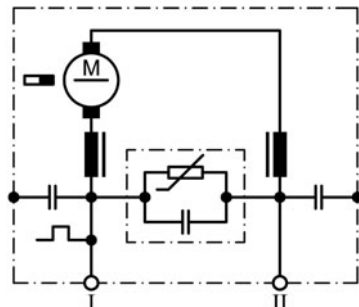
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 224



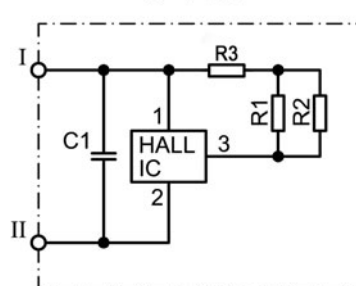
I through Profile KRC 316928 AEIZ 01

S 93



I Terminal 1
 II Terminal 5

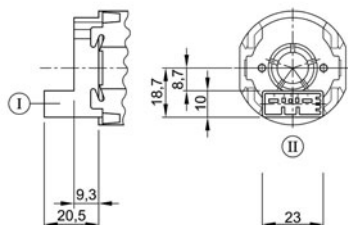
S 140



I Terminal 4; Hall-IC +
 II Terminal 2; Hall-IC -

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

K 220



Connector TYCO C-208-15621 (Z) mating with:
Connector housing 1379217-3 & cover
 1379218-2
www.tycoelectronics.com

Notes

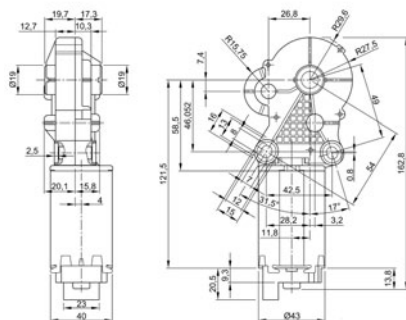
[illegible]

Series GMPD
Motor type 404 907

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

0320 BR



Motor picture



Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	21.0
Nominal power [W]	P_N	3.92
Nominal current [A]	I_N	3.5
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

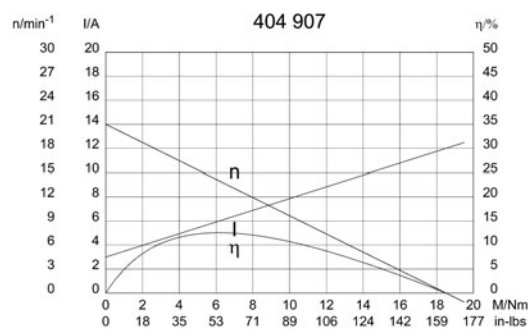
Pulses	210
Output channels	1

Other data

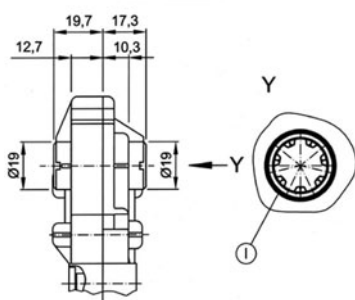
Gear ratio	210/1
Gear wheel material	plastic
Suppression components	""
Enclosure class	IP 40
Weight [kg]	0.440

Remarks: Plastic gearbox

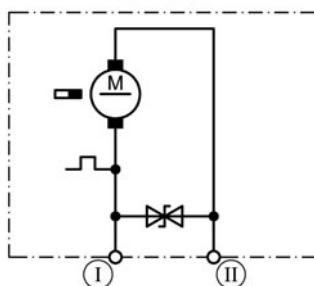
Characteristic curves



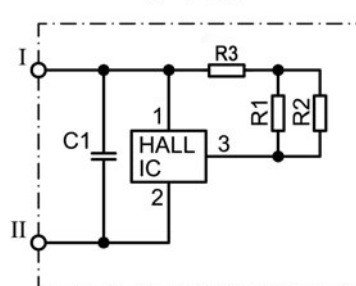
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 224

S 138



S 140



I through Profile KRC 316928 AEIZ 01

- I Terminal 1
- II Terminal 5

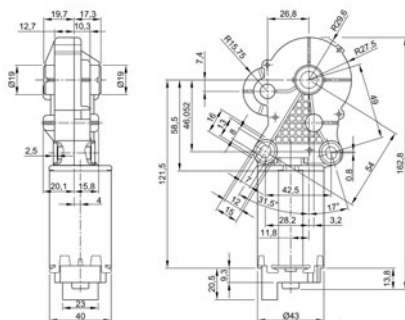
- I Terminal 4; Hall-IC +
- II Terminal 2; Hall-IC -

Series GMPD
Motor type 404 980

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

0320 BR



Motor picture



Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	22.0
Nominal power [W]	P_N	4.10
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

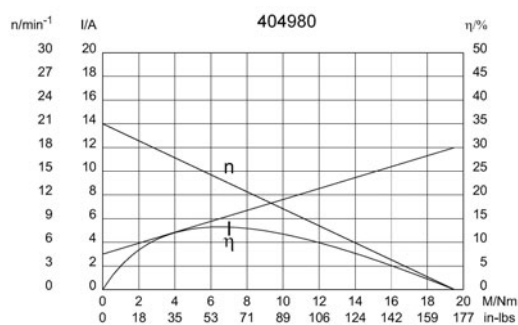
Pulses	0
Output channels	0

Other data

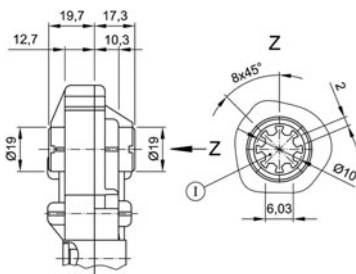
Gear ratio	210/1
Gear wheel material	plastic
Suppression components	7.5μH, 1nF
Enclosure class	IP40
Weight [kg]	0.440

Remarks:

Characteristic curves

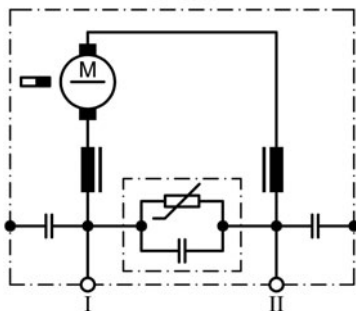


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 270

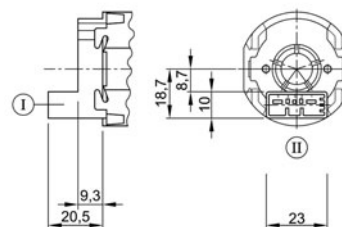
I through profile

S 86



- I Terminal 1
- II Terminal 5

K 220



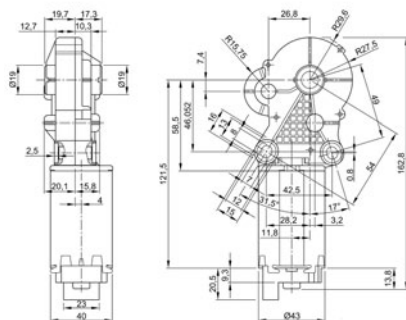
Connector TYCO C-208-15621 (Z) mating with:
Connector housing 1379217-3 & cover
1379218-2
www.tycoelectronics.com

Series GMPD
Motor type 405 031

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

0320 BR



Motor picture



Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	22.0
Nominal power [W]	P_N	4.19
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

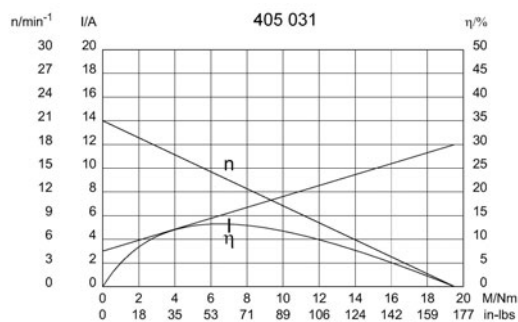
Pulses	210
Output channels	1

Other data

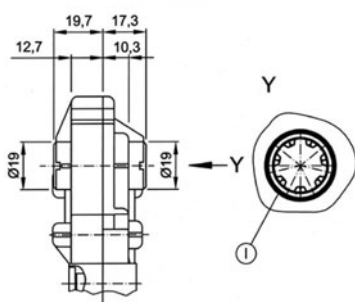
Gear ratio	210/1
Gear wheel material	plastic
Suppression components	5,5μH, 47nF
Enclosure class	IP 40
Weight [kg]	0.000

Remarks:

Characteristic curves

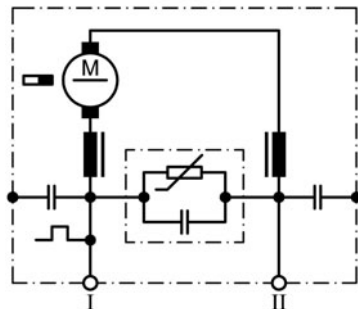


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

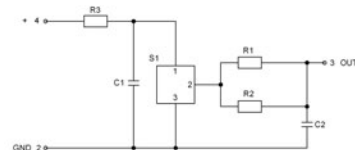
W 224

I through Profile KRC 316928 AEIZ 01

S 93

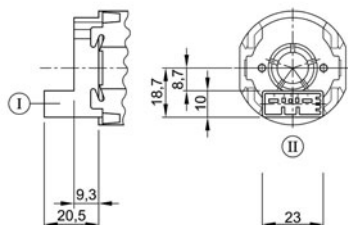


- I Terminal 1
- II Terminal 5



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

K 220



Connector TYCO C-208-15621 (Z) mating with:
Connector housing 1379217-3 & cover
 1379218-2
www.tycoelectronics.com

Notes

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	21.0
Nominal power [W]	P_N	3.95
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

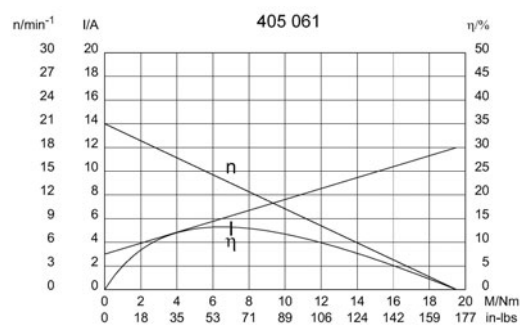
Pulses	210
Output channels	2

Other data

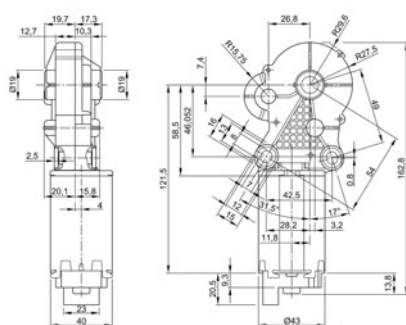
Gear ratio	210/1
Gear wheel material	plastic
Suppression components	5,5 μ H, 47nF
Enclosure class	IP 40
Weight [kg]	0.000

Remarks:

Characteristic curves

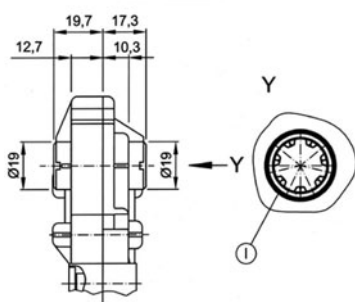


Motor picture

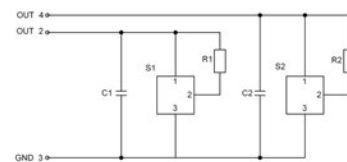
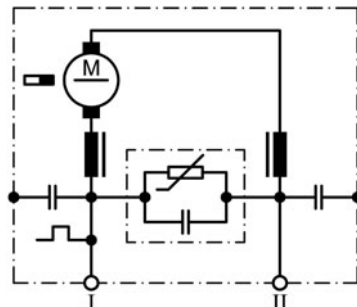


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 224



S 93



I through Profile KRC 316928 AEIZ 01

I Terminal 1
 II Terminal 5

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	20.0
Nominal power [W]	P_N	6.70
Nominal current [A]	I_N	2.0
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

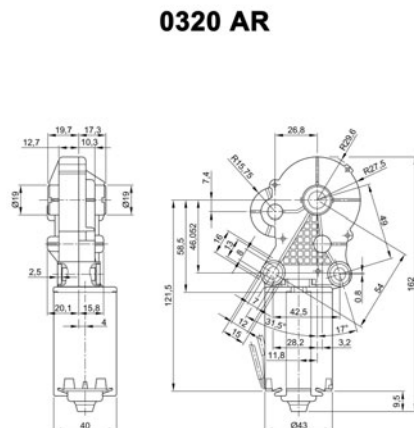
Pulses	0
Output channels	0

Other data

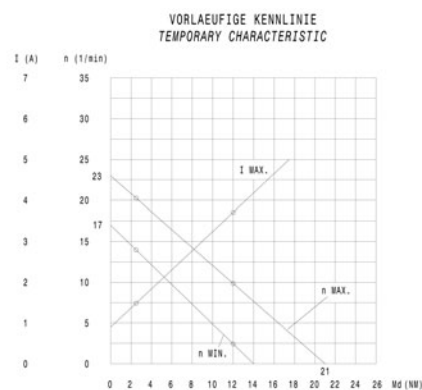
Gear ratio	246.75/1
Gear wheel material	plastic
Suppression components	7,5 μ , 47nF
Enclosure class	IP 40
Weight [kg]	0.440

Remarks:

Characteristic curves

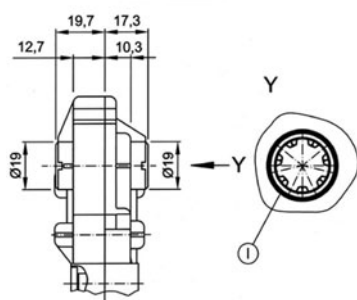


Motor picture

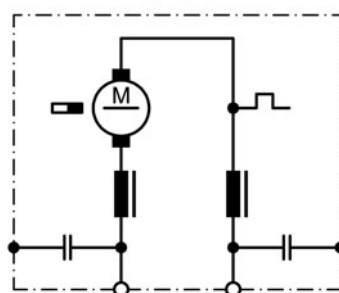


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

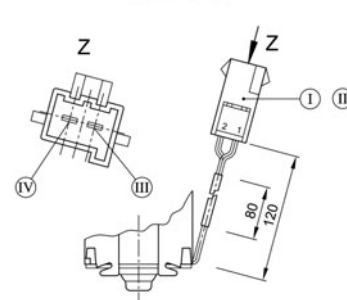
W 224



S 74



K 227



I through Profile KRC 316928 AEIZ 01

tap housing 365057-1, timer contacts 928781-5
 mating with receptacle housing 365058-1,
 timer contacts 927768-1
 1 black motor, 2 blue motor

Notes

This image shows a single sheet of white paper with horizontal blue or grey ruling lines. The lines are evenly spaced and run across the width of the page. There are approximately 20 lines visible. The paper has a slight shadow on its right side, suggesting it's resting on a surface.

0225 (GMPG)

⇄ DC MOTORS WITH WORM GEAR



⇄ TECHNICAL DESCRIPTION

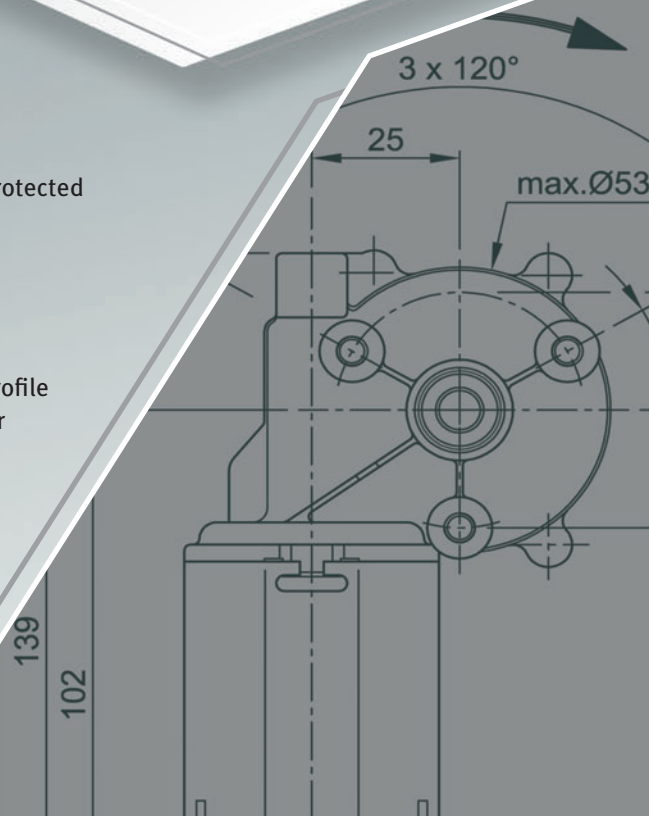
Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	zinc die cast
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	steel shaft or hollow shaft with profile
Electric interface:	connector or leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

⇄ INDUSTRIAL APPLICATION

Catering, Office machines, Furniture Adjustment,
Machine Construction

⇄ AUTOMOTIVE APPLICATION

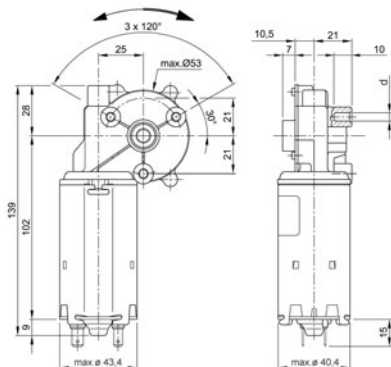
Sunroof adjustment



Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

0225 AR



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	1.00
No-load speed [min^{-1}]	n_0	80.0
Nominal power [W]	P_N	7.33
Nominal current [A]	I_N	1.5
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

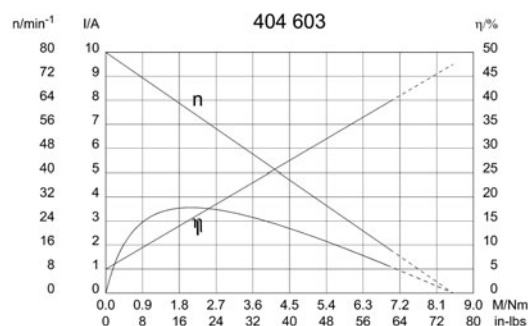
Pulses	0
Output channels	0

Other data

Gear ratio	62/1
Gear wheel material	plastic
Suppression components	
Enclosure class	IP 30
Weight [kg]	0.610

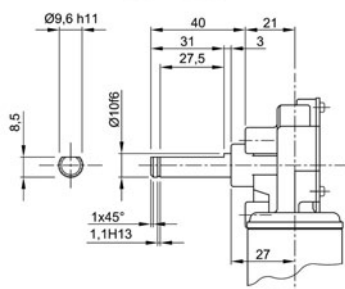
Remarks: d=selftapping screw M5

Characteristic curves

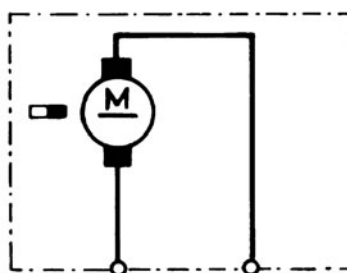


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

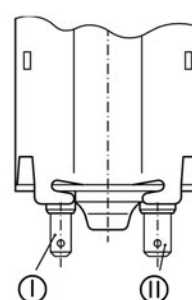
W 147



S 28



K 117



- I - Blade terminal ends 4,8 x 0,8 DIN 46 244
- II - Blade terminal ends 6,3 x 0,8 DIN 46 244

Series GMPG
Motor type 404 157

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.50
No-load speed [min^{-1}]	n_0	540.0
Nominal power [W]	P_N	24.7
Nominal current [A]	I_N	2.0
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

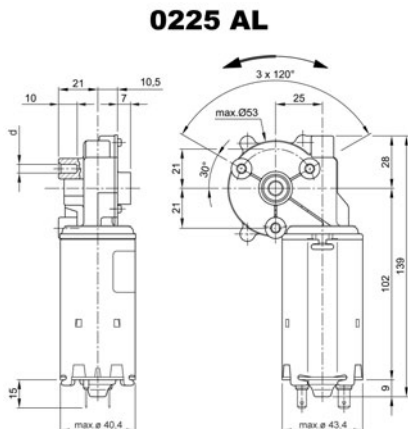
Pulses	0
Output channels	0

Other data

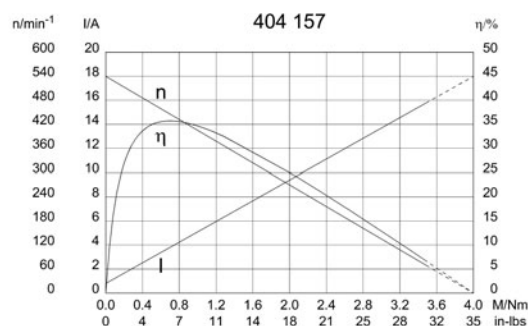
Gear ratio	56/4
Gear wheel material	plastic
Suppression components	7,5μH, 1nF
Enclosure class	IP 30
Weight [kg]	0.710

Remarks: d = for thread-forming screw M 5 DIN 7500

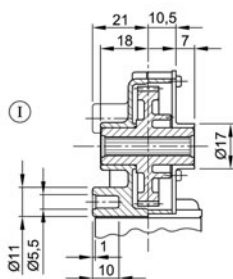
Characteristic curves



Motor picture

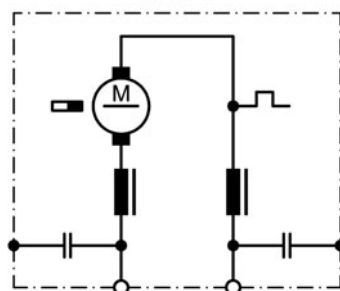
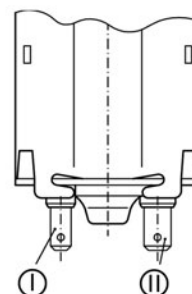


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 148

I Tapered splines 7 x 8 DIN 5481
continuous

S 74

**K 117**

- I Blade terminal ends 4,8 x 0,8 DIN 46 244
- II Blade terminal ends 6.3 x 0.8 DIN 46 244

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	0.50
No-load speed [min^{-1}]	n_0	60.0
Nominal power [W]	P_N	2.83
Nominal current [A]	I_N	2.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

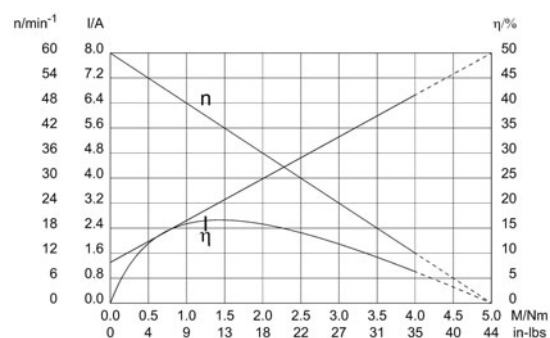
Pulses	0
Output channels	0

Other data

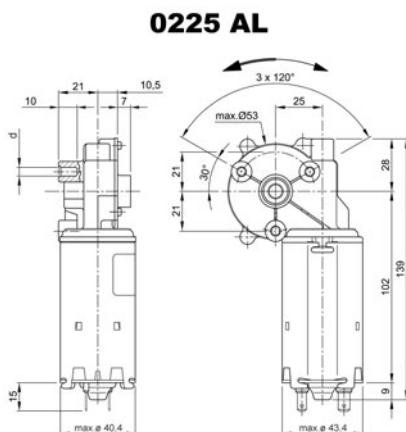
Gear ratio	62/1
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

Remarks:

Characteristic curves

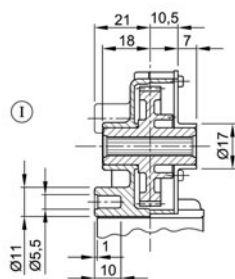


Motor picture



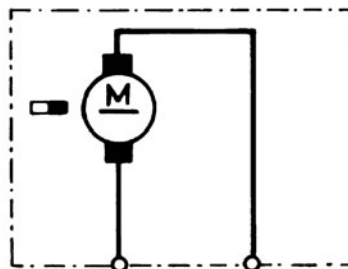
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 148

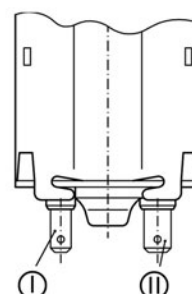


I Tapered splines 7 x 8 DIN 5481 continuous

S 28



K 117



I Blade terminal ends 4,8 x 0,8 DIN 46 244
 II Blade terminal ends 6,3 x 0,8 DIN 46 244

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	1.00
No-load speed [min^{-1}]	n_0	80.0
Nominal power [W]	P_N	7.39
Nominal current [A]	I_N	2.0
Nominal force [kN]	F_N	0.00
Duty cycle	s3	

Sensor data

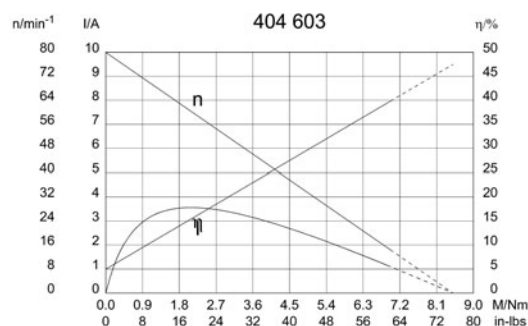
Pulses	0
Output channels	0

Other data

Gear ratio	62/1
Gear wheel material	plastic
Suppression components	7,5 μ H, 1nF
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = for thread-forming screw M 5 DIN 7500

Characteristic curves

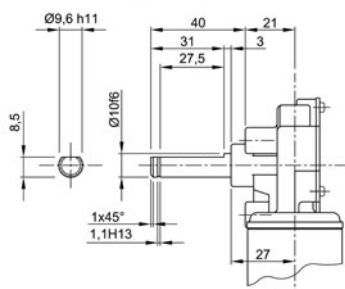


Motor picture

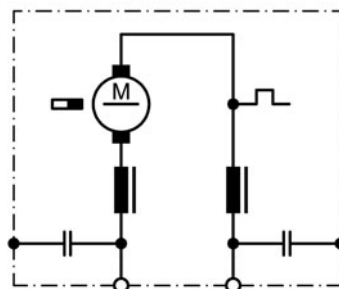


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

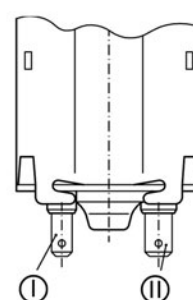
W 147



S 74



K 117



- I - Blade terminal ends 4,8 x 0,8 DIN 46 244
- II - Blade terminal ends 6,3 x 0,8 DIN 46 244

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	1.00
No-load speed [min^{-1}]	n_0	28.0
Nominal power [W]	P_N	2.48
Nominal current [A]	I_N	1.0
Nominal force [kN]	F_N	0.00
Duty cycle		s2

Sensor data

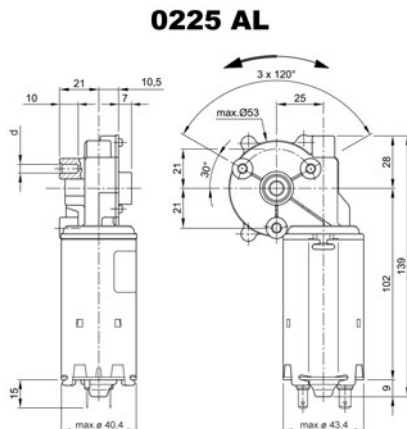
Pulses	0
Output channels	0

Other data

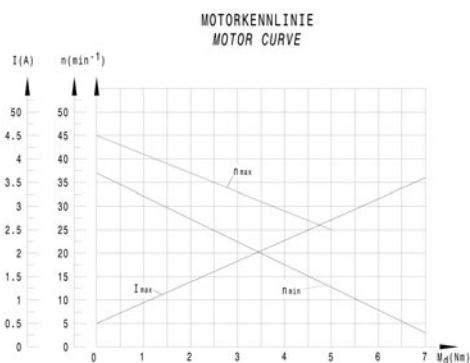
Gear ratio	72/1
Gear wheel material	plastic
Suppression components	7,5 μ H, 1nF
Enclosure class	IP 30
Weight [kg]	0.710

Remarks: d=selftapping screw M5

Characteristic curves

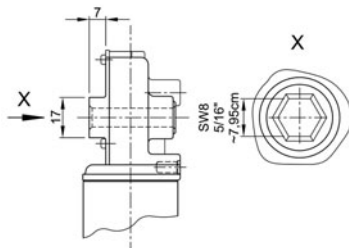


Motor picture

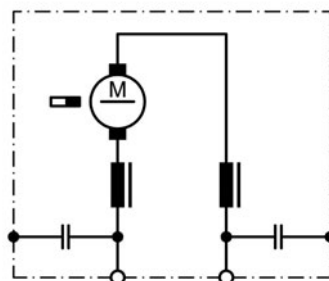


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

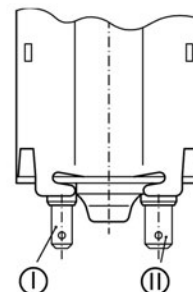
W 229



S 30



K 117



- I Blade terminal ends 4,8 x 0,8 DIN 46 244
- II Blade terminal ends 6,3 x 0,8 DIN 46 244

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	140.0
Nominal power [W]	P_N	25.1
Nominal current [A]	I_N	5.0
Nominal force [kN]	F_N	0.00
Duty cycle	s3	

Sensor data

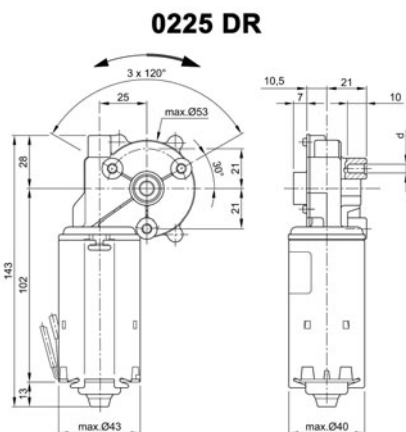
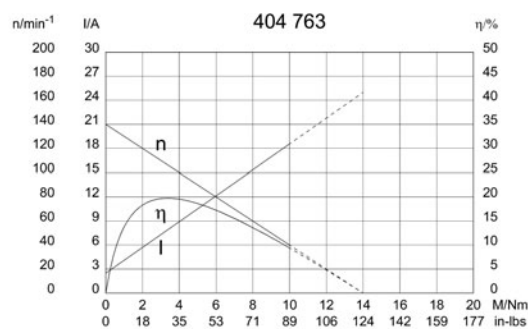
Pulses	62
Output channels	2

Other data

Gear ratio	62/1
Gear wheel material	plastic
Suppression components	4 μ H, 1nF
Enclosure class	IP 30
Weight [kg]	0.710

Remarks: d = for thread-forming screw M5 DIN 7500

Characteristic curves

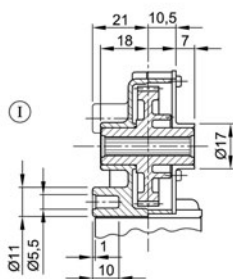


Motor picture



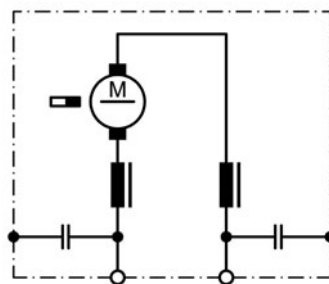
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 148

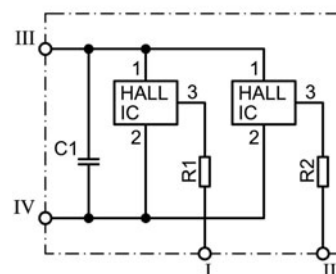


I Tapered splines 7 x 8 DIN 5481 continuous

S 30



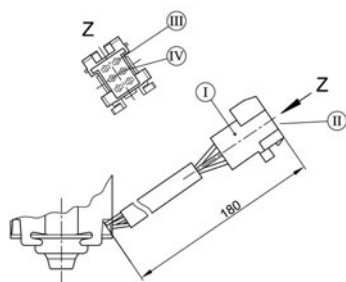
S 109



I Terminal 1, OUT A1, grey
 II Terminal 2, OUT A2, black
 III Terminal 3, +, white
 IV Terminal 4, -, red

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

K 205



I Connector housing AMP 929505-2 mating

with connector AMP 929504-2

blue motor, **violet** motor, **white** encoder +, **red** encoder -, **grey** A1, **black** A2

Notes

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	1.30
No-load speed [min^{-1}]	n_0	35.0
Nominal power [W]	P_N	3.94
Nominal current [A]	I_N	1.5
Nominal force [kN]	F_N	0.00
Duty cycle		s3

Sensor data

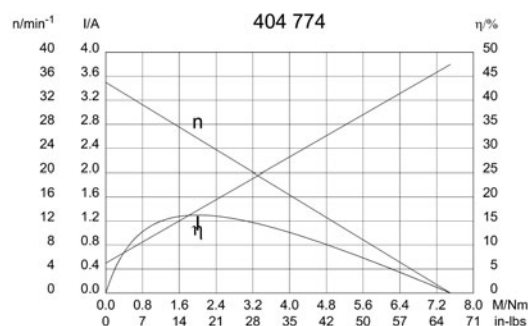
Pulses	0
Output channels	0

Other data

Gear ratio	72/1
Gear wheel material	plastic
Suppression components	7,5 μ H, 1nF
Enclosure class	IP 30
Weight [kg]	0.570

Remarks: d = for self-tapping screw M5 DIN 7500

Characteristic curves

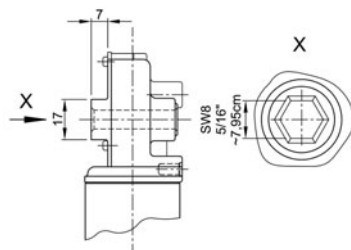


Motor picture

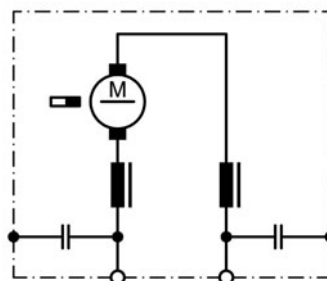


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

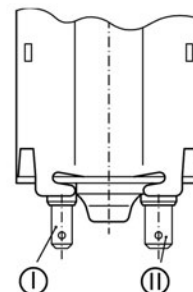
W 229



S 30



K 117



- I - Blade terminal ends 4,8 x 0,8 DIN 46 244
- II - Blade terminal ends 6,3 x 0,8 DIN 46 244

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	1.50
No-load speed [min^{-1}]	n_0	35.0
Nominal power [W]	P_N	4.47
Nominal current [A]	I_N	1.5
Nominal force [kN]	F_N	0.00
Duty cycle	s3	

Sensor data

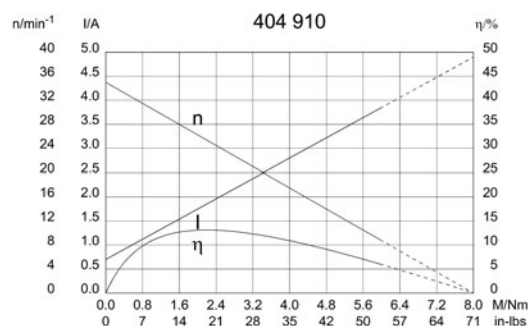
Pulses	288
Output channels	1

Other data

Gear ratio	72/1
Gear wheel material	plastic
Suppression components	7,5 μ H
Enclosure class	IP 30
Weight [kg]	0.710

Remarks: d = for thread-forming screw M5 DIN 7500

Characteristic curves

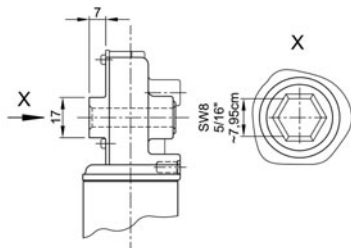


Motor picture

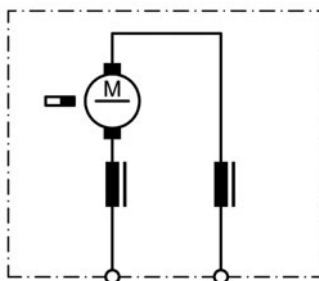


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

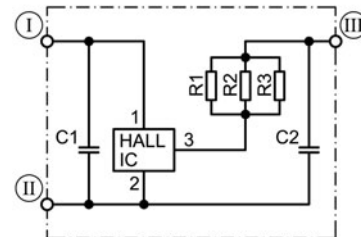
W 229



S 27



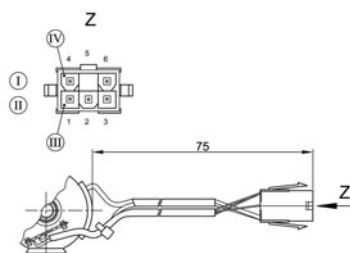
S 125



- I Terminal 3, +, white
- II Terminal 2, -, black
- III Terminal 6, OUT, red

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

K 268



plug housing Molex minifit jr 39-01-2066

(4,2mm - .165"), **terminals** Molex 39-00-0430
(18-24AWG, gold plated)

1 violet motor, **2 black** encoder gnd, **3 white** encoder +, **4 blue** motor, **6 red** encoder out

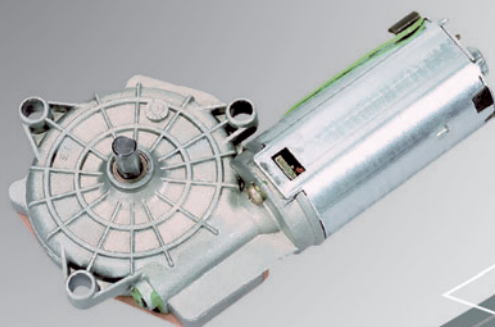
Notes

Notes

This image shows a single sheet of white paper with horizontal blue or grey ruling lines. The lines are evenly spaced and run across the width of the page. There are approximately 20 lines visible. The paper has a slight shadow on the right side, suggesting it's resting on a surface.

0223 (SWMP)

❖❖❖ DC MOTORS WITH WORM GEAR

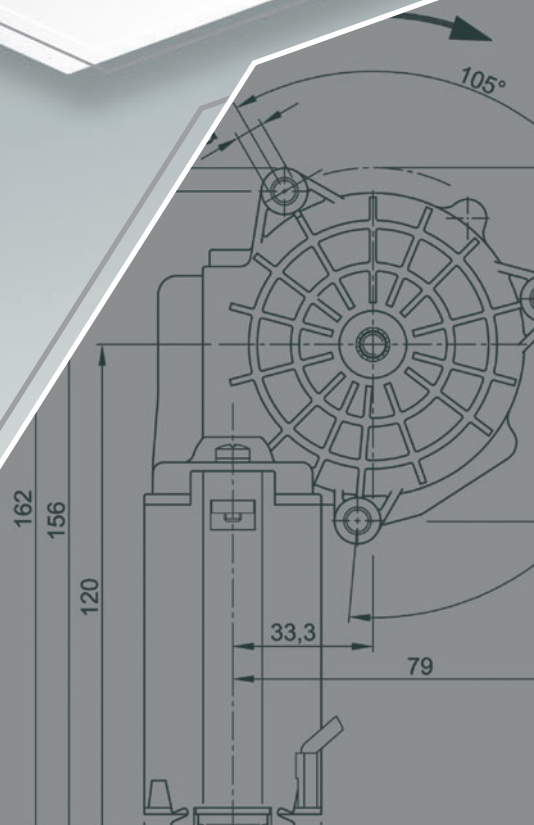


❖❖❖ TECHNICAL DESCRIPTION

Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	zinc die cast
Gear wheel material:	plastic or resinbonded fabric
Lubrication:	grease
Mechanical interface:	output shaft
Electric interface:	connector or leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

❖❖❖ APPLICATION

General machine construction, Automatic machines,
Agricultural technology, Business machines,
Laboratory appliances, Medical appliances,
Traffic & communications technology,
Photographic/optical equipment

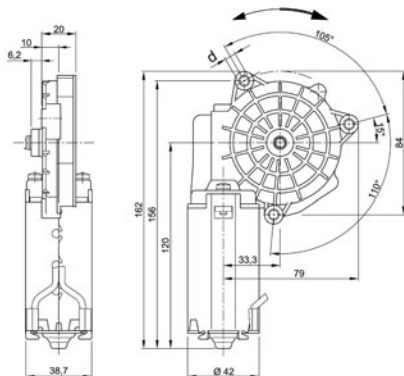


Series SWMP

Motor type 403 194

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	50.0
Nominal power [W]	P_N	8.73
Nominal current [A]	I_N	1.5
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

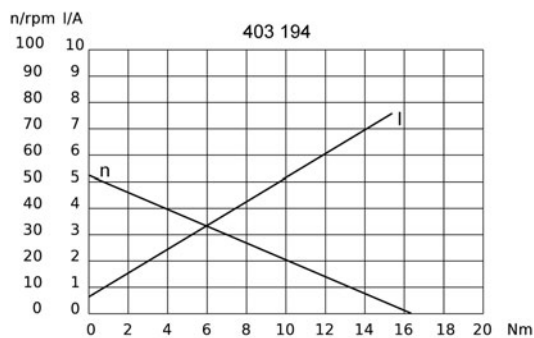
Pulses	0
Output channels	0

Other data

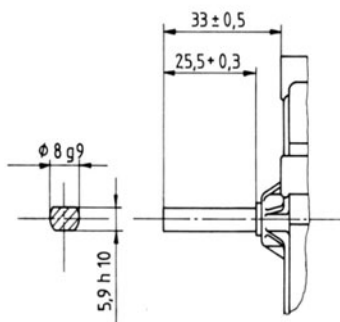
Gear ratio	85/1
Gear wheel material	Resinbonded fabric
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = M6

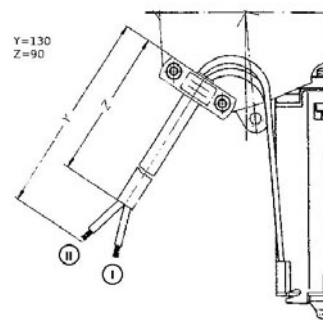
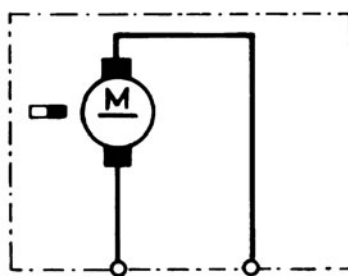
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 28



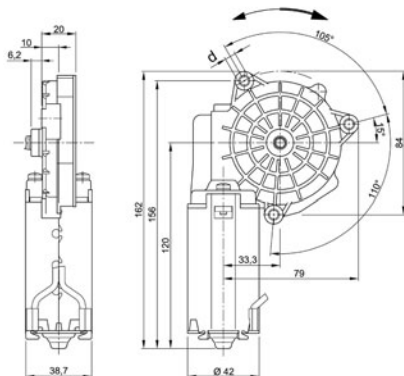
I: green
 II: black

Series SWMP

Motor type 403 279

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	54.0
Nominal power [W]	P_N	9.94
Nominal current [A]	I_N	1.5
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

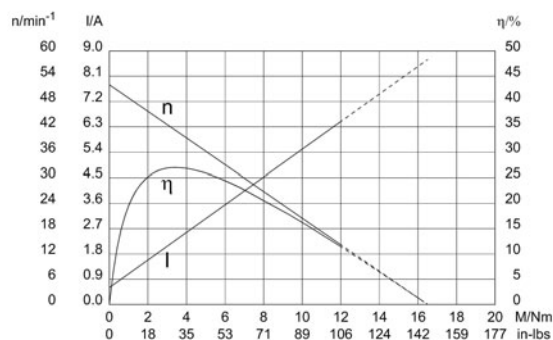
Pulses	0
Output channels	0

Other data

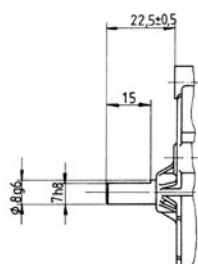
Gear ratio	85/1
Gear wheel material	Plastic
Suppression components	7.5 μ H, 47nF
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = 7.5mm, Ball bearing

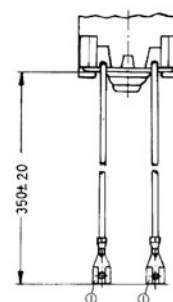
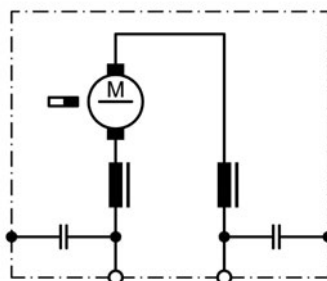
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30



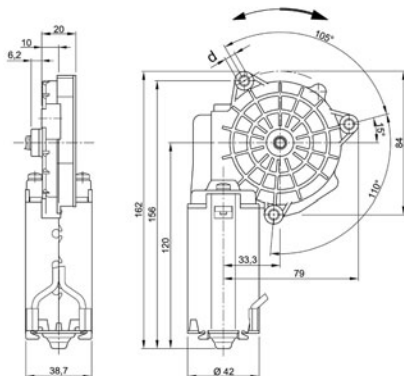
Spade connector 4.8 DIN 46 247

Series SWMP

Motor type 403 280

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	52.0
Nominal power [W]	P_N	9.57
Nominal current [A]	I_N	0.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

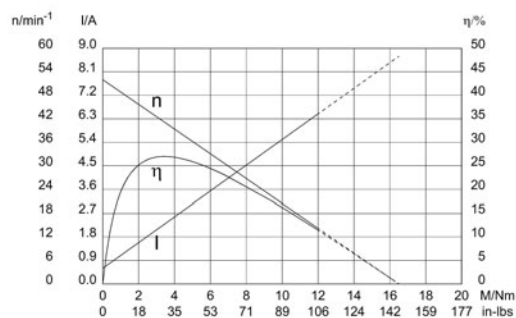
Pulses	0
Output channels	0

Other data

Gear ratio	85/1
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = 7.5mm, Ball bearing

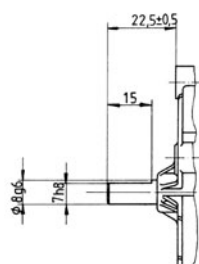
Characteristic curves



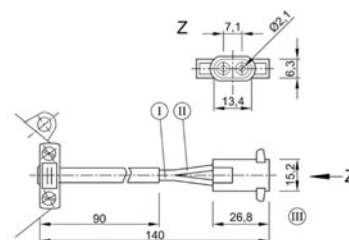
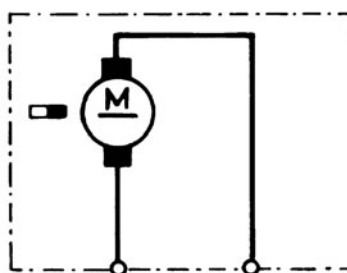
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

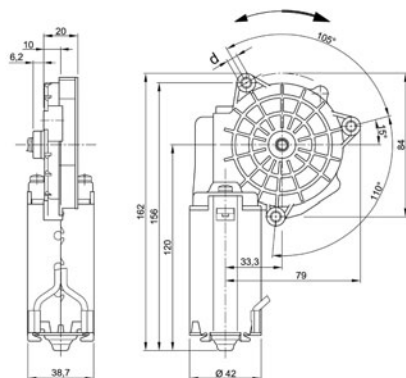


S 28



Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	52.0
Nominal power [W]	P_N	9.34
Nominal current [A]	I_N	1.5
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

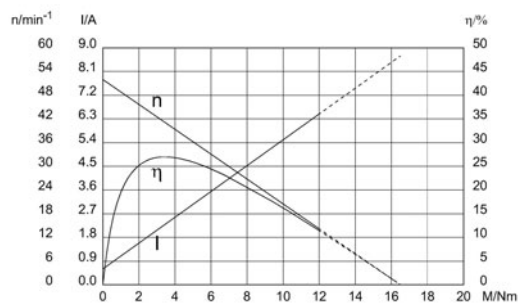
Pulses	0
Output channels	0

Other data

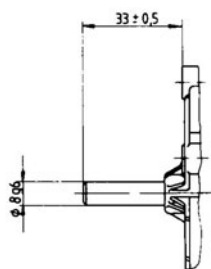
Gear ratio	85/1
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = M6, Ball bearing

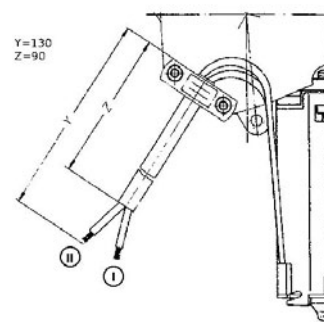
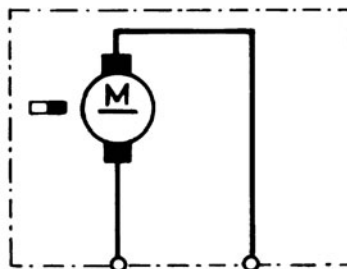
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 28



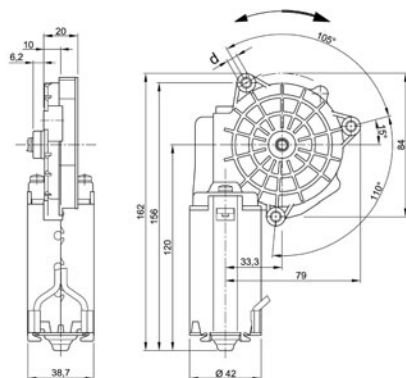
I: green
 II: black

Series SWMP

Motor type 403 290

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	52.0
Nominal power [W]	P_N	9.34
Nominal current [A]	I_N	1.5
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

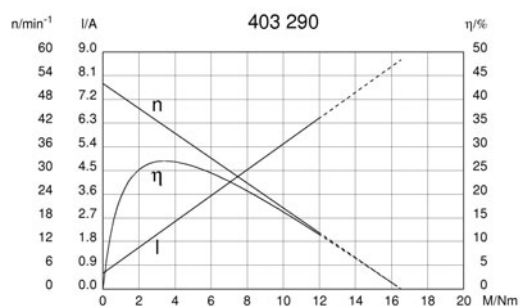
Pulses	0
Output channels	0

Other data

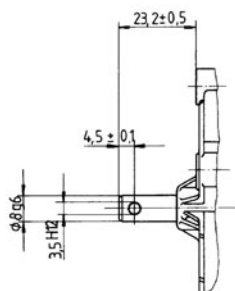
Gear ratio	85/1
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = M6, Ball bearing

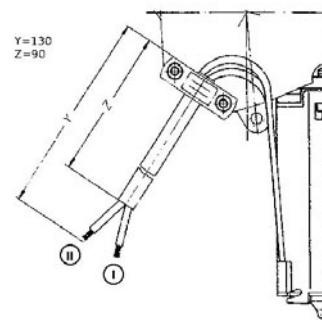
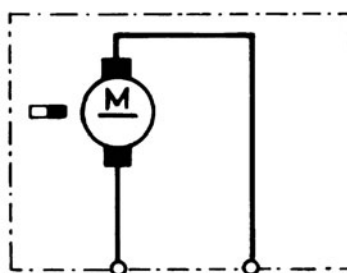
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 28



I: green
 II: black

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	1.30
No-load speed [min^{-1}]	n_0	110.0
Nominal power [W]	P_N	12.2
Nominal current [A]	I_N	2.6
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

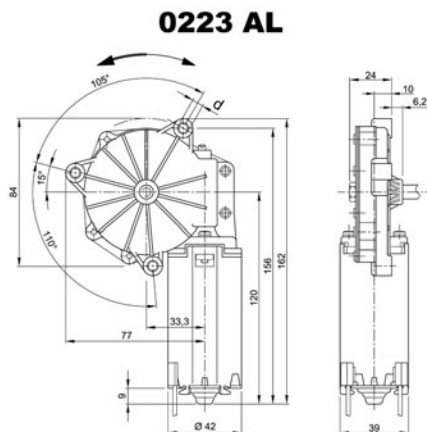
Pulses	0
Output channels	0

Other data

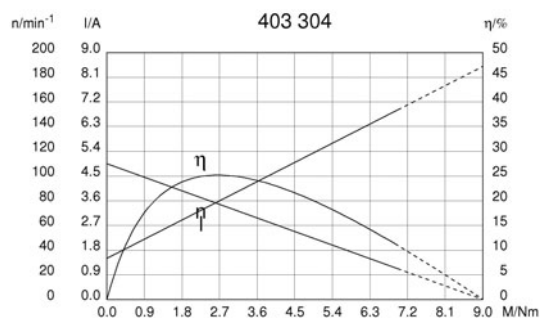
Gear ratio	83/2
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = M6, Ball bearing

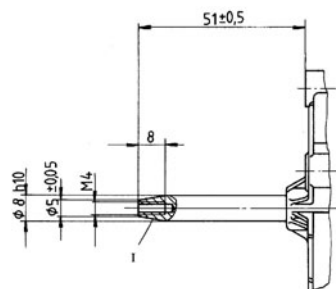
Characteristic curves



Motor picture

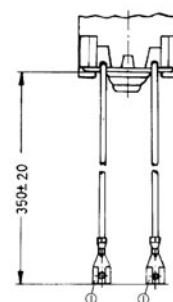
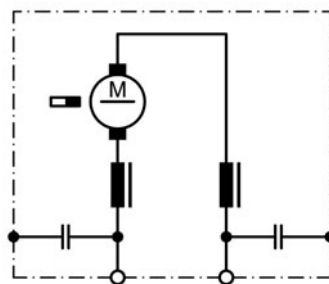


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



I: Cone 1:4

S 30



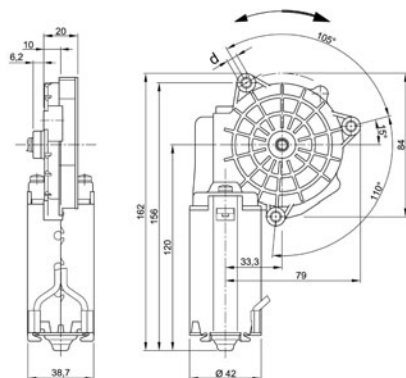
Spade connector 4.8 DIN 46 247

Series SWMP

Motor type 403 712

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	1.30
No-load speed [min^{-1}]	n_0	100.0
Nominal power [W]	P_N	11.1
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

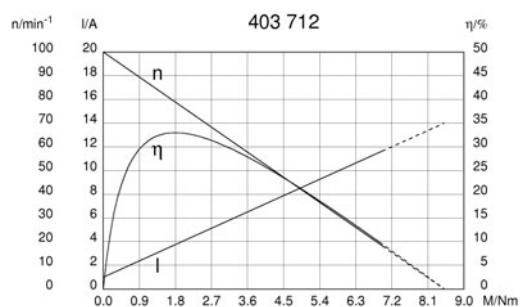
Pulses	0
Output channels	0

Other data

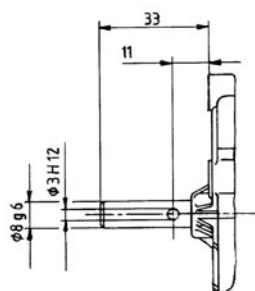
Gear ratio	83/2
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = M6, Ball bearing

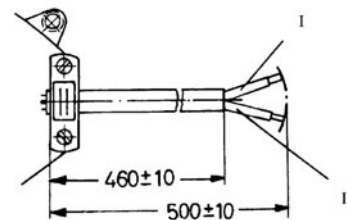
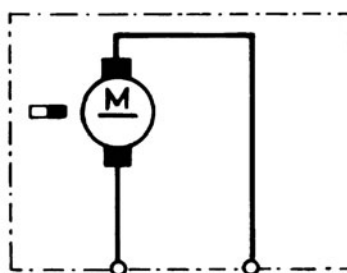
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 28



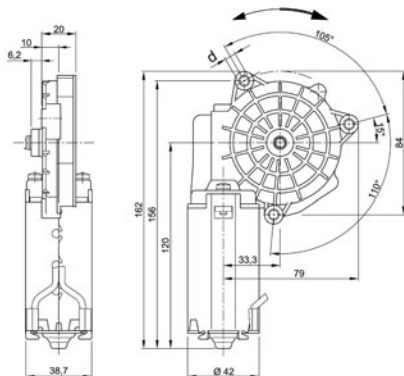
I: black
 II: green

Series SWMP

Motor type 404 003

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	50.0
Nominal power [W]	P_N	8.98
Nominal current [A]	I_N	2.5
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

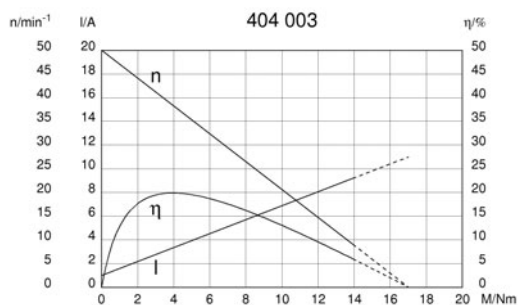
Pulses	0
Output channels	0

Other data

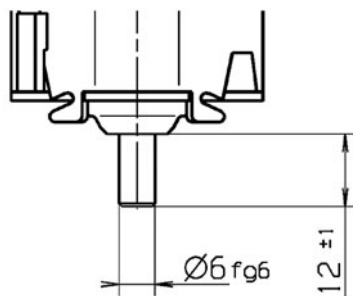
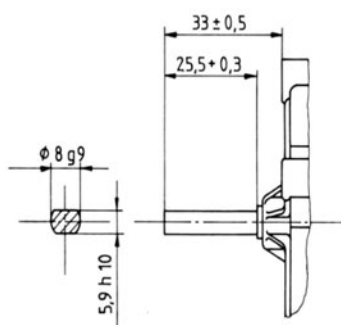
Gear ratio	99/1
Gear wheel material	Resinbonded fabric
Suppression components	
Enclosure class	
Weight [kg]	0.710

Remarks: d = M6, Ball bearing

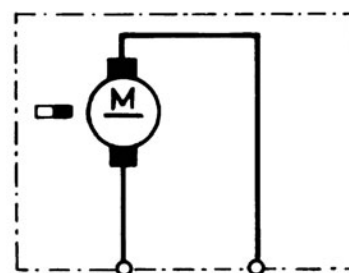
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 28

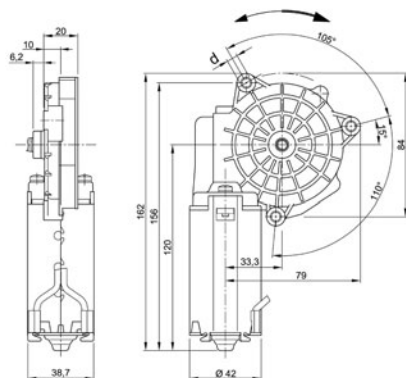


Series SWMP

Motor type 404 127

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

**Performance data**

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	50.0
Nominal power [W]	P_N	8.38
Nominal current [A]	I_N	2.3
Nominal force [kN]	F_N	0.00
Duty cycle		s1

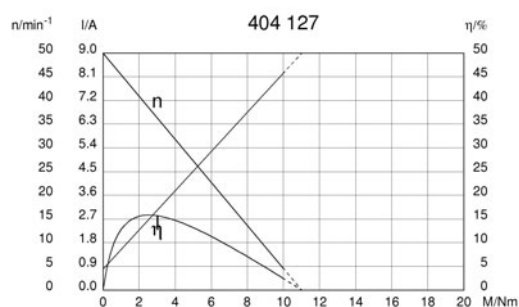
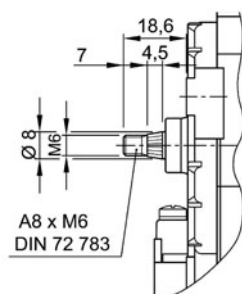
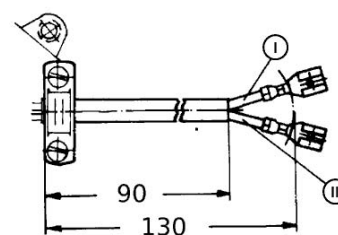
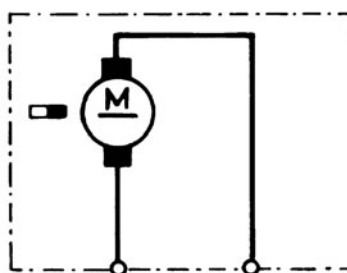
Sensor data

Pulses	0
Output channels	0

Other data

Gear ratio	85/1
Gear wheel material	Resinbonded fabric
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = M6, Ball bearing

Motor picture**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)****S 28**

Spade connector 6.3 x 0.8 DIN 46 244

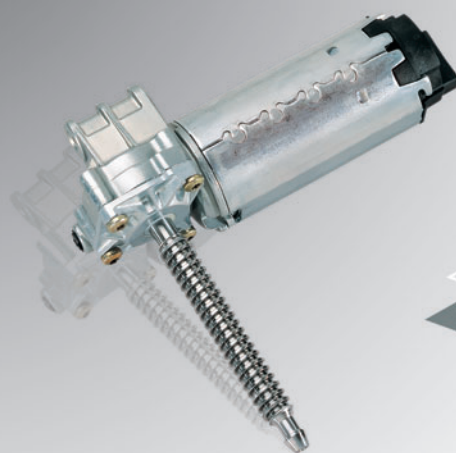
I: black
II: green

Notes

This image shows a single sheet of white paper with horizontal blue or grey ruling lines. The lines are evenly spaced and run across the width of the page. There are approximately 20 lines visible. The paper appears to be a standard notebook page or a sheet of stationery.

0321 (GMPS)

DC MOTORS WITH WORM GEAR



TECHNICAL DESCRIPTION

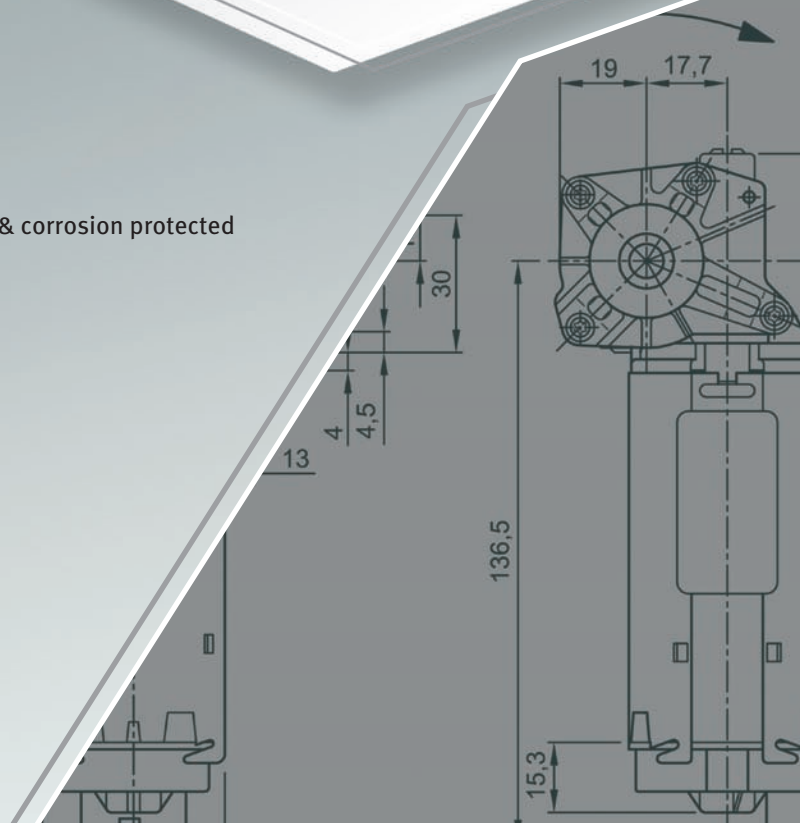
Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	zinc die cast
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	steel lead screw
Electric interface:	connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

INDUSTRIAL APPLICATION

Home automation

AUTOMOTIVE APPLICATION

Seat tilt and height adjustment



Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	1.50
No-load speed [min^{-1}]	n_0	180.0
Nominal power [W]	P_N	21.3
Nominal current [A]	I_N	9.0
Nominal force [kN]	F_N	2.00
Duty cycle		s3

Sensor data

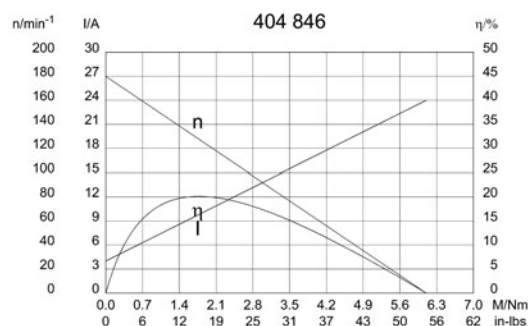
Pulses	29
Output channels	1

Other data

Gear ratio	29/1
Gear wheel material	plastic
Suppression components	5,5 μ H, 47nF, (0,47 μ F)
Enclosure class	IP 40
Weight [kg]	0.880

Remarks: L = 116mm, 1 start worm

Characteristic curves

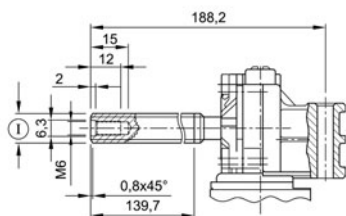


Motor picture



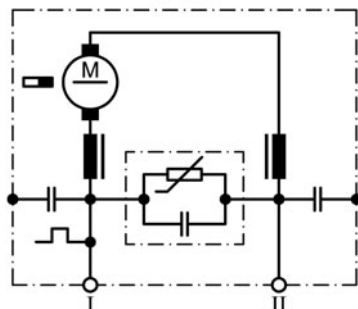
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 288



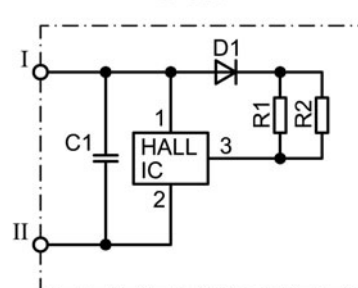
shape 7/16-8 STUB ACME RH, pressure angle 20°, pitch 3,175mm (0,125"), no of starts 1

S 93



I Terminal 1
 II Terminal 5

S 85



I Terminal 4, Hall-IC +
 II Terminal 2, Hall-IC -

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	1.50
No-load speed [min^{-1}]	n_0	180.0
Nominal power [W]	P_N	21.3
Nominal current [A]	I_N	6.0
Nominal force [kN]	F_N	2.00
Duty cycle		s3

Sensor data

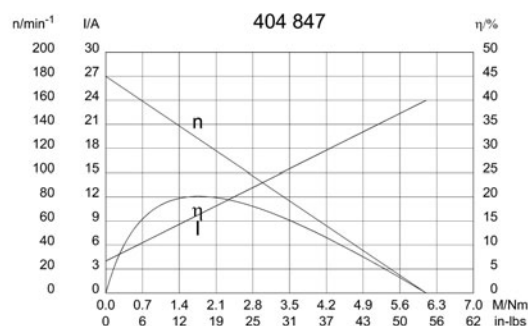
Pulses	29
Output channels	1

Other data

Gear ratio	29/1
Gear wheel material	plastic
Suppression components	5,5 μ H, 47nF, (0,47 μ F)
Enclosure class	IP 40
Weight [kg]	0.880

Remarks: L = 116mm, 1 start worm

Characteristic curves

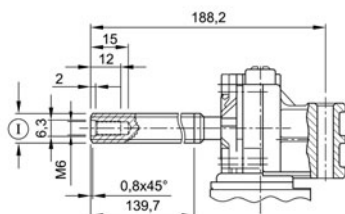


Motor picture



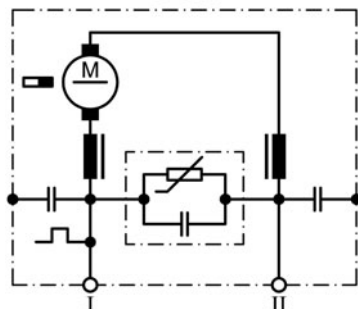
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 288



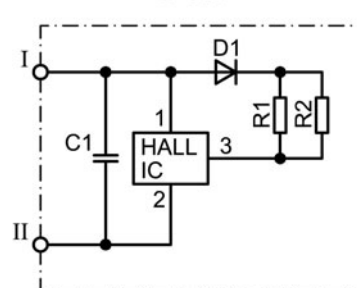
shape 7/16-8 STUB ACME RH, pressure angle 20°, pitch 3,175mm (0,125"), no of starts 1

S 93



I Terminal 1
 II Terminal 5

S 85

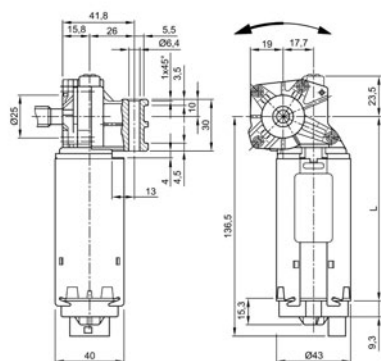


I Terminal 4, Hall-IC +
 II Terminal 2, Hall-IC -

Design Data

Commutation	none
Direction of rotation	Bi-directional
Bearing type	A: Sleeve - B: Sleeve

0321 BL



Motor picture



Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	1.50
No-load speed [min^{-1}]	n_0	145.0
Nominal power [W]	P_N	16.6
Nominal current [A]	I_N	6.0
Nominal force [kN]	F_N	1.50
Duty cycle		s3

Sensor data

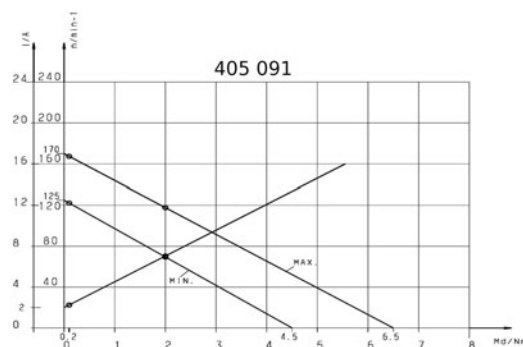
Pulses	29
Output channels	1

Other data

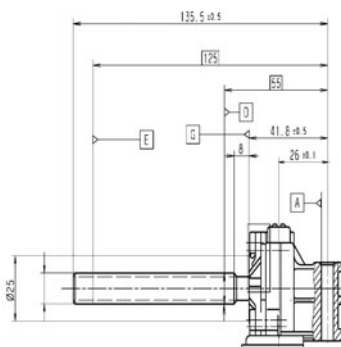
Gear ratio	29/1
Gear wheel material	
Suppression components	5,5 μ H, 47nF, (0,47 μ F)
Enclosure class	IP40
Weight [kg]	0.880

Remarks: 1 start worm

Characteristic curves

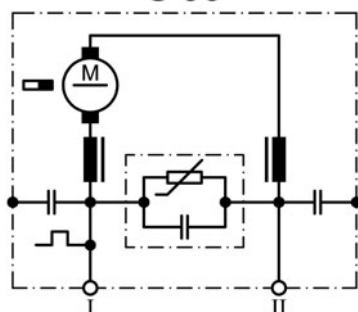


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



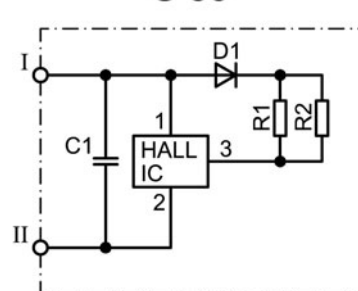
Output spindle: 7 / 16 Stub ACME RH

S 93



I Terminal 1
 II Terminal 5

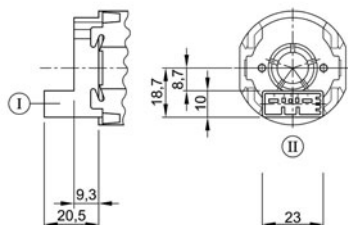
S 85



I Terminal 4, Hall-IC +
 II Terminal 2, Hall-IC -

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

K 220



Connector TYCO C-208-15621 (Z) mating with:
Connector housing 1379217-3 & cover
 1379218-2
www.tycoelectronics.com

Notes

[illegible]

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Sleeve - B: Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	1.50
No-load speed [min^{-1}]	n_0	145.0
Nominal power [W]	P_N	16.6
Nominal current [A]	I_N	6.0
Nominal force [kN]	F_N	1.50
Duty cycle		s3

Sensor data

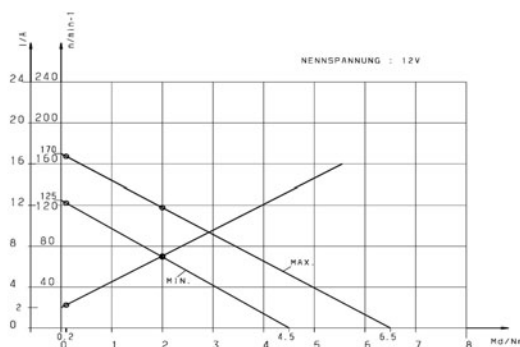
Pulses	0
Output channels	0

Other data

Gear ratio	29/1
Gear wheel material	
Suppression components	5,5 μ H, 47nF, (0,47 μ F)
Enclosure class	IP40
Weight [kg]	0.880

Remarks: 1 start worm

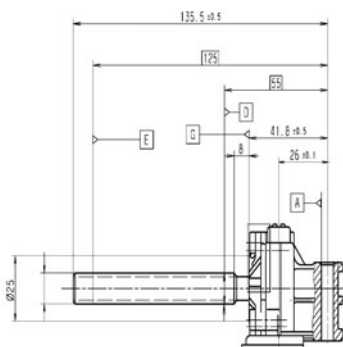
Characteristic curves



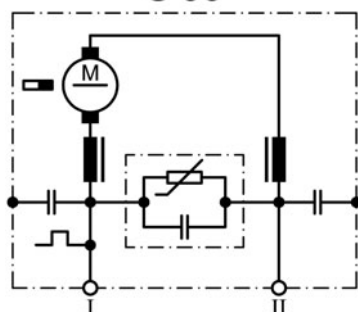
Motor picture



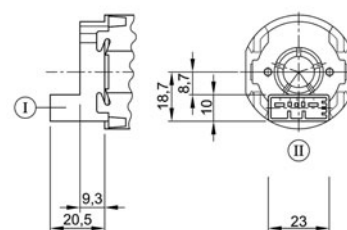
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 93



K 220



Output spindle: 7 / 16 Stub ACME RH

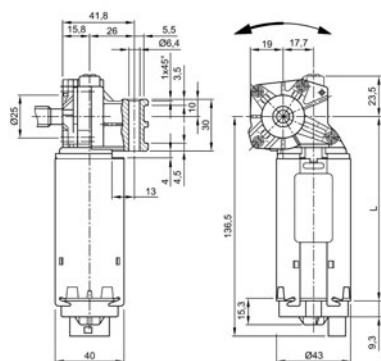
I Terminal 1
 II Terminal 5

Connector TYCO C-208-15621 (Z) mating with:
 Connector housing 1379217-3 & cover
 1379218-2
www.tycoelectronics.com

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Sleeve - B: Sleeve

0321 BL



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	1.50
No-load speed [min^{-1}]	n_0	145.0
Nominal power [W]	P_N	17.2
Nominal current [A]	I_N	4.5
Nominal force [kN]	F_N	1.50
Duty cycle		s3

Sensor data

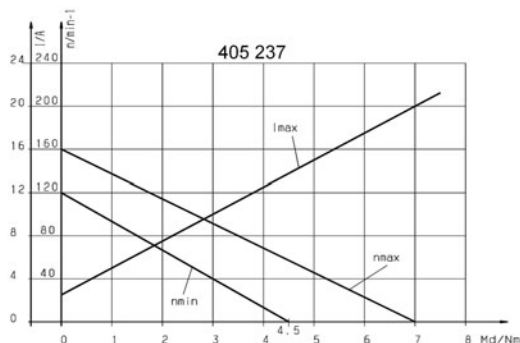
Pulses	0
Output channels	0

Other data

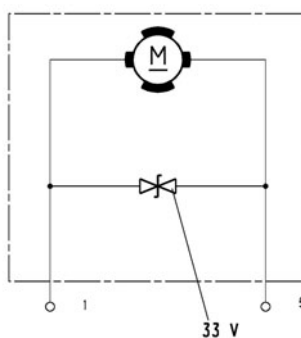
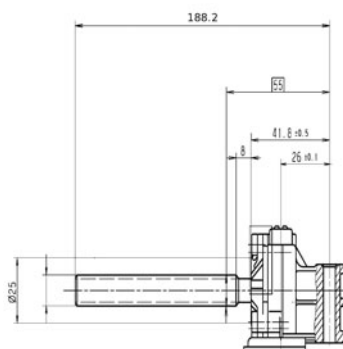
Gear ratio	29/1
Gear wheel material	
Suppression components	
Enclosure class	IP40
Weight [kg]	0.880

Remarks: L = 116mm

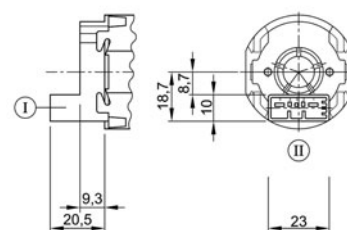
Characteristic curves



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



K 220



Output spindle: 7 / 16 Stub ACME RH

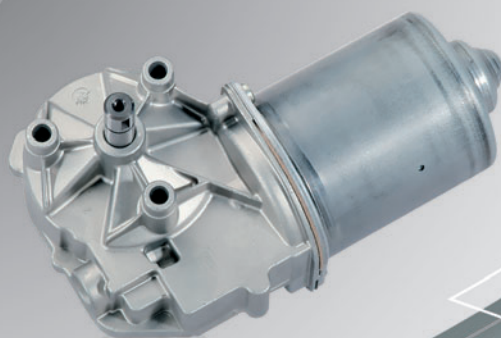
Connector TYCO C-208-15621 (Z) mating with:
 Connector housing 1379217-3 & cover
 1379218-2
www.tycoelectronics.com

Notes

[illegible]

0266 (DCK31)

⇨ DC MOTORS WITH WORM GEAR



⇨ TECHNICAL DESCRIPTION

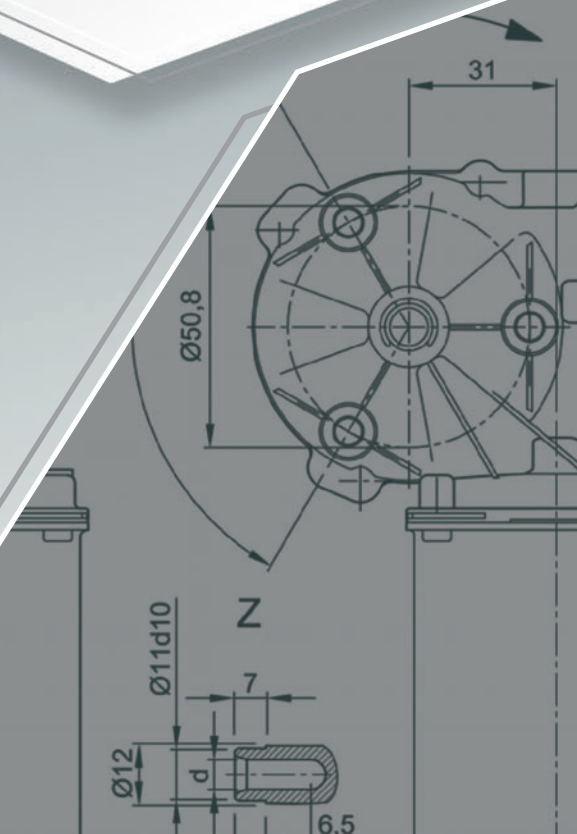
Motorhousing:	deep drawn & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	zinc die cast
Gear wheel material:	plastic, steel
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	connector or leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

⇨ INDUSTRIAL APPLICATION

Door & gate openers, pumps,
lubricating technology, appliance, linear actuators

⇨ AUTOMOTIVE APPLICATION

Trunk & tailgate opening & closing



Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:ball - B:sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	65.0
Nominal power [W]	P_N	25.0
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

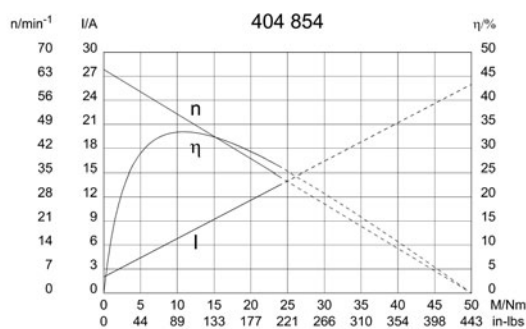
Pulses	69
Output channels	1

Other data

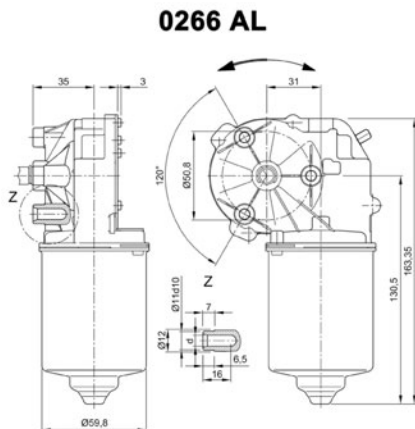
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	6 μH
Enclosure class	IP 30
Weight [kg]	1.250

Remarks: d=for selftapping screw M6 DIN ISO 965-2

Characteristic curves

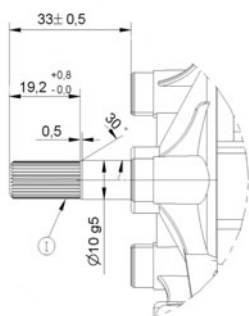


Motor picture

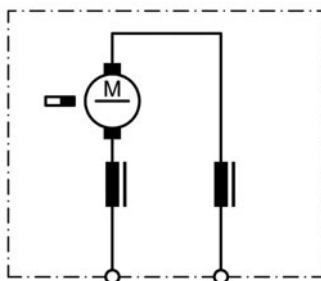


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

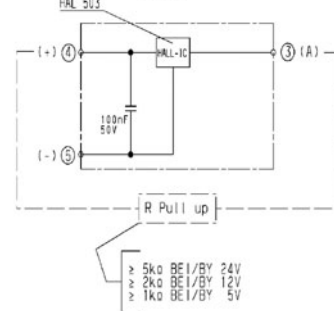
W330



S 27



S150

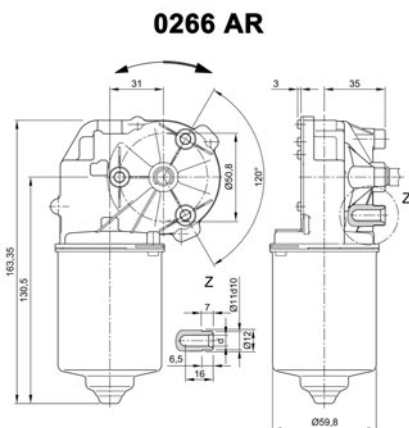


I serration (rolled): no of teeth 28, pitch circle
 dia 9 mm, tip circle dia 9.6 mm, root circle
 dia 8.26 mm space width angle 60° - go/no go
 gauge Frenco 33906 - www.frenco.de

Series DCK31
Motor type 404 864

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: ball - B: sleeve



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	66.0
Nominal power [W]	P_N	25.4
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

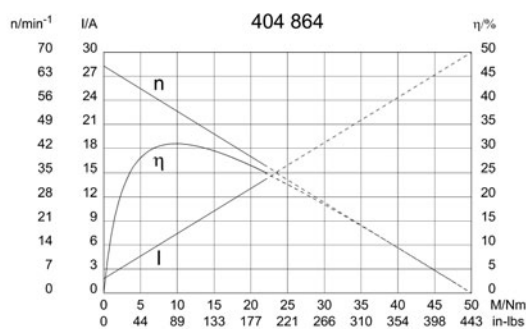
Pulses	0
Output channels	0

Other data

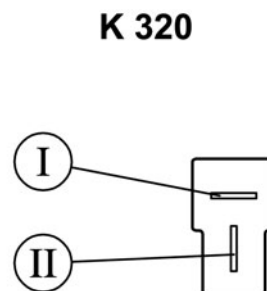
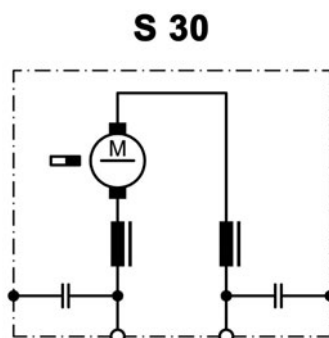
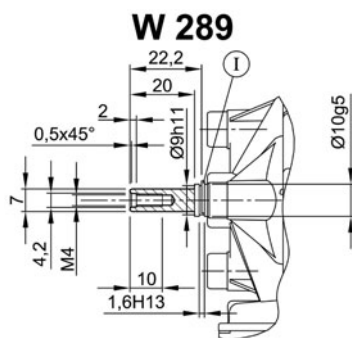
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	3,5μH, 1μF
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

Characteristic curves



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



I Circlip

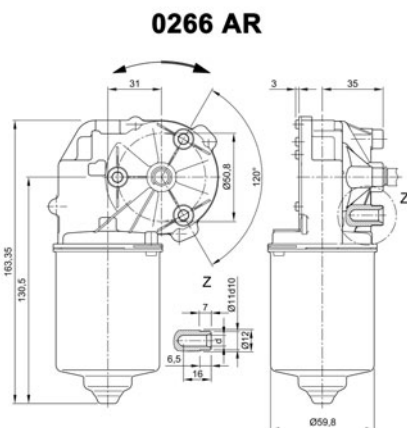
Flat plug (DIN 46244) 6,3x0,8 mating with
receptacle housing part#180907, drwg#
C-180907& Receptacles for tabs, conductor cross
section 0,5-1,5 sqmm (20-18AWG) part# 925603-
x, drwg# 925603 www.tycoelectronics.com

Series DCK31

Motor type 404 865

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	75.0
Nominal power [W]	P_N	28.9
Nominal current [A]	I_N	5.5
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

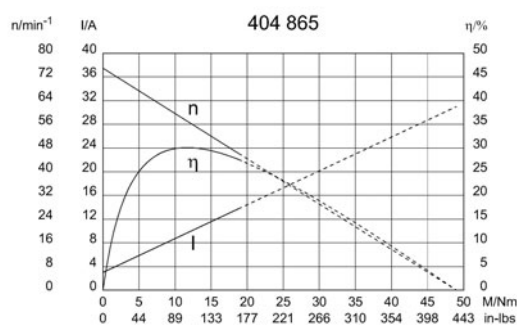
Pulses	69
Output channels	2

Other data

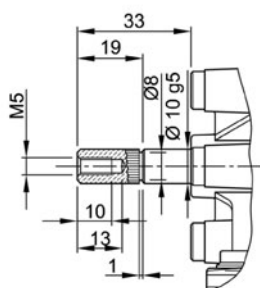
Gear ratio	69/1
Gear wheel material	Plastic
Suppression components	6.0 μ H, 1nF
Enclosure class	IP30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

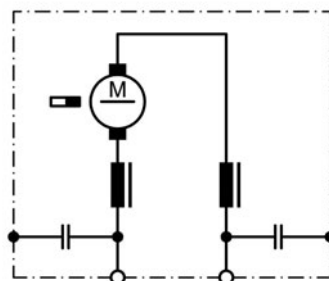
Characteristic curves



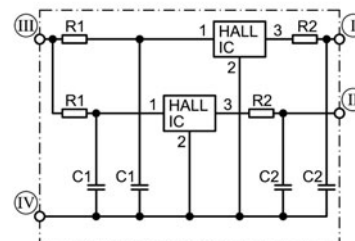
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30



S 141

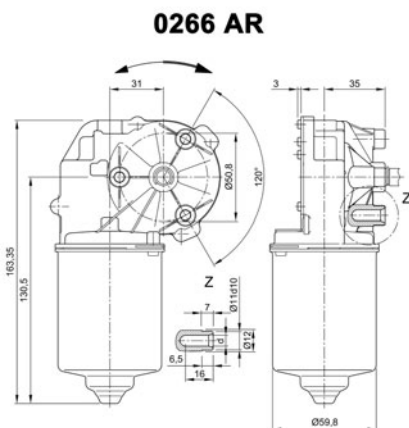


- I Hall-IC A1, terminal 3
- II Hall-IC A2, terminal 4
- III Hall-IC +, terminal 5
- IV Hall-IC -, terminal 6

Series DCK31
Motor type 404 866

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:ball - B:sleeve



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	64.0
Nominal power [W]	P_N	24.4
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

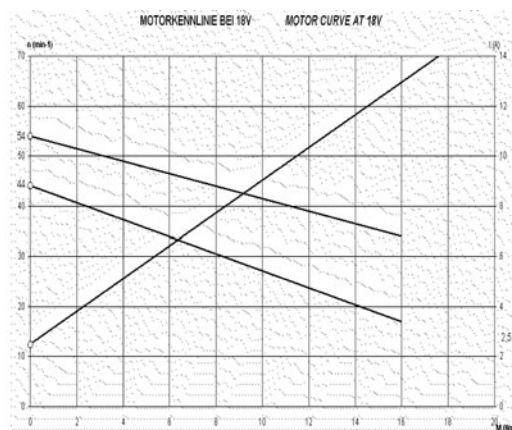
Pulses	0
Output channels	0

Other data

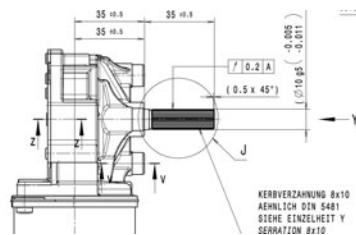
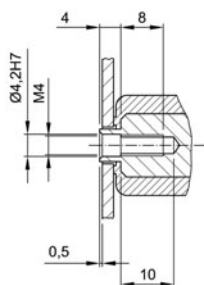
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	6μH, 1nF
Enclosure class	IP 30
Weight [kg]	1.216

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

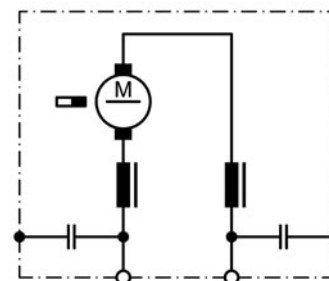
Characteristic curves



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 222

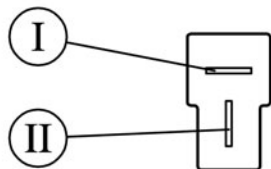
S 30



! Only for connection of encoder

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

K 320



Flat plug (DIN 46244) 6,3x0,8 mating with
receptacle housing part#180907, drwg#
C-180907& Receptacles for tabs, conductor cross
section 0,5-1,5 sqmm (20-18AWG) part# 925603-
x, drwg# 925603 www.tycoelectronics.com

Notes

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: ball - B: sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	6.00
No-load speed [min^{-1}]	n_0	35.0
Nominal power [W]	P_N	19.2
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

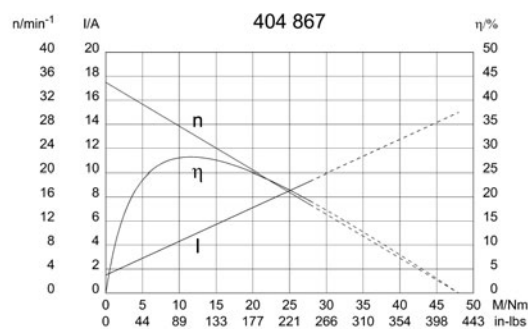
Pulses	0
Output channels	0

Other data

Gear ratio	69/1
Gear wheel material	plastic
Suppression components	6 μ H, 1nF
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

Characteristic curves

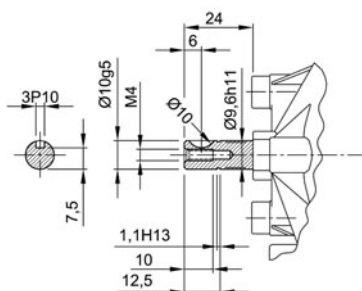


Motor picture

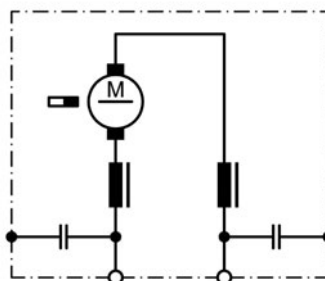


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

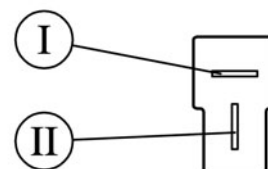
W 304



S 30



K 320



Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 www.tycoelectronics.com

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:ball - B:sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	21.0
Nominal power [W]	P_N	7.79
Nominal current [A]	I_N	2.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

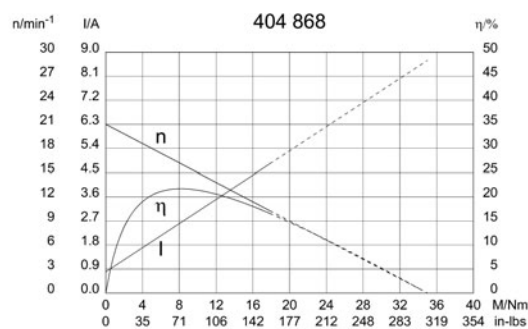
Pulses	0
Output channels	0

Other data

Gear ratio	69/1
Gear wheel material	plastic
Suppression components	3,5 μ H, 1 μ F
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

Characteristic curves

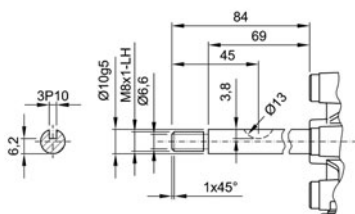


Motor picture

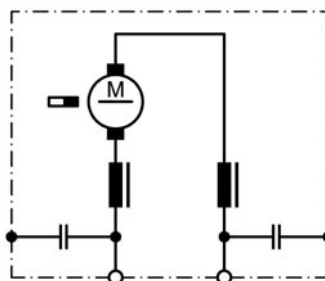


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

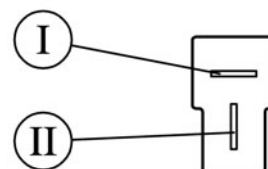
W 120



S 30



K 320



Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 www.lycoelectronics.com

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	30.0
Nominal power [W]	P_N	10.8
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

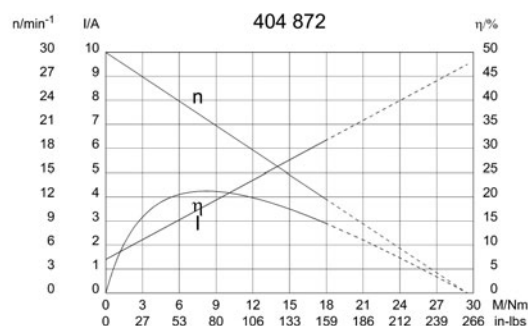
Pulses	0
Output channels	0

Other data

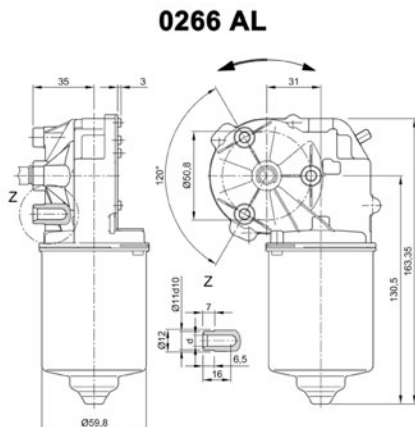
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	6 μ H
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

Characteristic curves

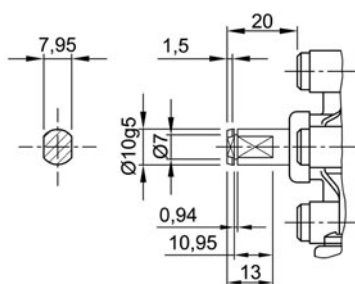


Motor picture

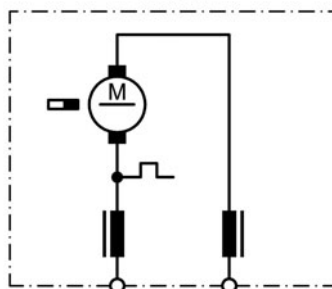


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

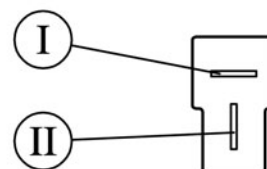
W 252



S 25



K 320



Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 www.tycoelectronics.com

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	160.0
Nominal power [W]	P_N	30.9
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

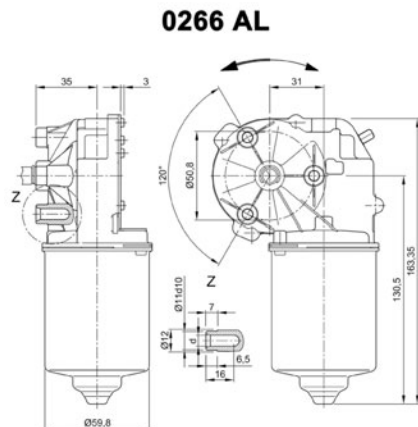
Pulses	1
Output channels	2

Other data

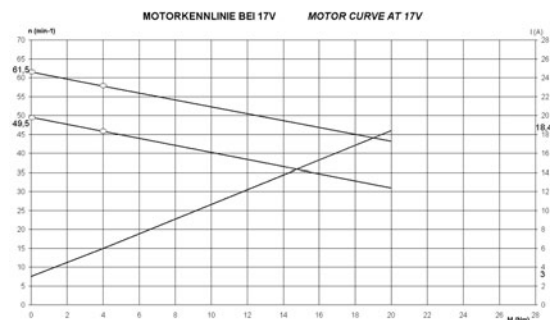
Gear ratio	53/2
Gear wheel material	plastic
Suppression components	$6\mu\text{H}$, 1nF
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d= for thread forming screw M6 DIN ISO 965-2

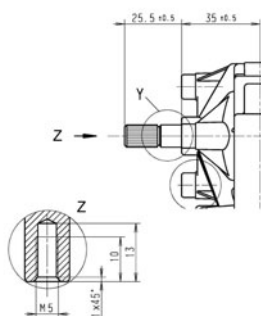
Characteristic curves



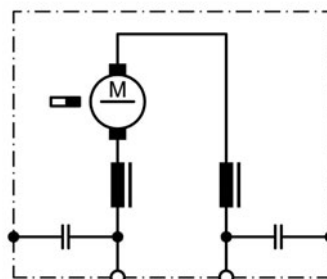
Motor picture



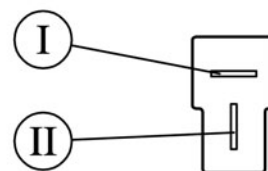
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30



K 320



I serration (rolled): **No teeth 28, pitch circle dia 9 mm, tip circle dia 9.6 mm, root circle dia 8.26 mm space width angle 60° - go/no go gauge** Frenco 33906 - www.frenco.de

Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 www.lycoelectronics.com

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	3.00
No-load speed [min^{-1}]	n_0	14.0
Nominal power [W]	P_N	3.60
Nominal current [A]	I_N	1.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

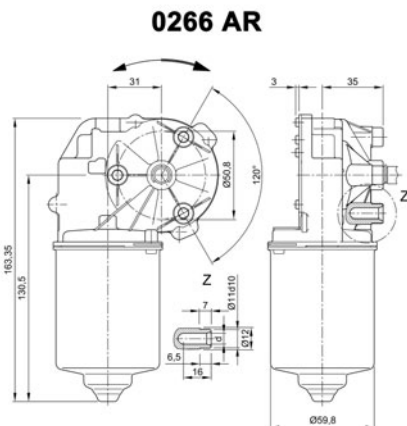
Pulses	234
Output channels	1

Other data

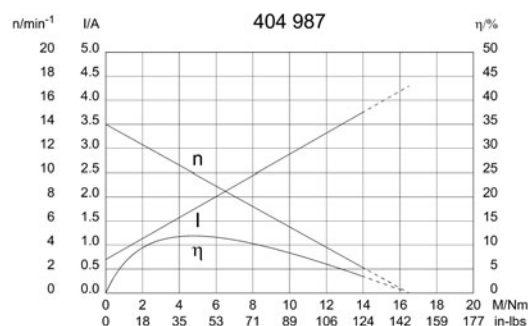
Gear ratio	78/1
Gear wheel material	bronze
Suppression components	$6\mu\text{H}, 1\text{nF}$
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

Characteristic curves

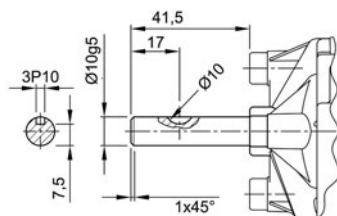


Motor picture

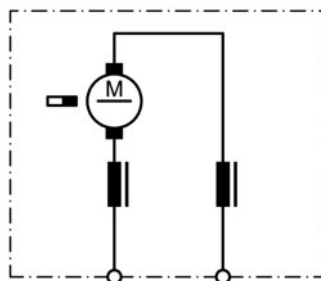


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

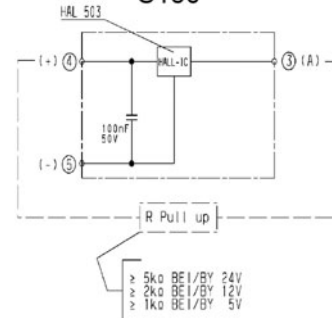
W 327



S 27

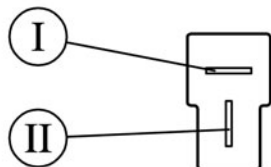


S150



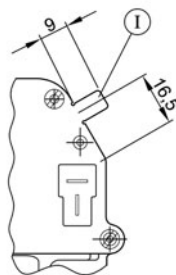
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

K 320



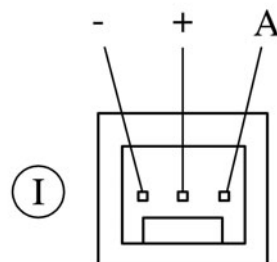
Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 www.tycoelectronics.com

K 321



I Ground connection
Blade terminal 6.3 x 0.8 DIN 46 244

K 326



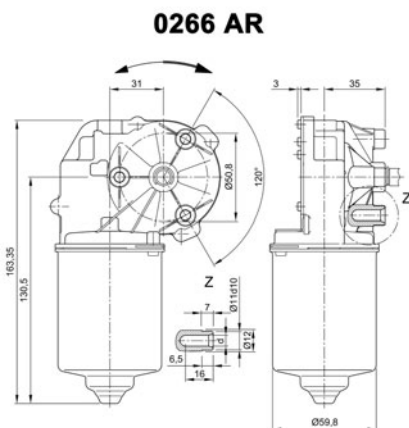
MAS-CON solder tail MLAS 100-3435 mating with
end connector CE 100F-22-xx-x-x or CEP
100F-22-xx-x-x

Notes

Series DCK31
Motor type 404 988

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: ball - B: sleeve



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	36.0
Nominal power [W]	P_N	12.9
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

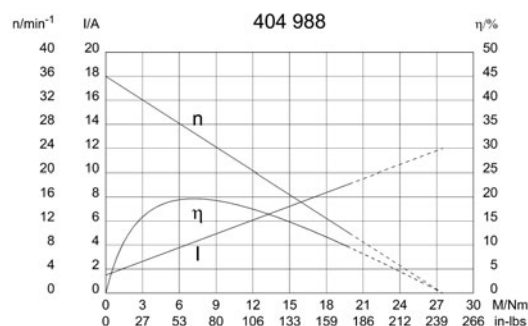
Pulses	207
Output channels	1

Other data

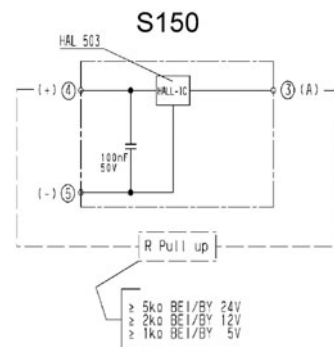
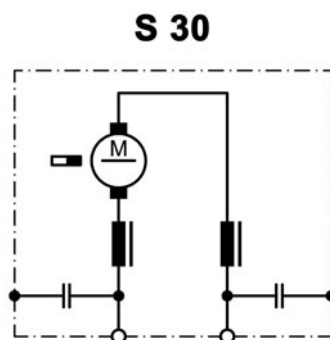
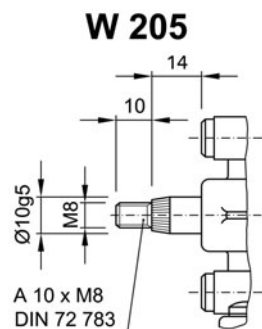
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	6μH, 1nF
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

Characteristic curves



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	3.00
No-load speed [min^{-1}]	n_0	195.0
Nominal power [W]	P_N	52.5
Nominal current [A]	I_N	5.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

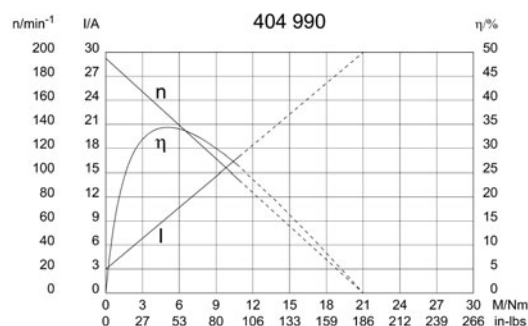
Pulses	207
Output channels	1

Other data

Gear ratio	53/2
Gear wheel material	plastic
Suppression components	6 μ H, 1nF
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

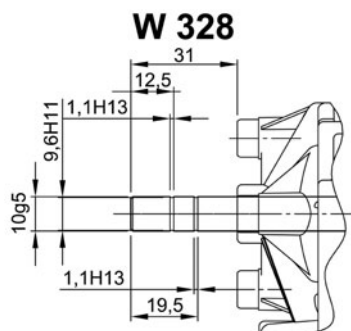
Characteristic curves



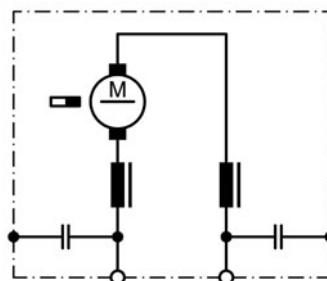
Motor picture



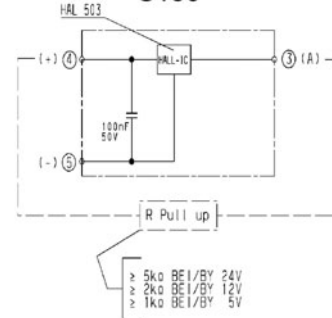
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30



S150



Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball- B:Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	1.00
No-load speed [min^{-1}]	n_0	270.0
Nominal power [W]	P_N	24.5
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

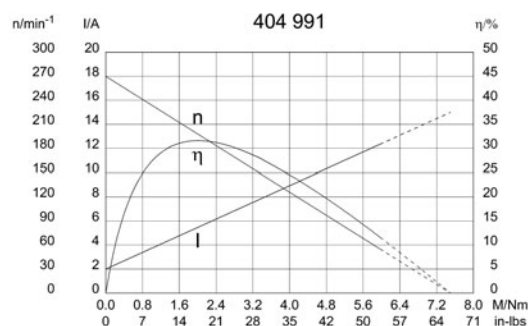
Pulses	10.25
Output channels	1

Other data

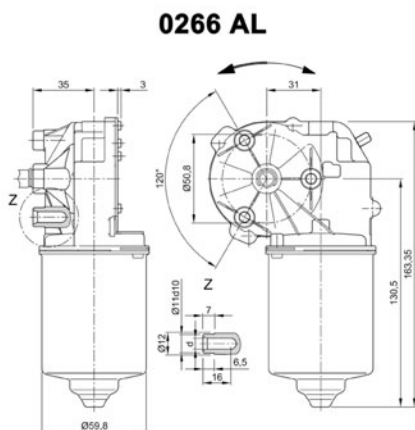
Gear ratio	41/4
Gear wheel material	plastic
Suppression components	$6\mu\text{H}$, 1nF
Enclosure class	IP 30
Weight [kg]	1.250

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

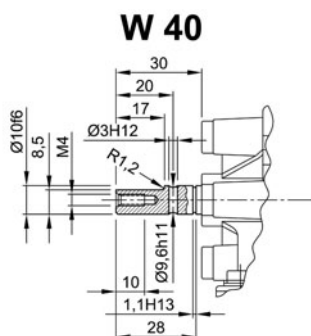
Characteristic curves



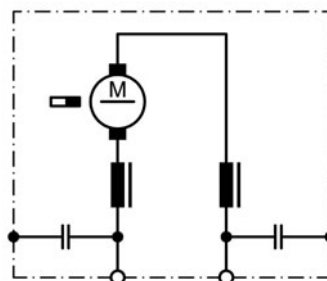
Motor picture



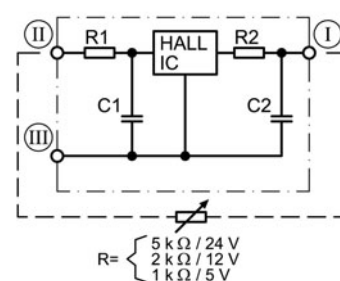
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30



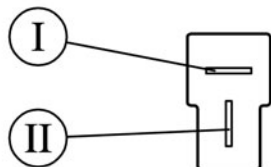
S 124



- I Terminal 3, A
- II Terminal 4, +
- III Terminal 5, -

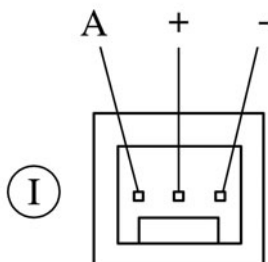
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

K 320



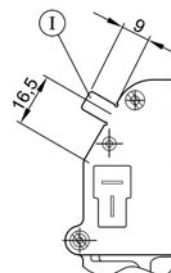
Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 www.tycoelectronics.com

K 325



MAS-CON Solder tail MLAS 100-3435 mating
with end connector CE100F-22-xx-x-x or CEP100
F-22-xx-x-x
www.itwpancon.com

K 312



Ground connection 6.3 x 0.8 DIN 46 244,
d=0.9-0.1mm, mating with receptacle for tab,
conductor cross section 0.5-1.5 sqmm/20-16
AWG, part# RSB8240.158 F 6.3-1.5
www.stocko.de

Notes

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	21.0
Nominal power [W]	P_N	7.79
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

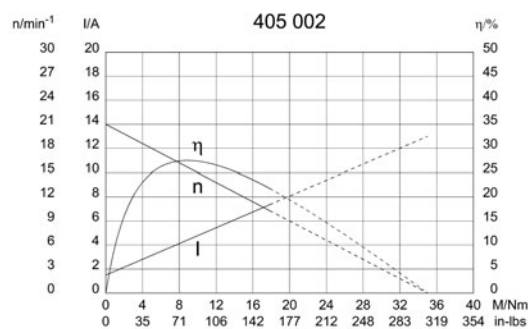
Pulses	0
Output channels	0

Other data

Gear ratio	69/1
Gear wheel material	plastic
Suppression components	3,5 μ H, 1 μ F
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

Characteristic curves

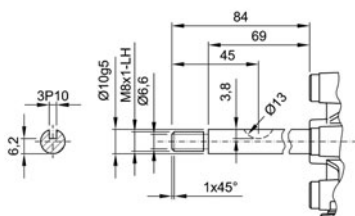


Motor picture

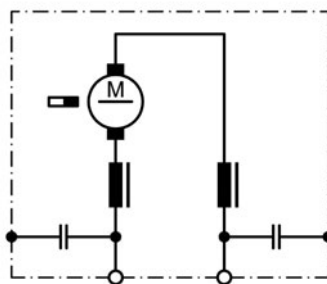


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

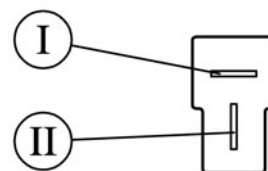
W 120



S 30



K 320



Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 www.lycoelectronics.com

Series DCK31

Motor type 405 006

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	65.0
Nominal power [W]	P_N	25.0
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

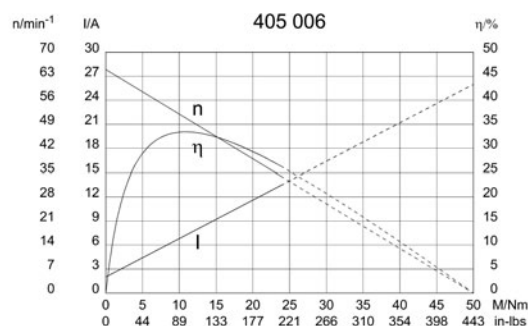
Pulses	69
Output channels	2

Other data

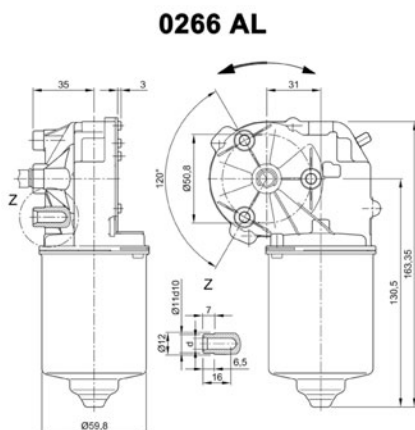
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	6 μ H
Enclosure class	IP 30
Weight [kg]	1.250

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

Characteristic curves

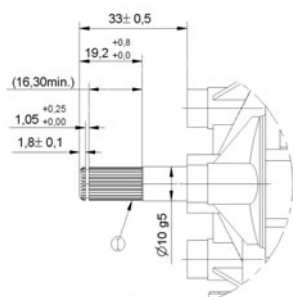


Motor picture

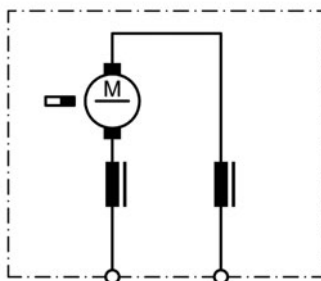


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

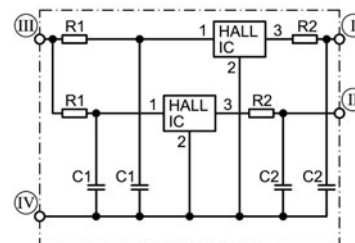
W334



S 27



S 141



I serration (rolled): no of teeth 28, pitch circle
 dia 9 mm, tip circle dia 9.6 mm, root circle
 dia 8.26 mm space width angle 60° - go/no go
 gauge Frenco 33906 - www.frenco.de

I Hall-IC A1, terminal 3
 II Hall-IC A2, terminal 4
 III Hall-IC +, terminal 5
 IV Hall-IC -, terminal 6

Series DCK31

Motor type 405 054

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	195.0
Nominal power [W]	P_N	59.9
Nominal current [A]	I_N	8.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

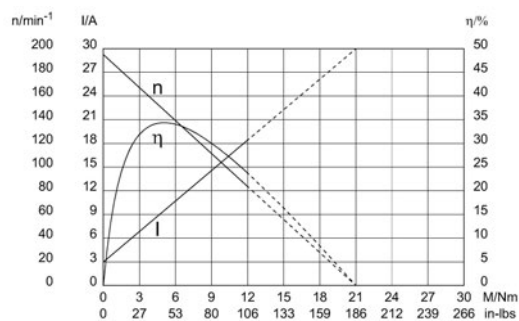
Pulses	26.5
Output channels	2

Other data

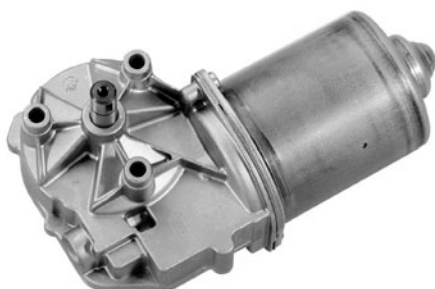
Gear ratio	53/2
Gear wheel material	Plastic
Suppression components	6.0 μ H, 1nF
Enclosure class	IP30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

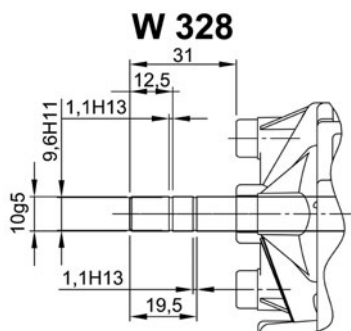
Characteristic curves



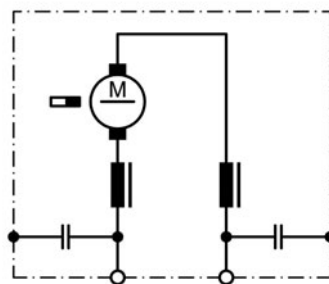
Motor picture



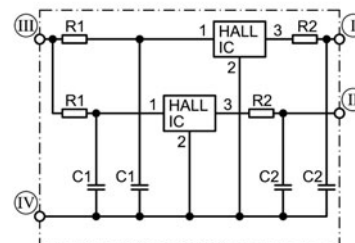
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30



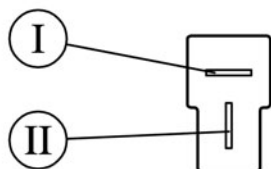
S 141



- I Hall-IC A1, terminal 3
- II Hall-IC A2, terminal 4
- III Hall-IC +, terminal 5
- IV Hall-IC -, terminal 6

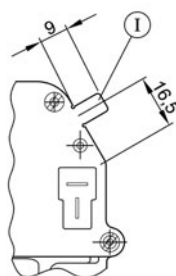
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

K 320

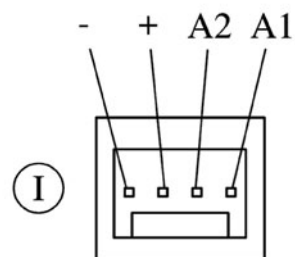


Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 www.tycoelectronics.com

K 321



I Ground connection
Blade terminal 6.3 x 0.8 DIN 46 244



I Mating connector: Panduit CE100 F22-04

Notes

[illegible]

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	55.0
Nominal power [W]	P_N	21.5
Nominal current [A]	I_N	5.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

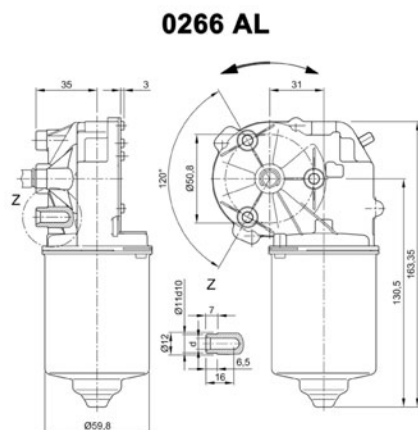
Pulses	78
Output channels	1

Other data

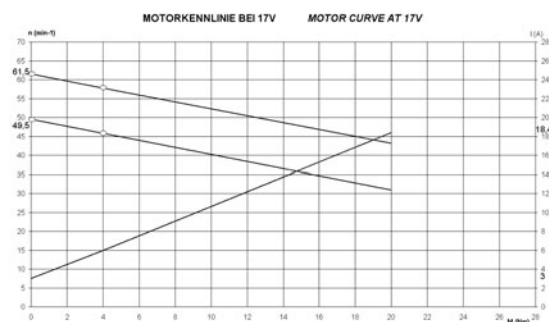
Gear ratio	78/1
Gear wheel material	plastic
Suppression components	$6\mu\text{H}$, 1nF
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d= for thread forming screw M6 DIN ISO 965-2

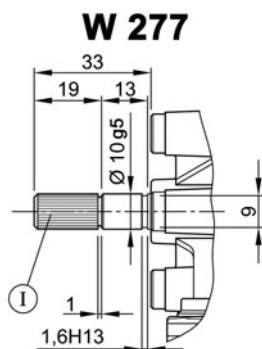
Characteristic curves



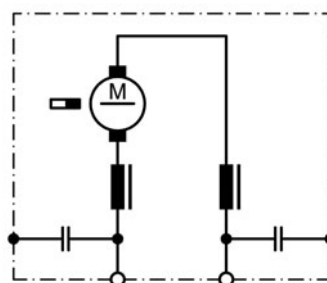
Motor picture



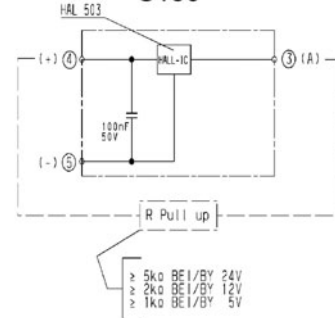
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30



S150



I serration (rolled)
 no of teeth 28, pitch circle dia 9 mm, tip circle
 dia 9.6 mm, root circle dia 8.26 mm space
 width angle 60°
 goes with go/no go gauge Frenco 33906
www.frenco.de

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	90.0
Nominal power [W]	P_N	35.9
Nominal current [A]	I_N	5.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

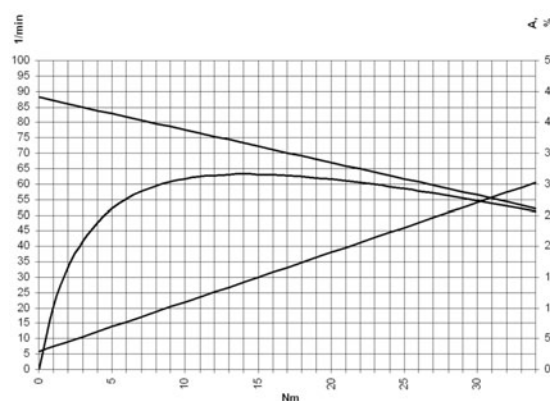
Pulses	69
Output channels	1

Other data

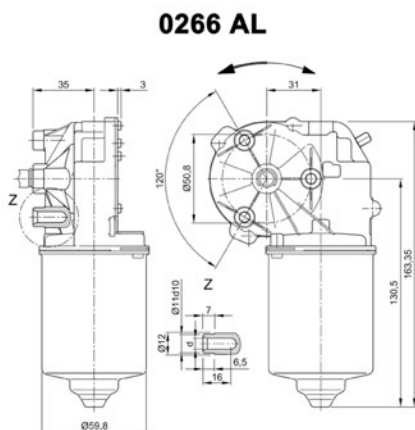
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	$6\mu\text{H}$, 1nF
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d=for thread forming screws M6 DIN-ISO 965-2

Characteristic curves

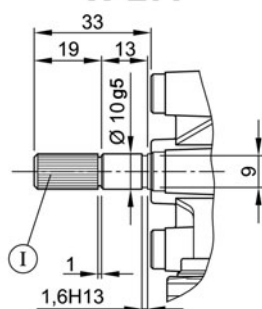


Motor picture

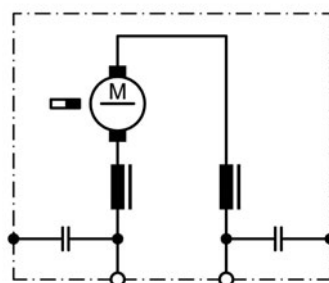


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

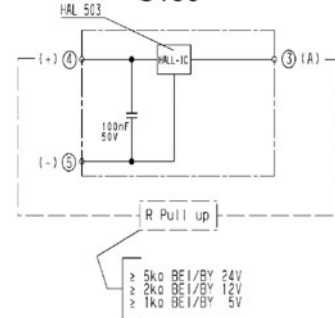
W 277



S 30



S150



I serration (rolled)
 no of teeth 28, pitch circle dia 9 mm, tip circle
 dia 9.6 mm, root circle dia 8.26 mm space
 width angle 60°
 goes with go/no go gauge Frenco 33906
www.frenco.de

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	120.0
Nominal power [W]	P_N	22.0
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

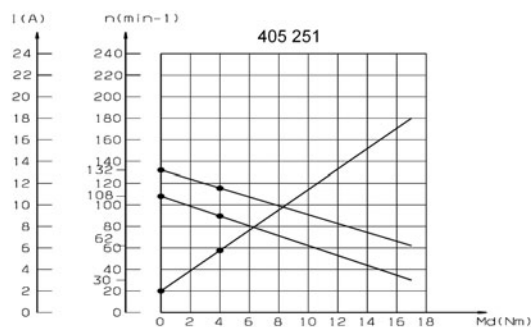
Pulses	79.5
Output channels	1

Other data

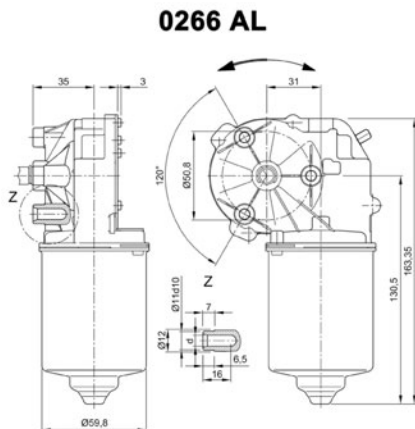
Gear ratio	53/2
Gear wheel material	Plastic
Suppression components	6.0 μ H, 1nF
Enclosure class	IP30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

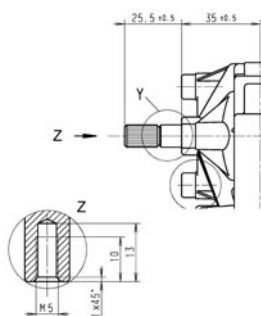
Characteristic curves



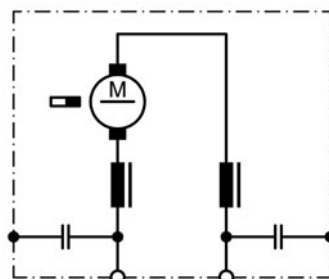
Motor picture



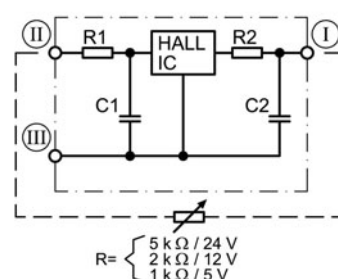
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30



S 124



I serration (rolled): **No teeth 28, pitch circle**
dia 9 mm, tip circle dia 9.6 mm, root circle
dia 8.26 mm space width angle 60° - go/no go
gauge Frenco 33906 - www.frenco.de

I Terminal 3, A
II Terminal 4, +
III Terminal 5, -

Notes

This image shows a blank sheet of white paper with horizontal blue ruling lines. The lines are evenly spaced and run across the width of the page. There are no margins, text, or other markings on the paper.

0268 (DCK35)

••• DC MOTORS WITH WORM GEAR



••• TECHNICAL DESCRIPTION

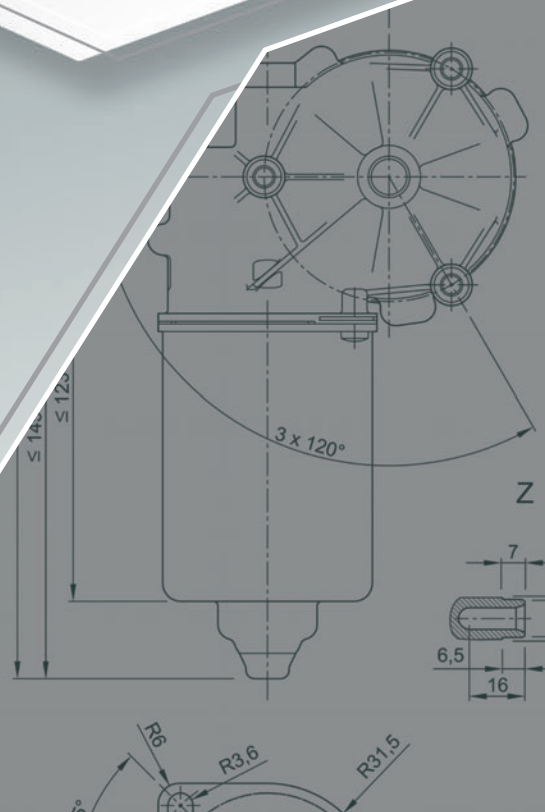
Motorhousing:	deep drawn & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	zinc die cast
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

••• INDUSTRIAL APPLICATION

Home automation, machine construction

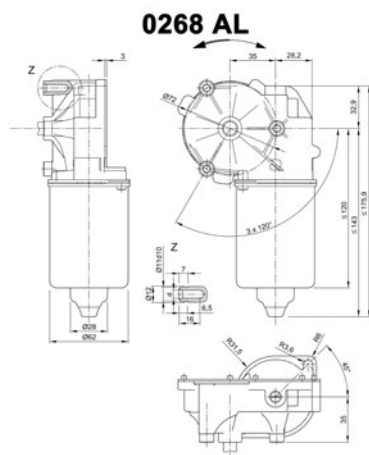
••• AUTOMOTIVE APPLICATION

Trunk & tailgate opening & closing



Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	5.00
No-load speed [min^{-1}]	n_0	62.0
Nominal power [W]	P_N	29.8
Nominal current [A]	I_N	5.5
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

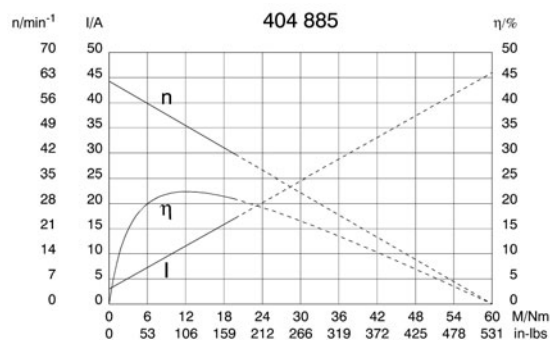
Pulses	63
Output channels	2

Other data

Gear ratio	63/1
Gear wheel material	plastic
Suppression components	3,5 μ H
Enclosure class	IP 30
Weight [kg]	1.250

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

Characteristic curves

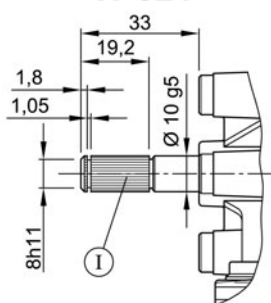


Motor picture

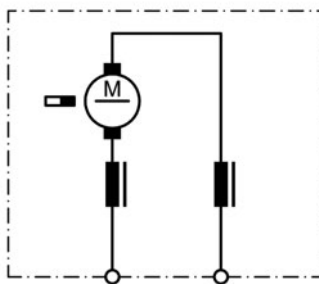


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

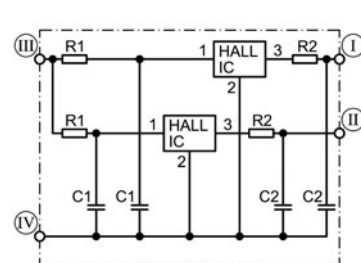
W 321



S 27



S 141

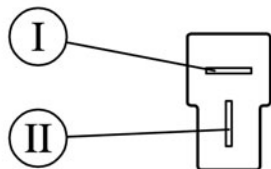


I serration (rolled): no of teeth 28, pitch circle dia 9 mm, tip circle dia 9.6 mm, root circle dia 8.26 mm space width angle 60° - go/no go gauge Frenco 33906 - www.frenco.de

I Hall-IC A1, terminal 3
 II Hall-IC A2, terminal 4
 III Hall-IC +, terminal 5
 IV Hall-IC -, terminal 6

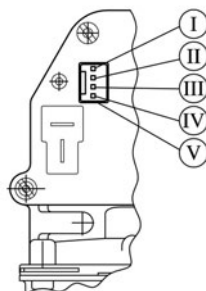
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

K 320



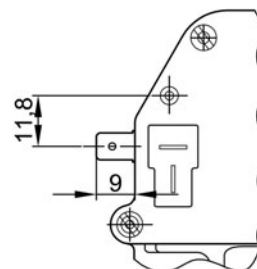
Flat plug (DIN 46244) 6,3x0,8 mating with
receptacle housing part#180907, drwg#
C-180907& Receptacles for tabs, conductor cross
section 0,5-1,5 sqmm (20-18AWG) part# 925603-
x, drwg# 925603 www.tycoelectronics.com

K 319



- I Hall-IC A1, terminal 3
- II Hall-IC A2, terminal 4
- III Hall-IC +, terminal 5
- IV Hall-IC -, terminal 6
- V Mating connector: Panduit CE100 F22 - 04

K 314



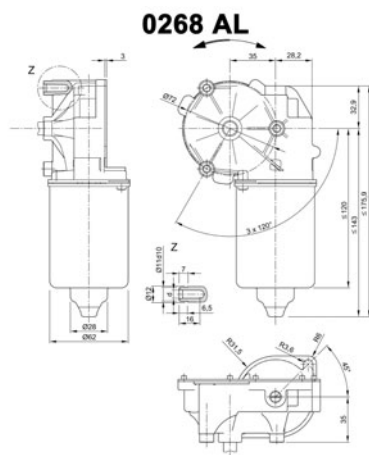
- I Ground connection
Blade terminal 6.3 x 0.8 DIN 46 244

Notes

Series DCK35
Motor type 404 938

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	6.00
No-load speed [min^{-1}]	n_0	50.0
Nominal power [W]	P_N	28.7
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

Pulses	0
Output channels	0

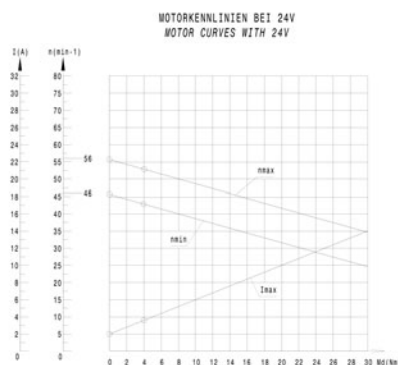
Other data

Gear ratio	63/1
Gear wheel material	plastic
Suppression components	3,5μH, 1nF
Enclosure class	IP 30
Weight [kg]	1.250

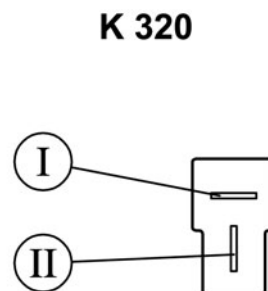
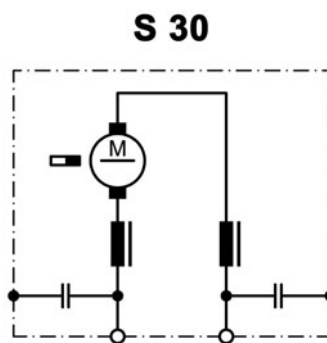
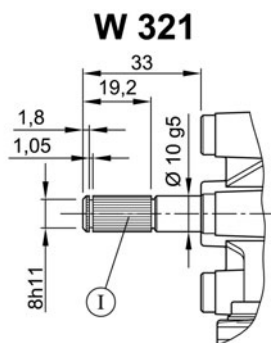
Remarks: d=for thread forming screws M6 DIN ISO 965-2

Characteristic curves

Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



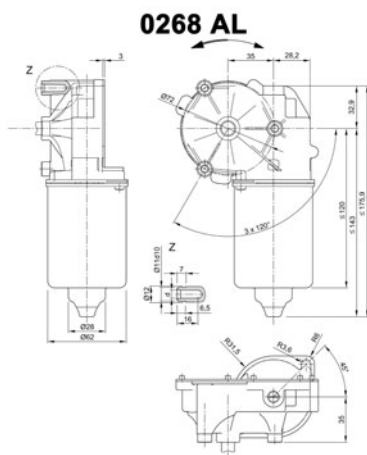
I serration (rolled): **no of teeth** 28, **pitch circle dia** 9 mm, **tip circle dia** 9.6 mm, **root circle dia** 8.26 mm **space width angle** 60°- go/no go gauge Frenco 33906 - www.frenco.de

Flat plug (DIN 46244) 6,3x0,8 mating with
receptacle housing part#180907, drwg#
C-180907& Receptacles for tabs, conductor cross
section 0,5-1,5 sqmm (20-18AWG) part# 925603-
x, drwg# 925603 www.tycoelectronics.com

Series DCK35
Motor type 404 983

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	5.00
No-load speed [min^{-1}]	n_0	70.0
Nominal power [W]	P_N	33.5
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

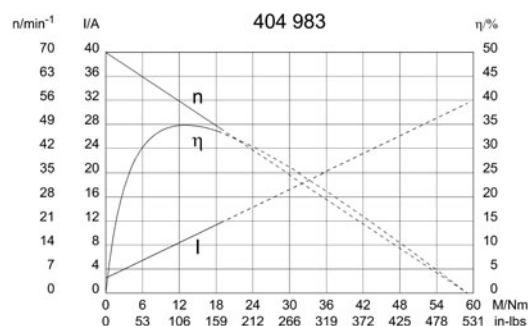
Pulses	0
Output channels	0

Other data

Gear ratio	55/1
Gear wheel material	plastic
Suppression components	3,5μH, 1nF
Enclosure class	IP 30
Weight [kg]	1.250

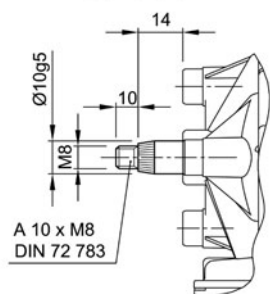
Remarks: d = for thread-forming screw M6 DIN ISO 965-2

Characteristic curves

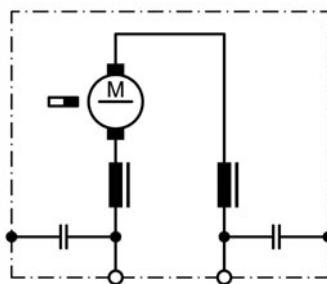


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

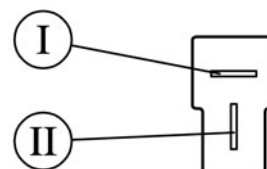
W 305



S 30



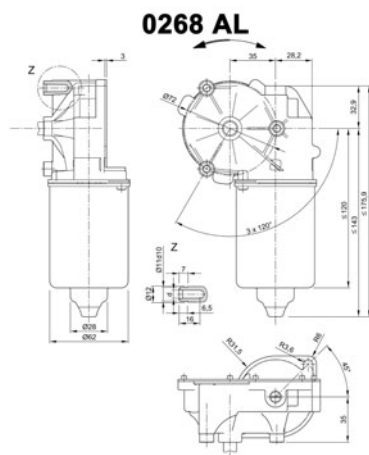
K 320



Flat plug (DIN 46244) 6,3x0,8 mating with
receptacle housing part#180907, drwg#
C-180907& Receptacles for tabs, conductor cross
section 0,5-1,5 sqmm (20-18AWG) part# 925603-
x, drwg# 925603 www.tycoelectronics.com

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	6.00
No-load speed [min^{-1}]	n_0	60.0
Nominal power [W]	P_N	29.3
Nominal current [A]	I_N	7.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

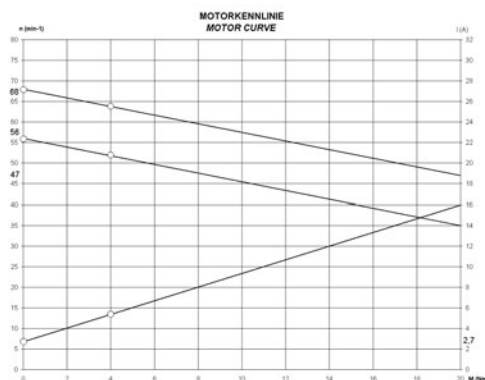
Pulses	0
Output channels	0

Other data

Gear ratio	63/1
Gear wheel material	plastic
Suppression components	3,5 μ H
Enclosure class	IP 30
Weight [kg]	1.376

Remarks:

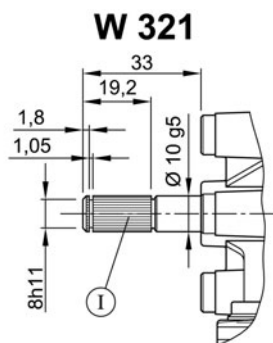
Characteristic curves



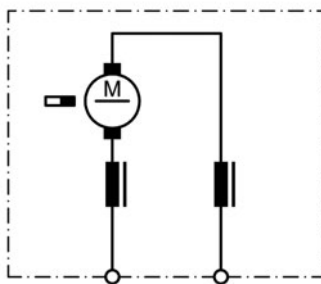
Motor picture



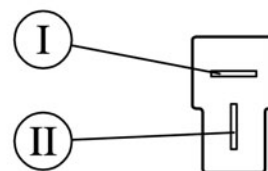
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 27



K 320

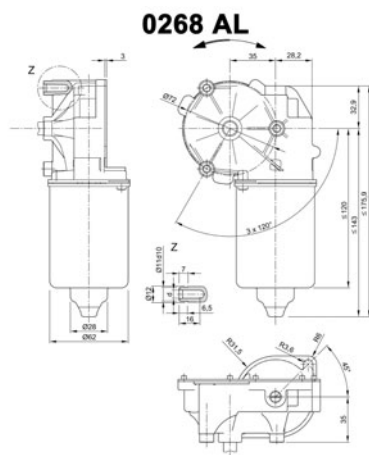


I serration (rolled): no of teeth 28, pitch circle dia 9 mm, tip circle dia 9.6 mm, root circle dia 8.26 mm space width angle 60°- go/no go gauge Frenco 33906 - www.frenco.de

Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 www.lycoelectronics.com

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	8.00
No-load speed [min^{-1}]	n_0	75.0
Nominal power [W]	P_N	37.7
Nominal current [A]	I_N	7.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

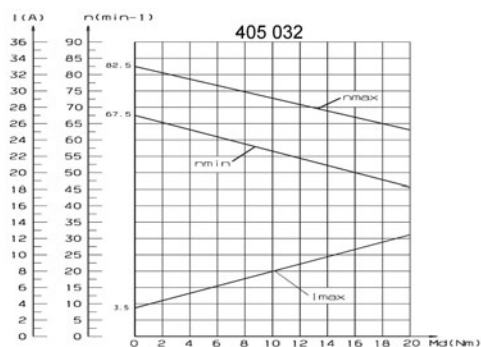
Pulses	63
Output channels	1

Other data

Gear ratio	63/1
Gear wheel material	Plastic
Suppression components	3.5 μ H
Enclosure class	IP30
Weight [kg]	1.250

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

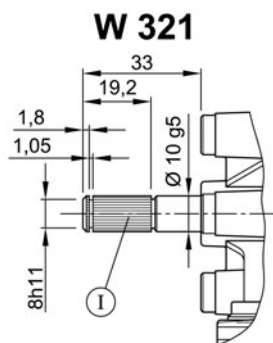
Characteristic curves



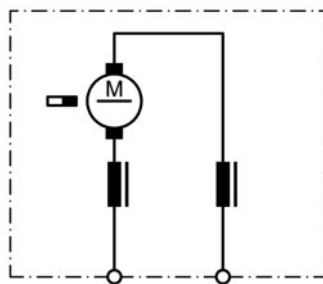
Motor picture



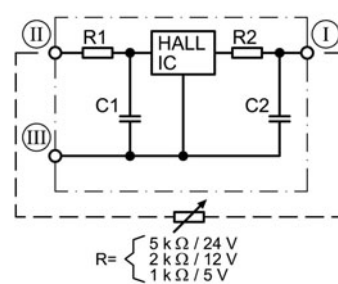
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 27



S 124



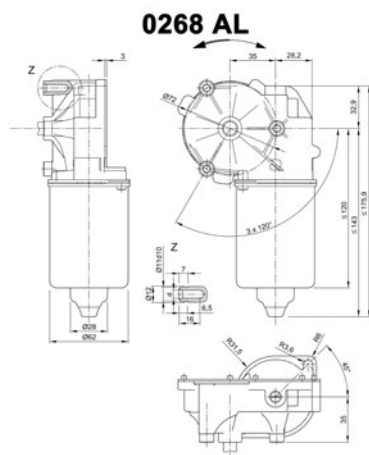
I serration (rolled): no of teeth 28, pitch circle
 dia 9 mm, tip circle dia 9.6 mm, root circle
 dia 8.26 mm space width angle 60° - go/no go
 gauge Frencos 33906 - www.frencos.de

I Terminal 3, A
 II Terminal 4, +
 III Terminal 5, -

Series DCK35
Motor type 405 033

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	8.00
No-load speed [min^{-1}]	n_0	53.0
Nominal power [W]	P_N	39.2
Nominal current [A]	I_N	6.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

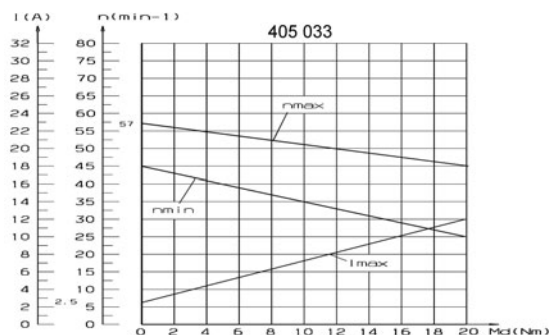
Pulses	91
Output channels	1

Other data

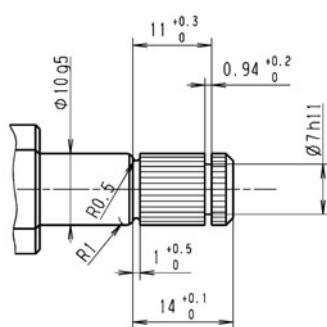
Gear ratio	91/1
Gear wheel material	plastic
Suppression components	3,5μH, 1nF
Enclosure class	IP 30
Weight [kg]	1.250

Remarks: d=for thread forming screws M6 DIN ISO 965-2

Characteristic curves

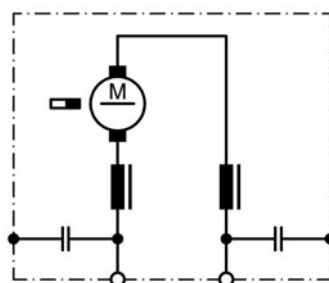


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

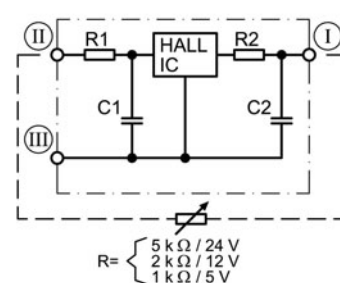


Splines: 8 x 10 (according to DIN 5481)
Output shaft length = 28mm

S 30



S 124

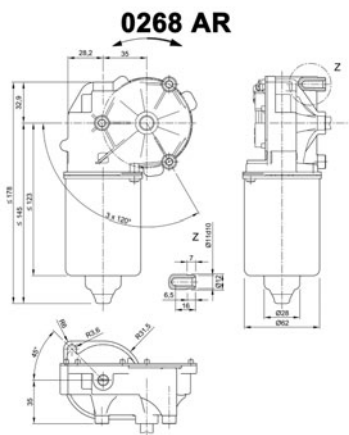


- I Terminal 3, A
- II Terminal 4, +
- III Terminal 5, -

Series DCK35
Motor type 405 060

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	6.00
No-load speed [min^{-1}]	n_0	60.0
Nominal power [W]	P_N	35.0
Nominal current [A]	I_N	6.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

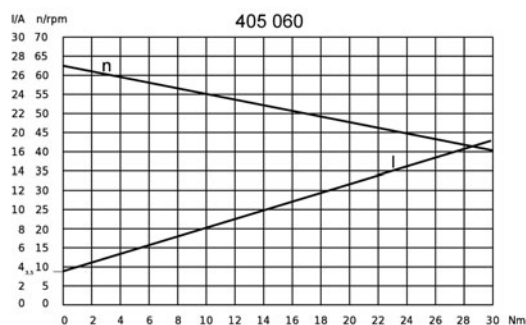
Pulses	91
Output channels	1

Other data

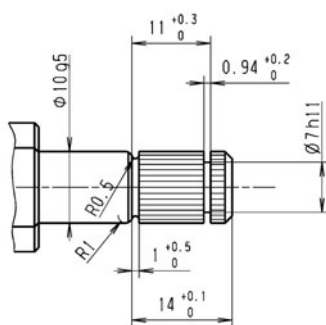
Gear ratio	91/1
Gear wheel material	plastic
Suppression components	3,5μ, 1nF
Enclosure class	IP 30
Weight [kg]	0.000

Remarks: d=for thread forming screw M6 DIN ISO 964-2

Characteristic curves

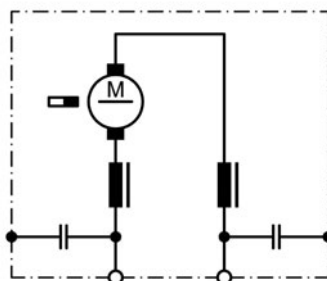


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

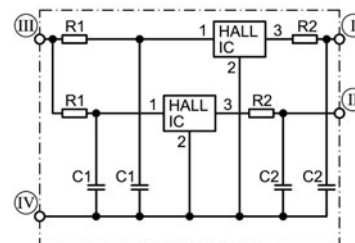


Splines: 8 x 10 (according to DIN 5481)
Output shaft length = 28mm

S 30



S 141

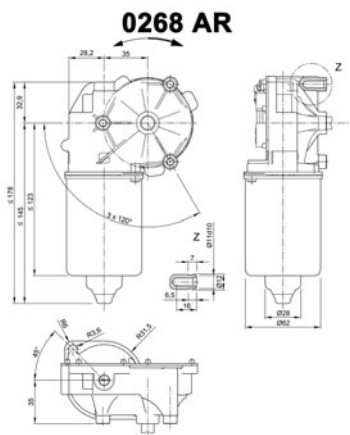


- I** Hall-IC A1, terminal 3
- II** Hall-IC A2, terminal 4
- III** Hall-IC +, terminal 5
- IV** Hall-IC -, terminal 6

Series DCK35
Motor type 405 063

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	3.00
No-load speed [min^{-1}]	n_0	240.0
Nominal power [W]	P_N	65.6
Nominal current [A]	I_N	8.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

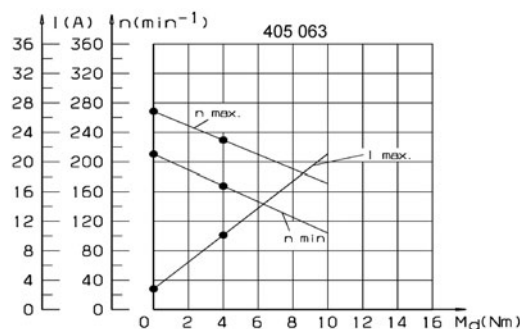
Pulses	17.5
Output channels	2

Other data

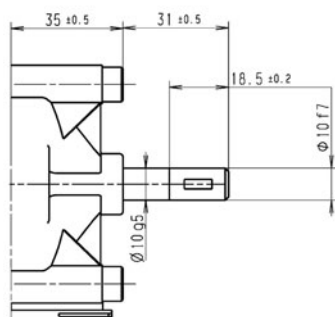
Gear ratio	70/4
Gear wheel material	plastic
Suppression components	6μH, 1nF
Enclosure class	IP 30
Weight [kg]	1.366

Remarks: d=for thread forming screw M6 DIN ISO 965-2

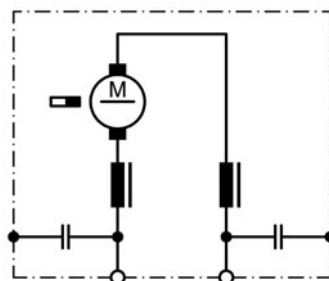
Characteristic curves



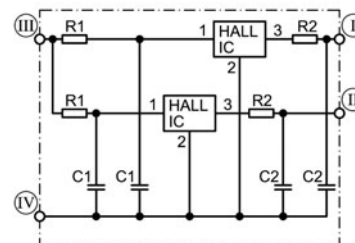
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30



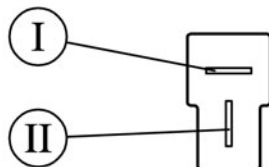
S 141



- I** Hall-IC A1, terminal 3
- II** Hall-IC A2, terminal 4
- III** Hall-IC +, terminal 5
- IV** Hall-IC -, terminal 6

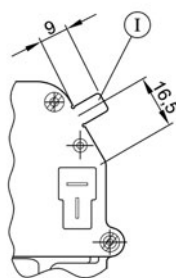
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

K 320

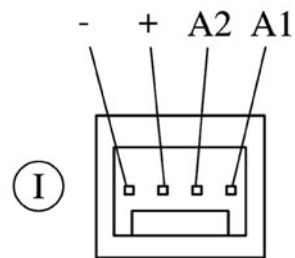


Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 www.tycoelectronics.com

K 321



I Ground connection
Blade terminal 6.3 x 0.8 DIN 46 244



I Mating connector: Panduit CE100 F22-04

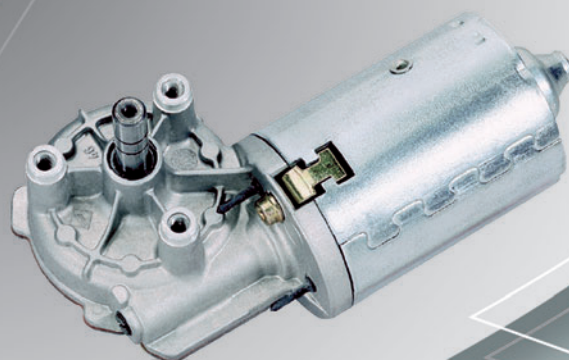
Notes

Notes

This image shows a single sheet of white paper with horizontal blue or grey ruling lines. The lines are evenly spaced and run across the width of the page. There are approximately 20 lines visible. The paper has a slight shadow on the right side, suggesting it's resting on a surface.

0270 (SWMK)

❖❖❖ DC MOTORS WITH WORM GEAR

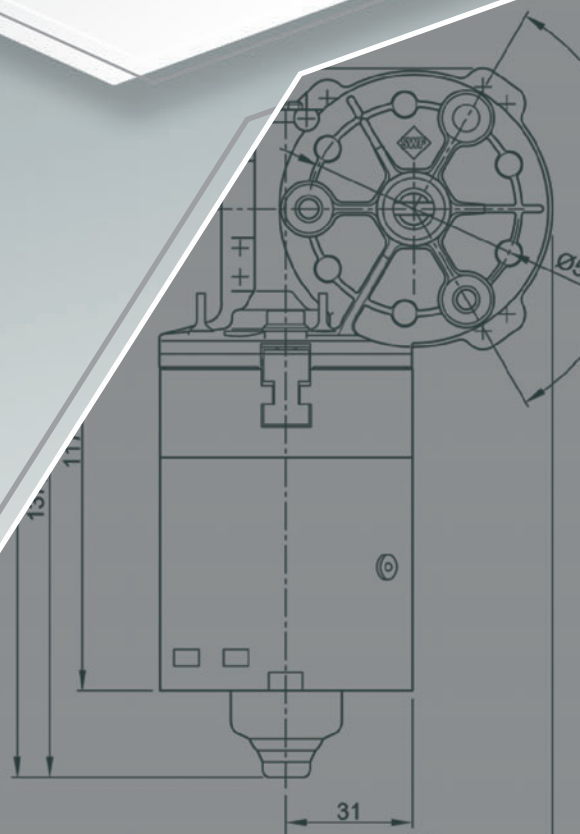


❖❖❖ TECHNICAL DESCRIPTION

Motorhousing:	rolled, corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	aluminium die cast
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	connector or tinned leads
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

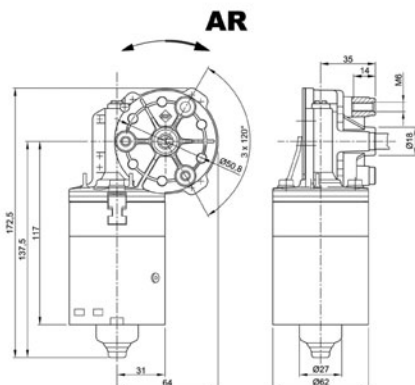
❖❖❖ APPLICATION

Industry, Linear drives, General machinery,
Vending machines, Agricultural technology,
Office machines, Laboratory devices,
Medical technology, Traffic & communications
technology, Film/optics



Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	50.0
Nominal power [W]	P_N	17.7
Nominal current [A]	I_N	2.5
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

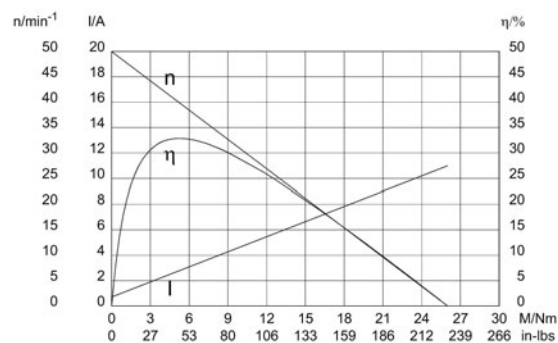
Pulses	0
Output channels	0

Other data

Gear ratio	55/1
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	1.200

Remarks:

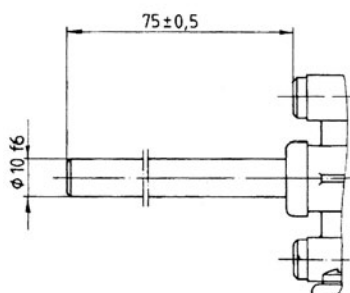
Characteristic curves



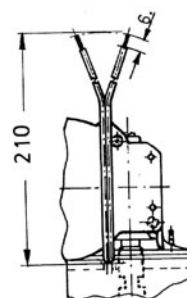
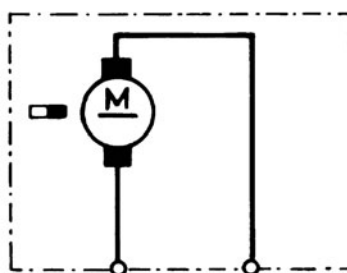
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

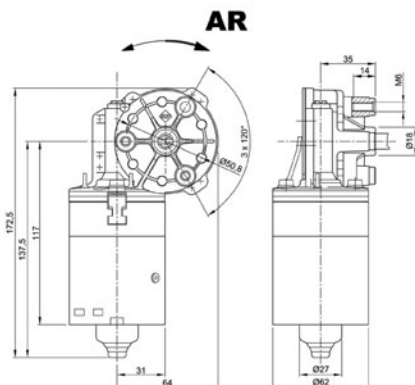


S 28

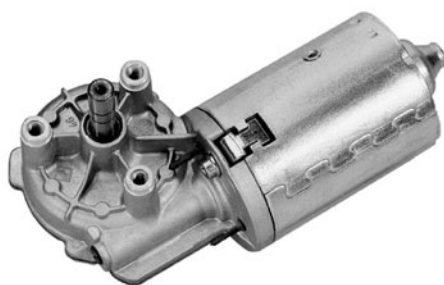


Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	33.0
Nominal power [W]	P_N	11.7
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

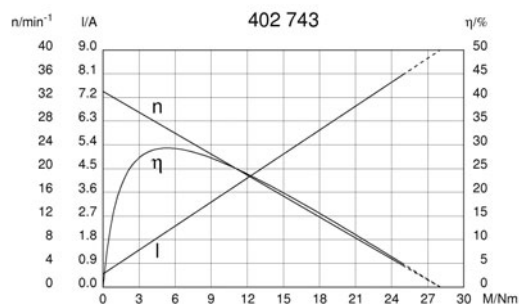
Pulses	0
Output channels	0

Other data

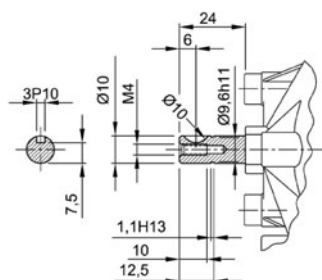
Gear ratio	69/1
Gear wheel material	Plastic
Suppression components	4.7 μ H
Enclosure class	IP30
Weight [kg]	1.200

Remarks:

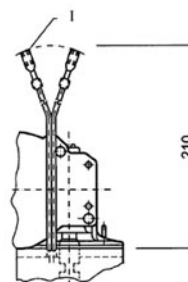
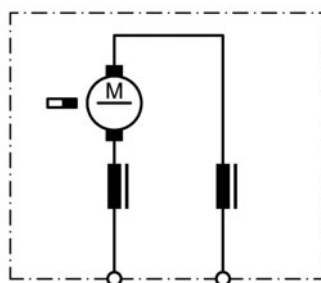
Characteristic curves



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 27



I: Spade connector 2.8 x 0.8 DIN 46 247

Series SWMK

Motor type 402 887

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	3.50
No-load speed [min^{-1}]	n_0	50.0
Nominal power [W]	P_N	15.9
Nominal current [A]	I_N	2.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

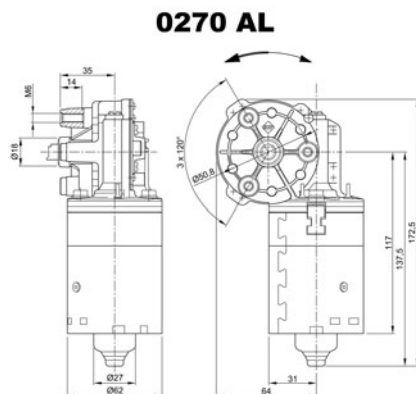
Pulses	0
Output channels	0

Other data

Gear ratio	55/1
Gear wheel material	Plastic
Suppression components	4.7 μ H, 1nF
Enclosure class	IP30
Weight [kg]	1.200

Remarks:

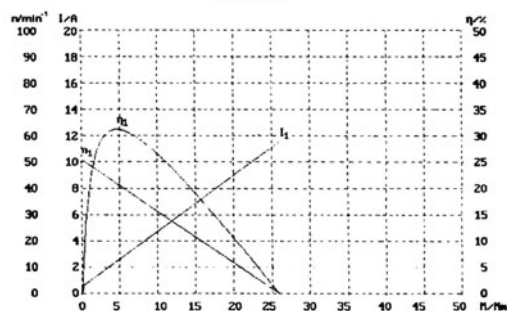
Characteristic curves



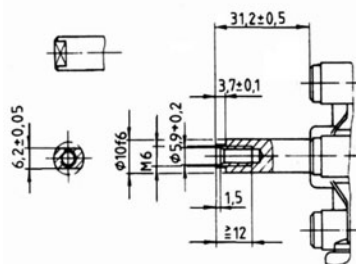
Motor picture



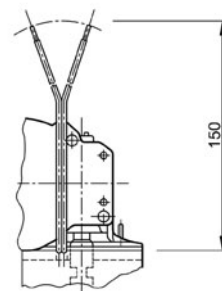
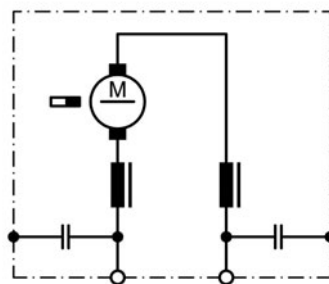
402.887



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30



Series SWMK

Motor type 403 389

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	1.00
No-load speed [min^{-1}]	n_0	280.0
Nominal power [W]	P_N	24.9
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

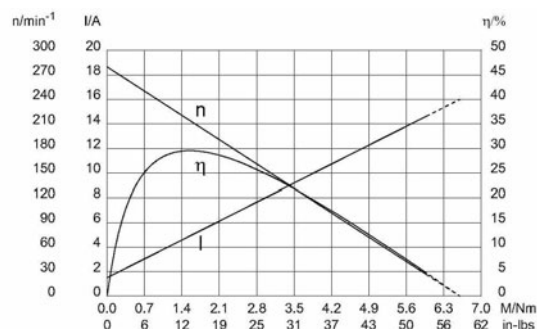
Pulses	0
Output channels	0

Other data

Gear ratio	41/4
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	1.200

Remarks:

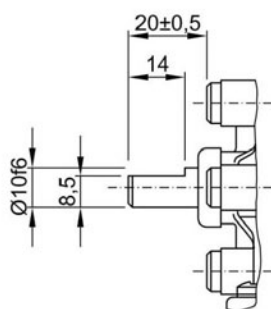
Characteristic curves



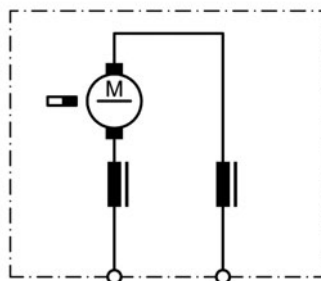
Motor picture



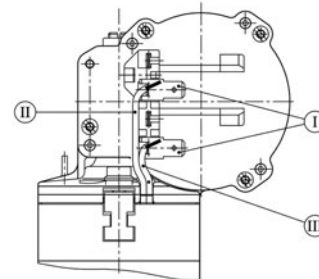
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 27



K 42



- I Blade terminal ends
6,3 x 0,8 DIN 46 244
- II green
- III red

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	36
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	100.0
Nominal power [W]	P_N	18.3
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

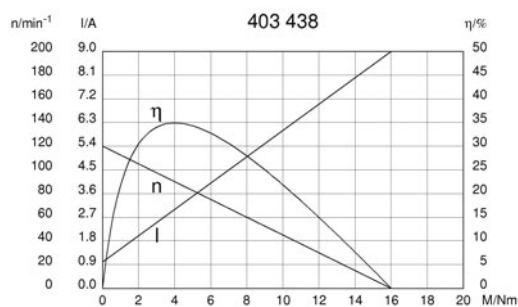
Pulses	0
Output channels	0

Other data

Gear ratio	53/2
Gear wheel material	Plastic
Suppression components	4.7 μ H, 1nF
Enclosure class	IP30
Weight [kg]	1.200

Remarks:

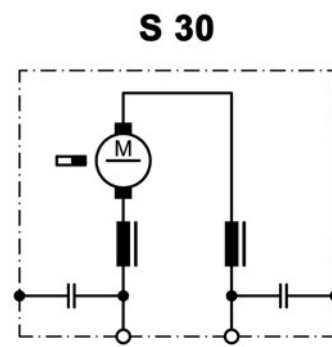
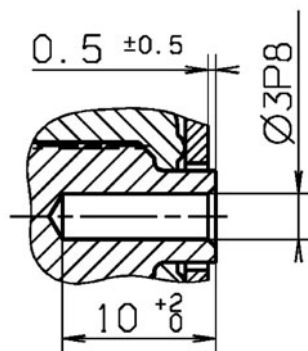
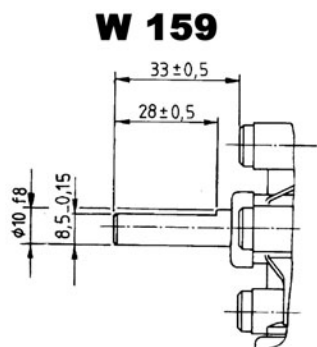
Characteristic curves



Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	0.80
No-load speed [min^{-1}]	n_0	350.0
Nominal power [W]	P_N	27.0
Nominal current [A]	I_N	8.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

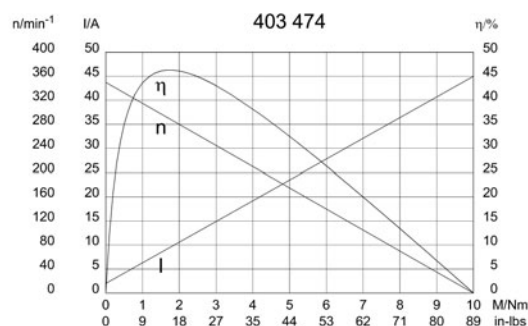
Pulses	0
Output channels	0

Other data

Gear ratio	41/4
Gear wheel material	plastic
Suppression components	""
Enclosure class	IP 30
Weight [kg]	1.200

Remarks:

Characteristic curves

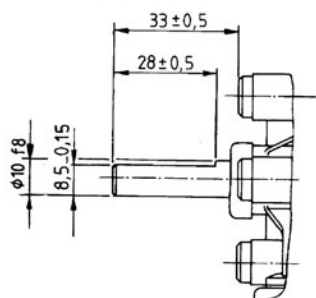


Motor picture

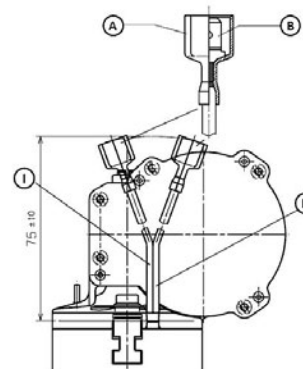
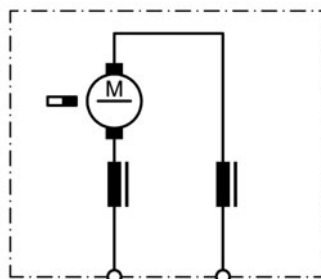


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 159



S 27



A: housing MST AMP No. 2-521055-2

B: spade terminals 6.3 x 0.8 DIN 46 244

I: red

II: green

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	0.80
No-load speed [min^{-1}]	n_0	350.0
Nominal power [W]	P_N	27.0
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

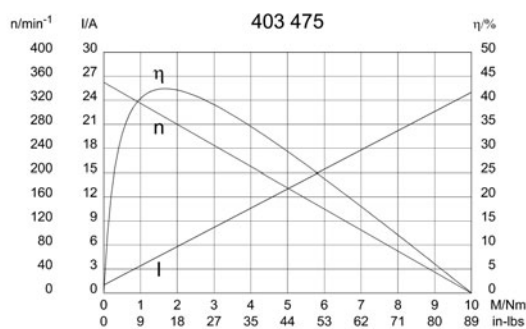
Pulses	0
Output channels	0

Other data

Gear ratio	41/4
Gear wheel material	plastic
Suppression components	1nF
Enclosure class	IP 30
Weight [kg]	1.200

Remarks:

Characteristic curves

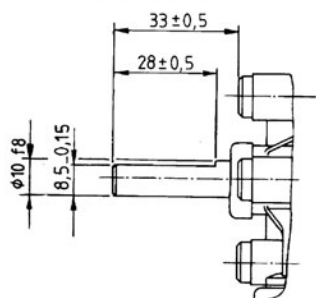


Motor picture

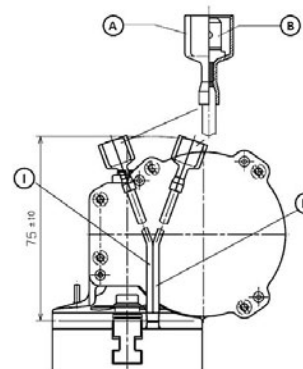
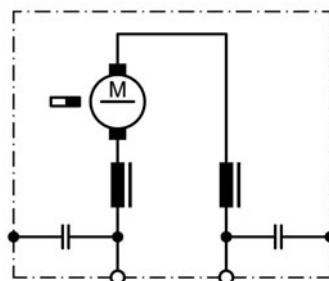


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 159



S 30



A: housing MST AMP No. 2-521055-2

B: spade terminals 6.3 x 0.8 DIN 46 244

I: red

II: green

Series SWMK

Motor type 403 559

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	110.0
Nominal power [W]	P_N	20.8
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

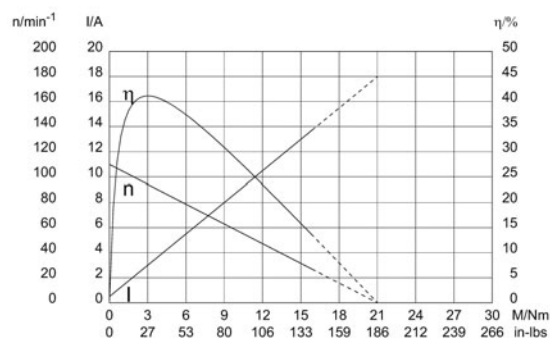
Pulses	0
Output channels	0

Other data

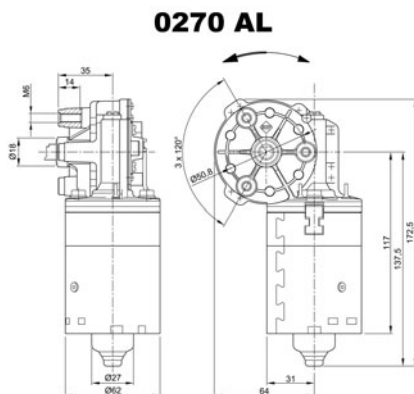
Gear ratio	53/2
Gear wheel material	Plastic
Suppression components	4.7 μ H, 1nF
Enclosure class	IP30
Weight [kg]	1.200

Remarks:

Characteristic curves

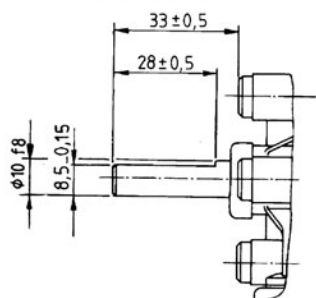


Motor picture

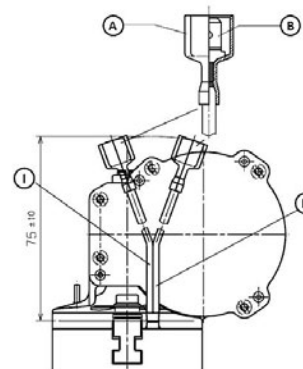
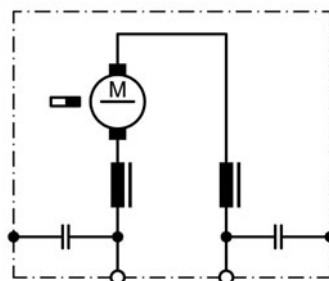


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 159



S 30



A: housing MST AMP No. 2-521055-2

B: spade terminals 6.3 x 0.8 DIN 46 244

I: red

II: green

Series SWMK

Motor type 403 567

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	1.00
No-load speed [min^{-1}]	n_0	260.0
Nominal power [W]	P_N	23.0
Nominal current [A]	I_N	10.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

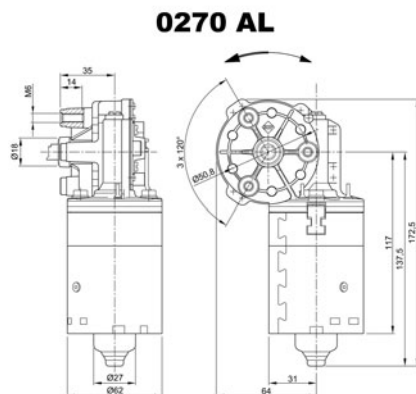
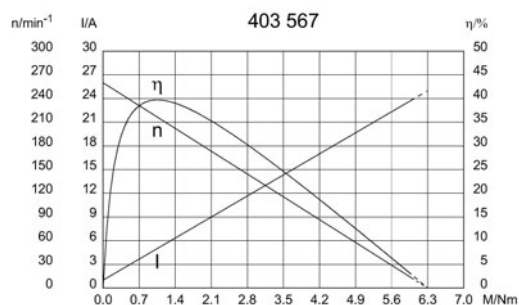
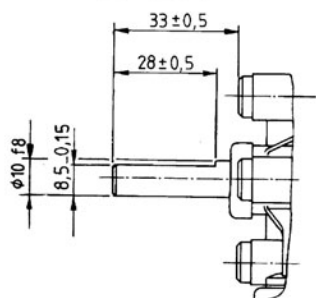
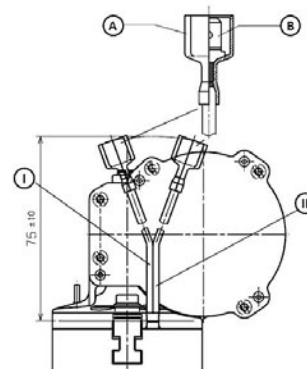
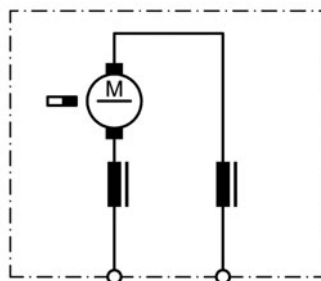
Sensor data

Pulses	0
Output channels	0

Other data

Gear ratio	41/4
Gear wheel material	Plastic
Suppression components	
Enclosure class	
Weight [kg]	1.200

Remarks:

Characteristic curves**Motor picture****Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)****W 159****S 27**

A: housing MST AMP No. 2-521055-2

B: spade terminals 6.3 x 0.8 DIN 46 244

I: red

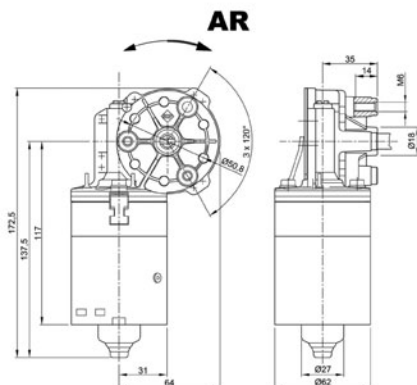
II: green

Series SWMK

Motor type 403 790

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.50
No-load speed [min^{-1}]	n_0	21.0
Nominal power [W]	P_N	4.87
Nominal current [A]	I_N	1.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

Pulses	0
Output channels	0

Other data

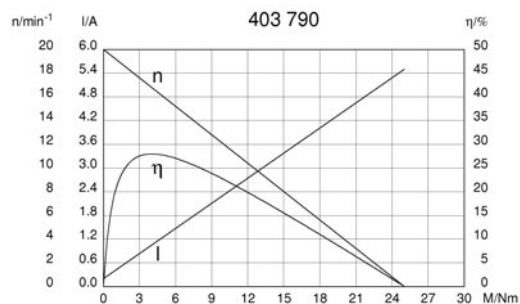
Gear ratio	69/1
Gear wheel material	Plastic
Suppression components	4.7 μ H, 1 μ F
Enclosure class	IP30
Weight [kg]	1.200

Remarks:

Motor picture

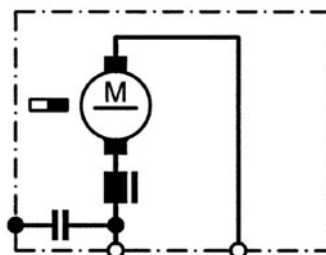
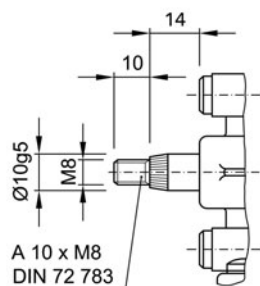


Characteristic curves

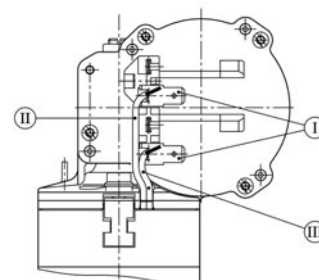


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 205



K 42



- I Blade terminal ends
6,3 x 0,8 DIN 46 244
- II green
- III red

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	1.00
No-load speed [min^{-1}]	n_0	264.0
Nominal power [W]	P_N	23.2
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

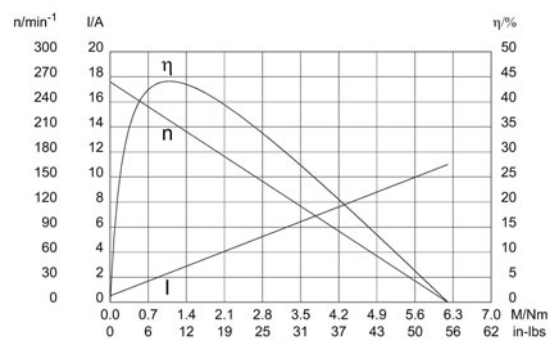
Pulses	10.25
Output channels	1

Other data

Gear ratio	41/4
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	1.200

Remarks:

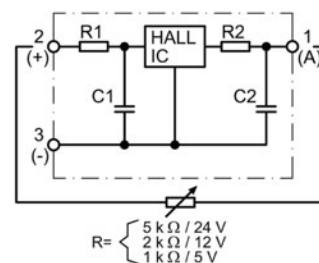
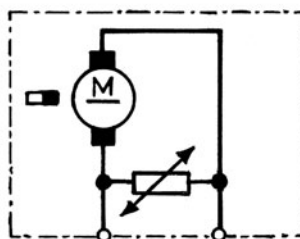
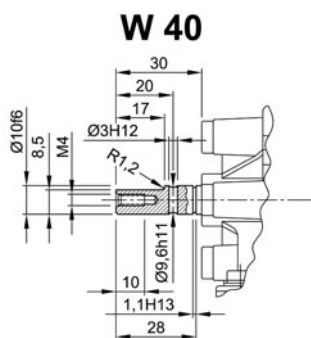
Characteristic curves



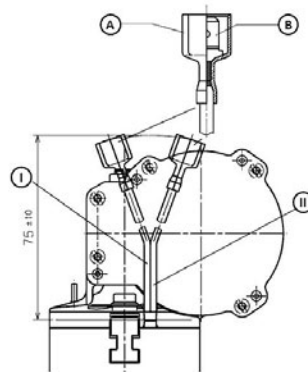
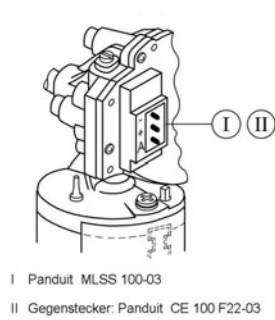
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



A: housing MST AMP No. 2-521055-2

B: spade terminals 6.3 x 0.8 DIN 46 244

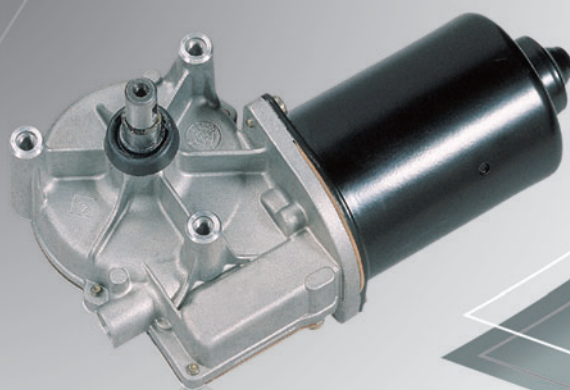
l: red

II: green

Notes

0277 (SW2K)

•••• DC MOTORS WITH WORM GEAR

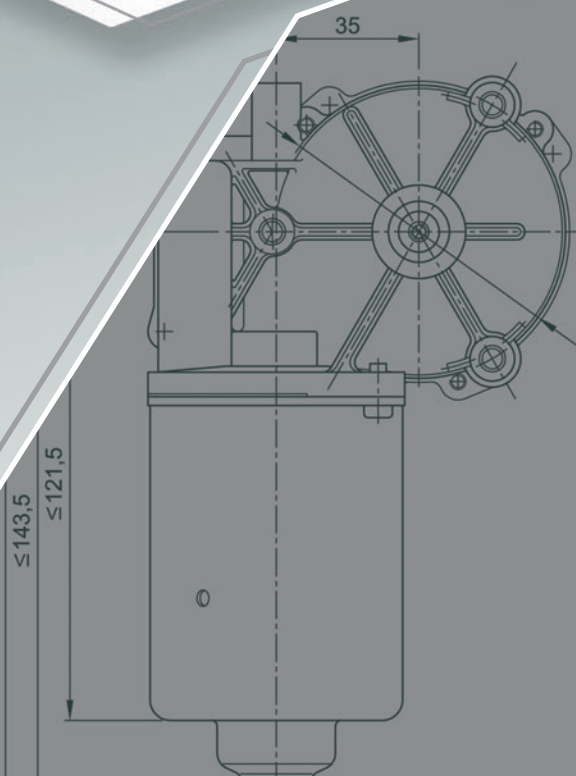


•••• TECHNICAL DESCRIPTION

Motorhousing:	deep drawn & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	aluminium die cast
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	connector or tinned leads
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

•••• APPLICATION

Industry, Linear drives, General machinery,
Vending machines, Agricultural technology,
Office machines, Laboratory devices,
Medical technology, Traffic & communications
technology, Film/optics



Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	5.00
No-load speed [min^{-1}]	n_0	40.0
Nominal power [W]	P_N	16.8
Nominal current [A]	I_N	3.5
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

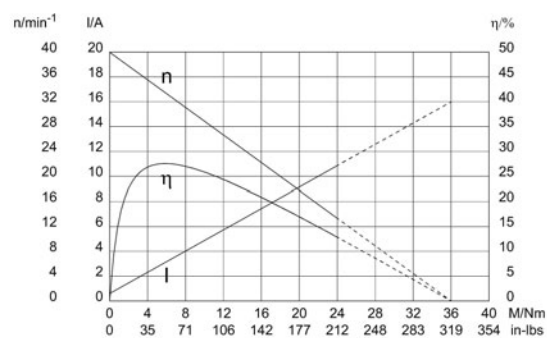
Pulses	0
Output channels	0

Other data

Gear ratio	78/1
Gear wheel material	Plastic
Suppression components	4.7 μ H, 1nF
Enclosure class	IP40
Weight [kg]	1.200

Remarks: Ball bearing

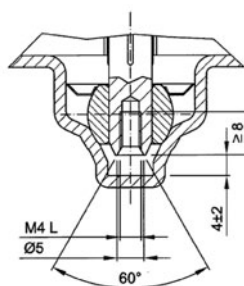
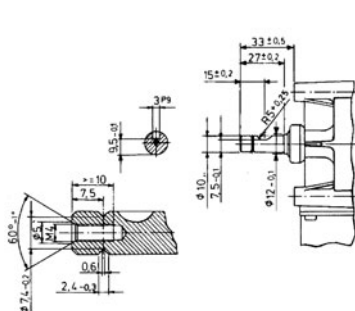
Characteristic curves



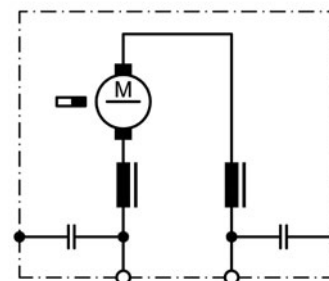
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

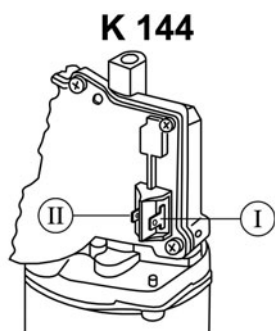


S 30



! Lefthand thread

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



- I Blade terminal ends 6,3 x 0,8 DIN 46 244
- II Blade terminal ends 4,8 x 0,8 DIN 46 244

Notes

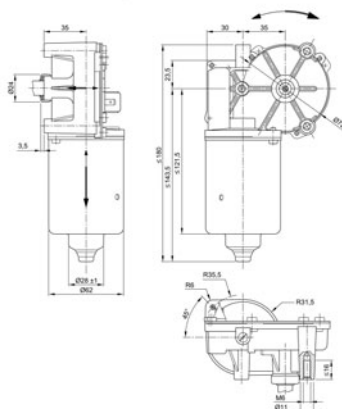
[illegible]

Series SW2K
Motor type 403 930

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

0277 AR



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	230.0
Nominal power [W]	P_N	44.2
Nominal current [A]	I_N	6.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

Pulses	0
Output channels	0

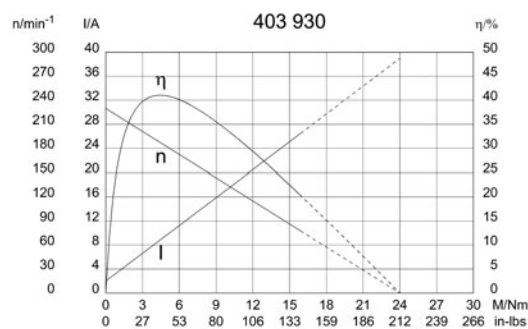
Other data

Gear ratio	70/4
Gear wheel material	plastic
Suppression components	""
Enclosure class	IP 40
Weight [kg]	1.200

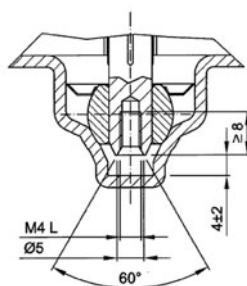
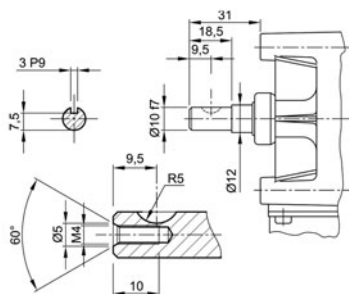
Remarks: Ball bearing

Characteristic curves

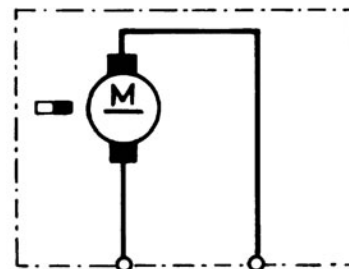
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 191

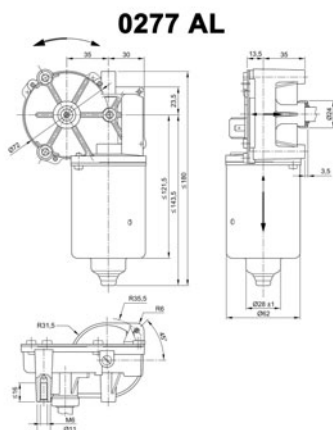
S 28



! Lefthand thread

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	126.0
Nominal power [W]	P_N	23.0
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

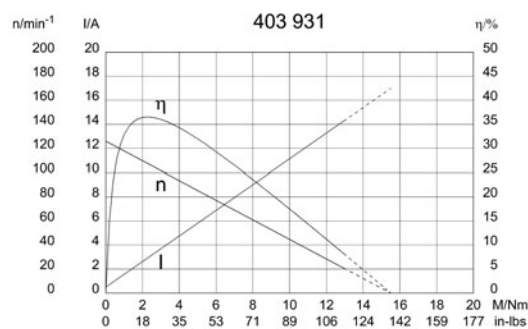
Pulses	0
Output channels	0

Other data

Gear ratio	70/4
Gear wheel material	plastic
Suppression components	4.7 μ H, 1nF
Enclosure class	IP 40
Weight [kg]	1.200

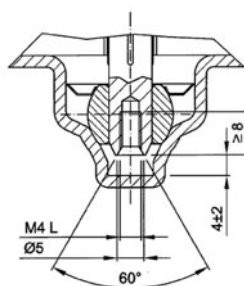
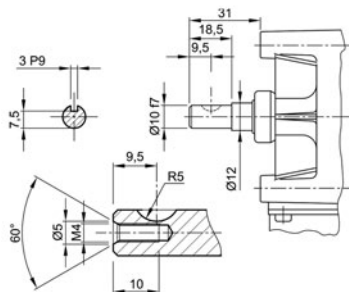
Remarks: Ball bearing

Motor picture

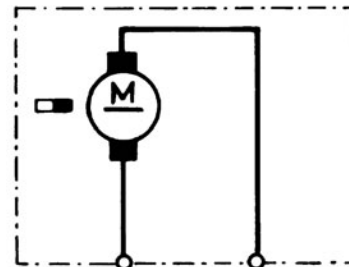


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 191

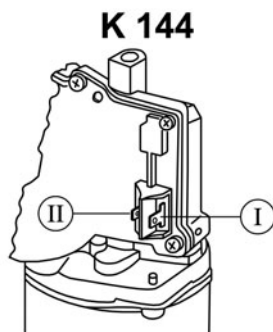


S 28



! Lefthand thread

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



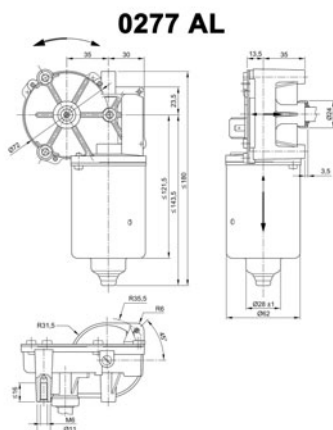
- I Blade terminal ends 6,3 x 0,8 DIN 46 244
- II Blade terminal ends 4,8 x 0,8 DIN 46 244

Notes

[illegible]

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	2.00
No-load speed [min^{-1}]	n_0	230.0
Nominal power [W]	P_N	44.2
Nominal current [A]	I_N	6.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

Pulses	0
Output channels	0

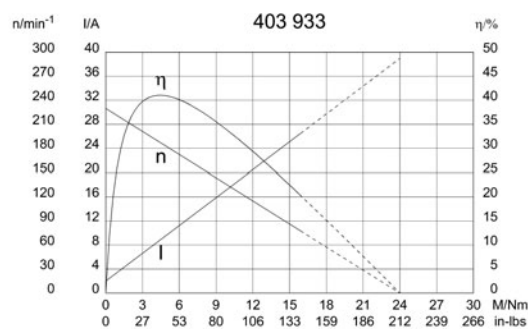
Other data

Gear ratio	70/4
Gear wheel material	plastic
Suppression components	""
Enclosure class	IP 40
Weight [kg]	1.200

Remarks: Ball bearing

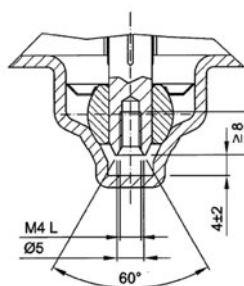
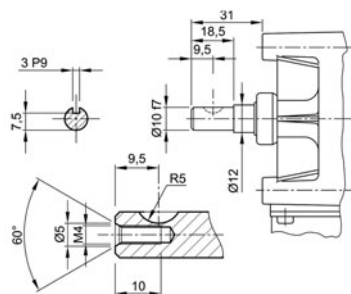
Characteristic curves

Motor picture

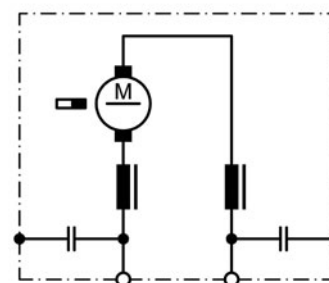


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

W 191

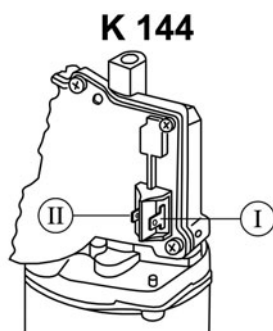


S 30



! Lefthand thread

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

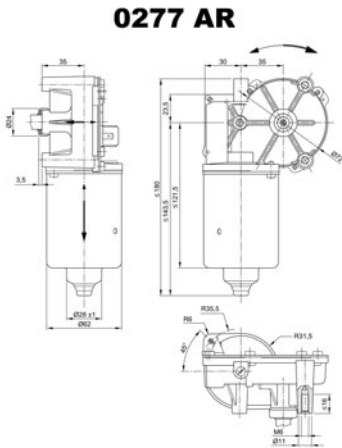


- I Blade terminal ends 6,3 x 0,8 DIN 46 244
- II Blade terminal ends 4,8 x 0,8 DIN 46 244

Notes

This image shows a single sheet of white paper with horizontal blue ruling lines. The lines are evenly spaced and run across the width of the page. There are no margins, text, or other markings on the paper.

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



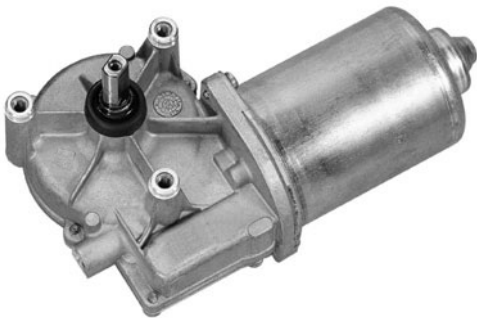
Performance data		
Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	5.00
No-load speed [min^{-1}]	n_0	54.0
Nominal power [W]	P_N	26.3
Nominal current [A]	I_N	5.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

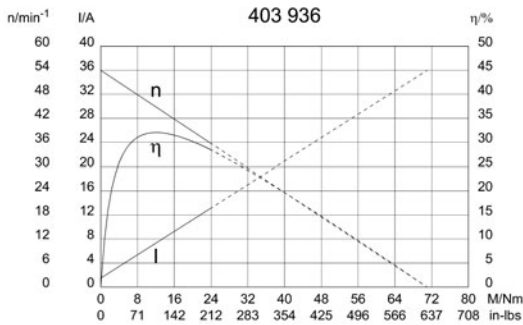
Other data	
Gear ratio	78/1
Gear wheel material	plastic
Suppression components	5 μ H, 1nF
Enclosure class	IP 40
Weight [kg]	1.200

Remarks:

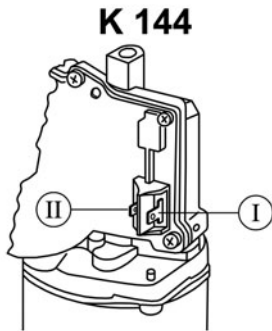
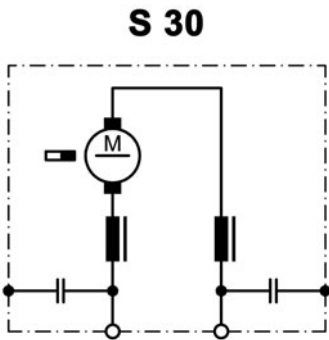
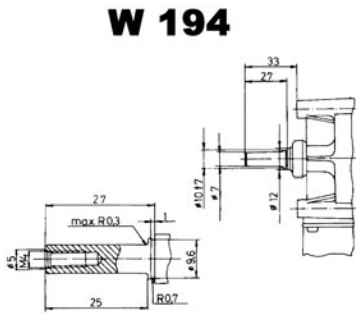
Motor picture



Characteristic curves



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

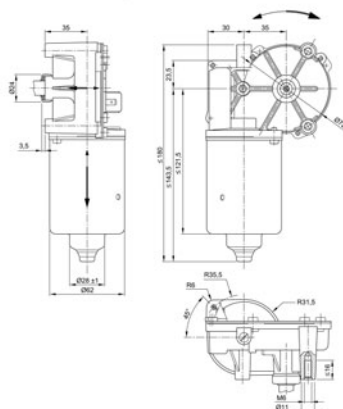


- I Blade terminal ends 6,3 x 0,8 DIN 46 244
- II Blade terminal ends 4,8 x 0,8 DIN 46 244

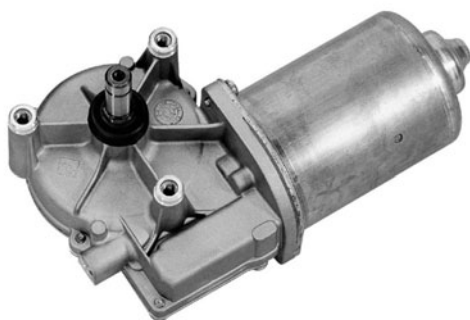
Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

0277 AR



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	5.00
No-load speed [min^{-1}]	n_0	40.0
Nominal power [W]	P_N	16.8
Nominal current [A]	I_N	3.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

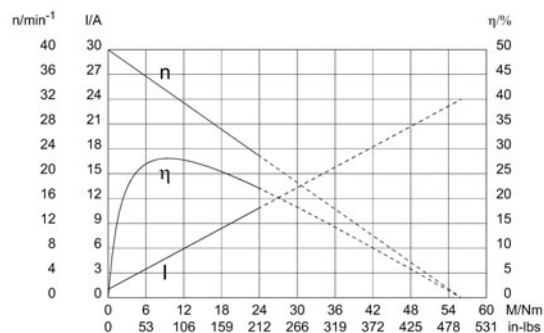
Pulses	0
Output channels	0

Other data

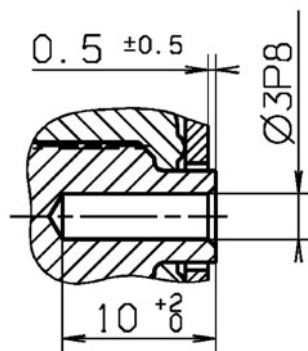
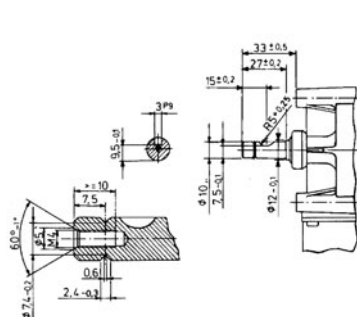
Gear ratio	78/1
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP40
Weight [kg]	1.200

Remarks:

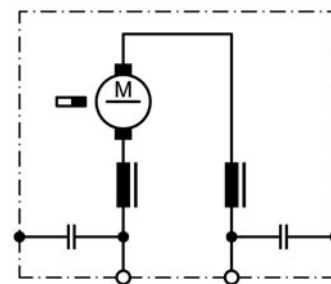
Characteristic curves



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



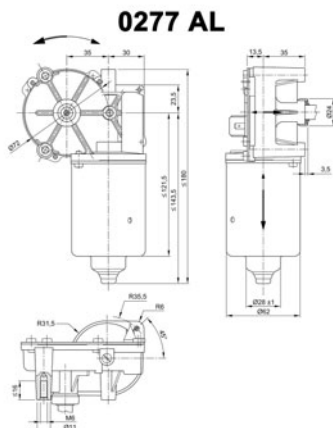
S 30



Series SW2K
Motor type 403 957

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	5.00
No-load speed [min^{-1}]	n_0	65.0
Nominal power [W]	P_N	27.2
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

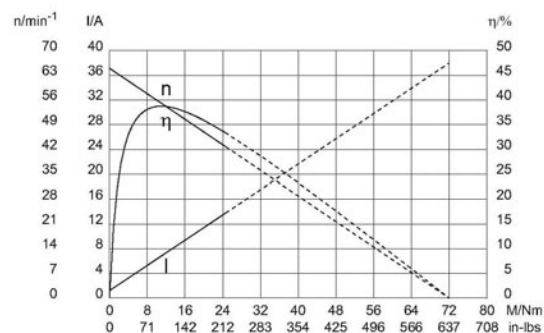
Pulses	0
Output channels	0

Other data

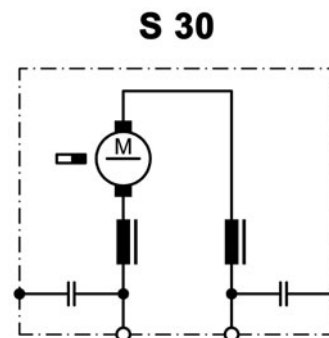
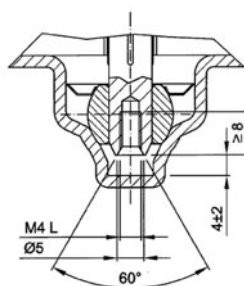
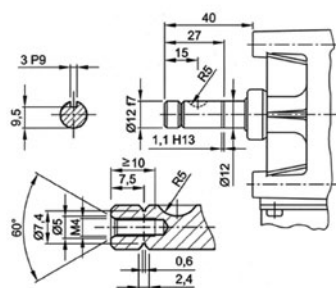
Gear ratio	63/1
Gear wheel material	Plastic
Suppression components	4.7μH, 1nF
Enclosure class	IP40
Weight [kg]	1.200

Remarks: Ball bearing

Characteristic curves



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



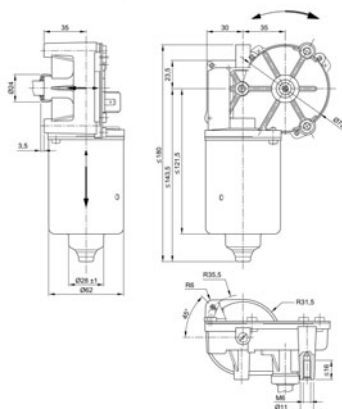
! Lefthand thread

Series SW2K
Motor type 403 958

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

0277 AR



Motor picture



Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	5.00
No-load speed [min^{-1}]	n_0	65.0
Nominal power [W]	P_N	27.2
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

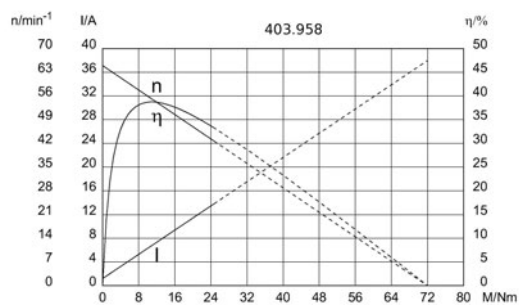
Pulses	0
Output channels	0

Other data

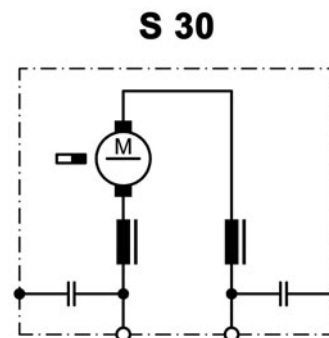
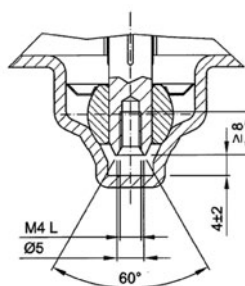
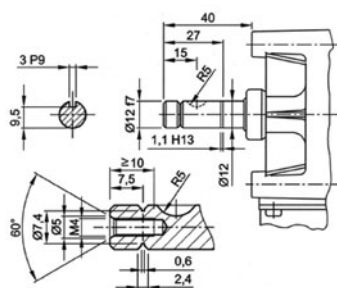
Gear ratio	63/1
Gear wheel material	Plastic
Suppression components	4.7μH, 1nF
Enclosure class	IP40
Weight [kg]	1.200

Remarks: Ball bearing

Characteristic curves

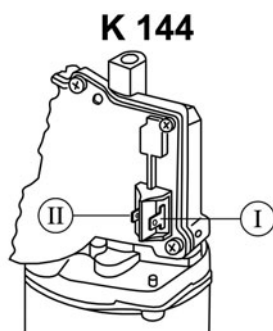


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



! Lefthand thread

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

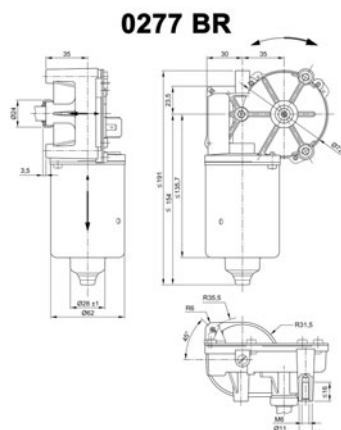


- I Blade terminal ends 6,3 x 0,8 DIN 46 244
- II Blade terminal ends 4,8 x 0,8 DIN 46 244

Notes

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	3.00
No-load speed [min^{-1}]	n_0	270.0
Nominal power [W]	P_N	68.9
Nominal current [A]	I_N	15.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

Pulses	0
Output channels	0

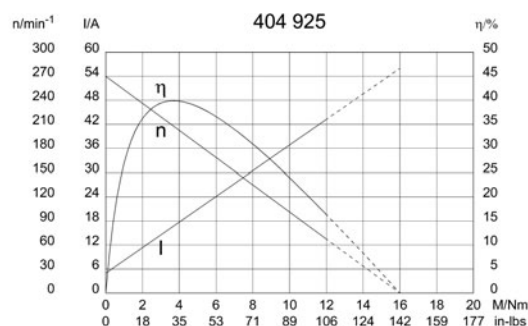
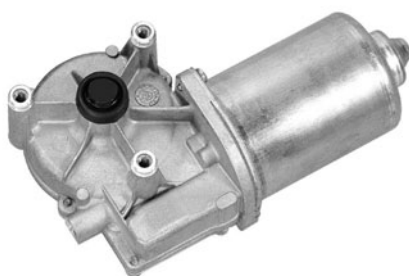
Other data

Gear ratio	70/4
Gear wheel material	plastic
Suppression components	1.9 μ H, 1 μ F
Enclosure class	IP 40
Weight [kg]	1.200

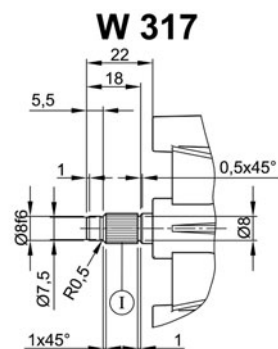
Remarks: Ball bearing

Characteristic curves

Motor picture

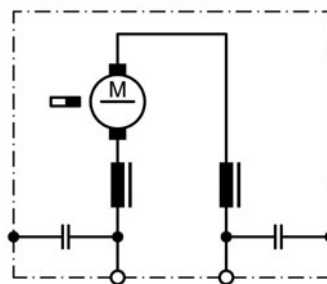


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

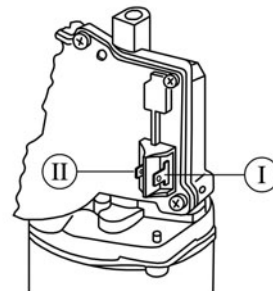


I Tapered splines 8 x 10 f
(similar DIN 5481)

S 30



K 144



I Blade terminal ends 6,3 x 0,8 DIN 46 244
II Blade terminal ends 4,8 x 0,8 DIN 46 244

Notes

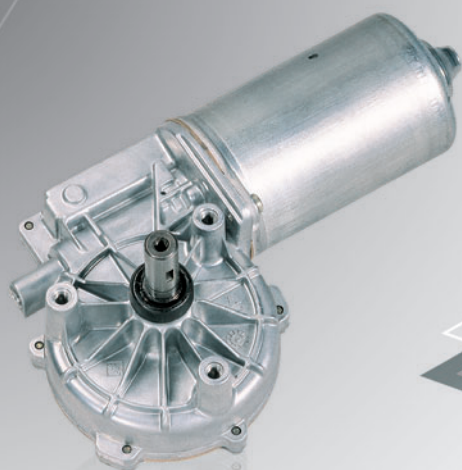
[illegible]



NIDEC MOTORS & ACTUATORS ⇄ MOTOR SERIES

0278 (SW2L)

⇄ DC MOTORS WITH WORM GEAR

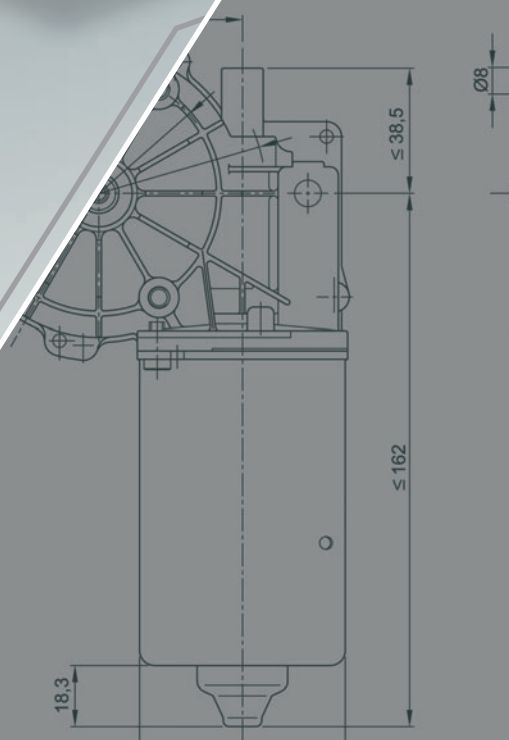


⇄ TECHNICAL DESCRIPTION

Motorhousing:	deep drawn & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	aluminium die cast
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

⇄ INDUSTRIAL APPLICATION

Gate Opener, Patient Hoist,
Machine construction



Series SW2L
Motor type 404 148

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	6.00
No-load speed [min^{-1}]	n_0	48.0
Nominal power [W]	P_N	27.9
Nominal current [A]	I_N	6.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

Pulses	0
Output channels	0

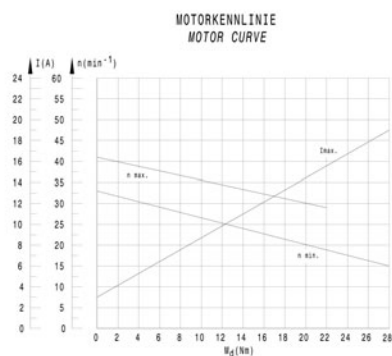
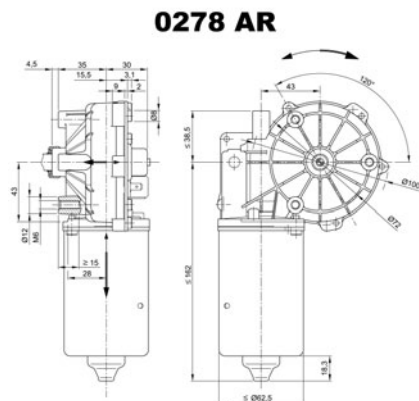
Other data

Gear ratio	74/1
Gear wheel material	plastic
Suppression components	4,7μH, 1μF
Enclosure class	IP40
Weight [kg]	1.716

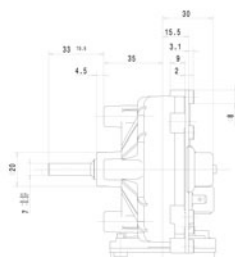
Remarks:

Characteristic curves

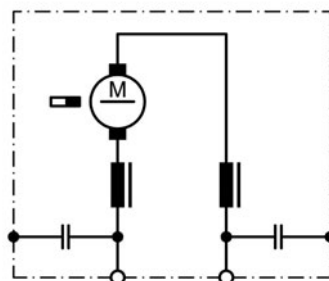
Motor picture



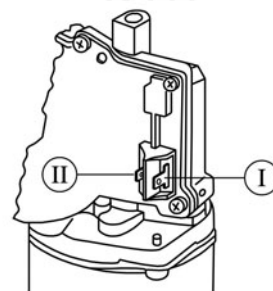
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30



K 144



- I Blade terminal ends 6,3 x 0,8 DIN 46 244
- II Blade terminal ends 4,8 x 0,8 DIN 46 244

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	8.00
No-load speed [min^{-1}]	n_0	48.0
Nominal power [W]	P_N	36.3
Nominal current [A]	I_N	5.5
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

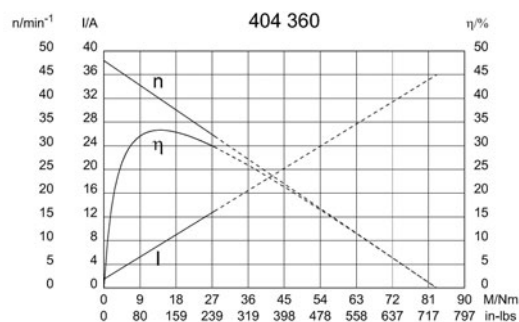
Pulses	0
Output channels	0

Other data

Gear ratio	74/1
Gear wheel material	Plastic
Suppression components	4.7 μH , 1 μF
Enclosure class	IP40
Weight [kg]	1.700

Remarks:

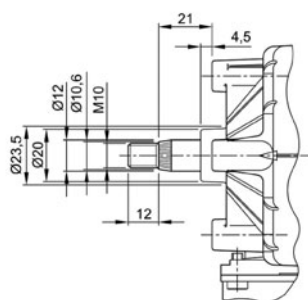
Characteristic curves



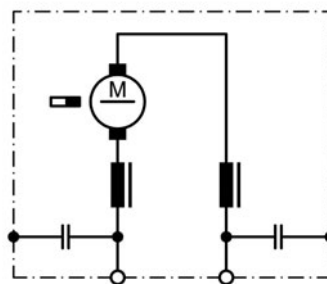
Motor picture



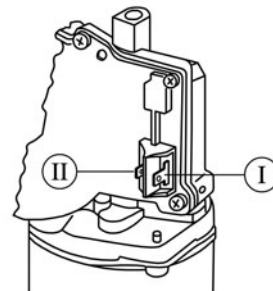
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30



K 144



- I - Blade terminal ends 6,3 x 0,8 DIN 46 244
- II - Blade terminal ends 4,8 x 0,8 DIN 46 244

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min^{-1}]	n_0	190.0
Nominal power [W]	P_N	73.1
Nominal current [A]	I_N	7.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

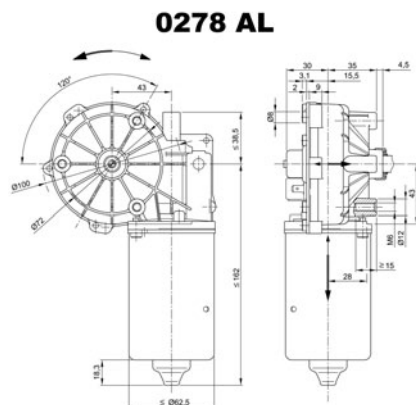
Pulses	0
Output channels	0

Other data

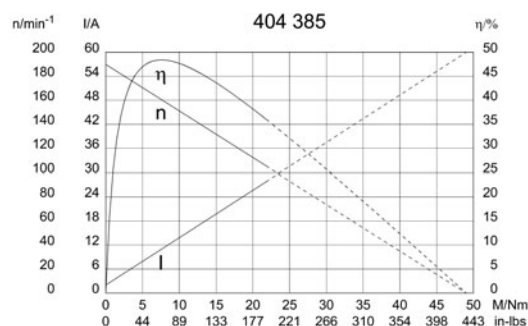
Gear ratio	103/4
Gear wheel material	plastic
Suppression components	4,7 μ H, 1nF
Enclosure class	IP 40
Weight [kg]	1.700

Remarks:

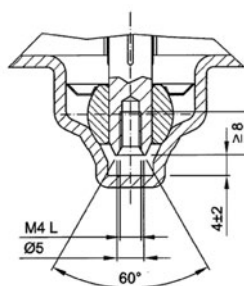
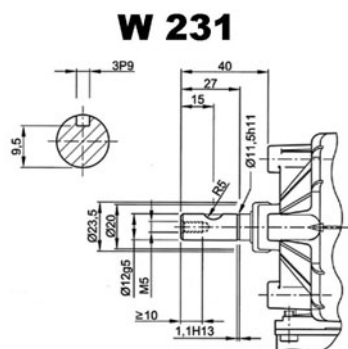
Characteristic curves



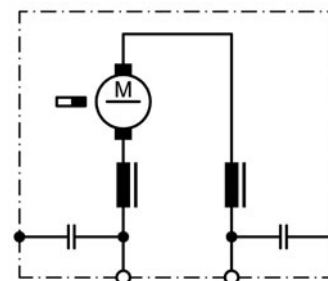
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

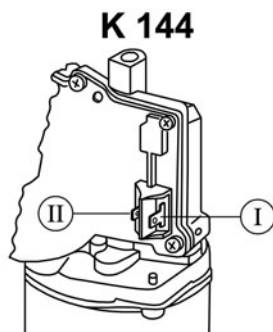


S 30



! Lefthand thread

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



- I Blade terminal ends 6,3 x 0,8 DIN 46 244
- II Blade terminal ends 4,8 x 0,8 DIN 46 244

Notes

[illegible]

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	4.00
No-load speed [min ⁻¹]	n_0	190.0
Nominal power [W]	P_N	73.1
Nominal current [A]	I_N	7.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

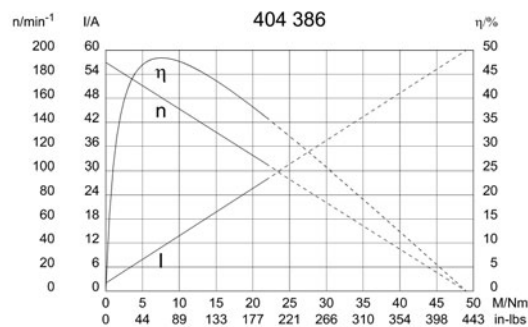
Other data	
Gear ratio	103/4
Gear wheel material	plastic
Suppression components	4,7μH, 1nF
Enclosure class	IP 40
Weight [kg]	1.700

Remarks:

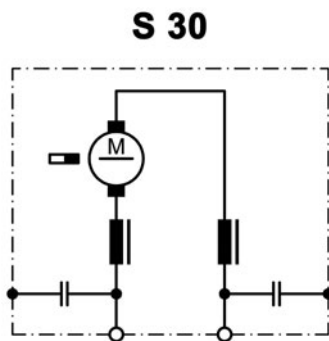
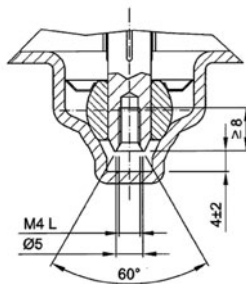
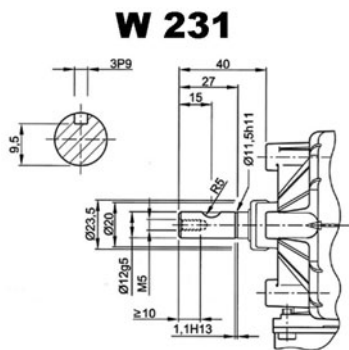
Motor picture



Characteristic curves

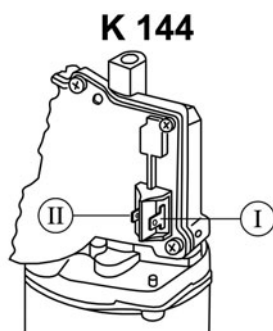


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



! Lefthand thread

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



- I Blade terminal ends 6,3 x 0,8 DIN 46 244
- II Blade terminal ends 4,8 x 0,8 DIN 46 244

Notes

This image shows a blank sheet of white paper with horizontal blue ruling lines. The lines are evenly spaced and run across the width of the page. There are no margins, text, or other markings on the paper.

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	6.00
No-load speed [min^{-1}]	n_0	48.0
Nominal power [W]	P_N	21.9
Nominal current [A]	I_N	4.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

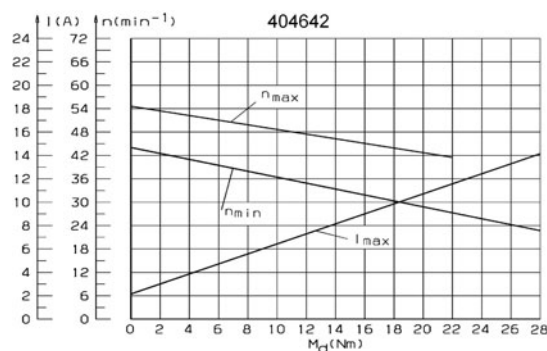
Pulses	74
Output channels	1

Other data

Gear ratio	74/1
Gear wheel material	plastic
Suppression components	4,7 μ H, 1nF
Enclosure class	IP40
Weight [kg]	1.730

Remarks:

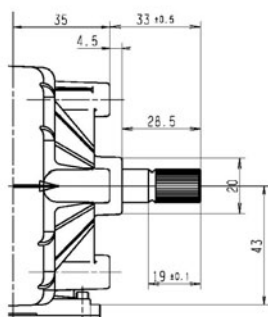
Characteristic curves



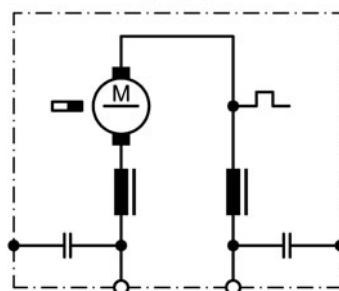
Motor picture



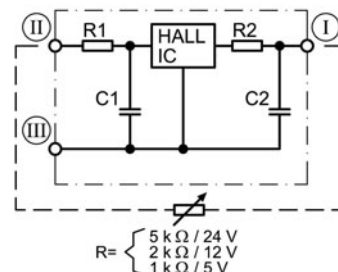
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 74



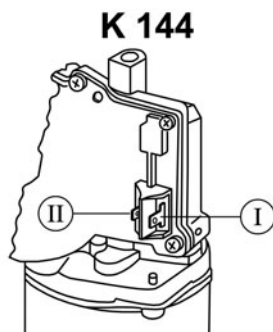
S 124



Splines: 10 x 12f (according to DIN 5481)

I Terminal 3, A
 II Terminal 4, +
 III Terminal 5, -

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



- I Blade terminal ends 6,3 x 0,8 DIN 46 244
- II Blade terminal ends 4,8 x 0,8 DIN 46 244

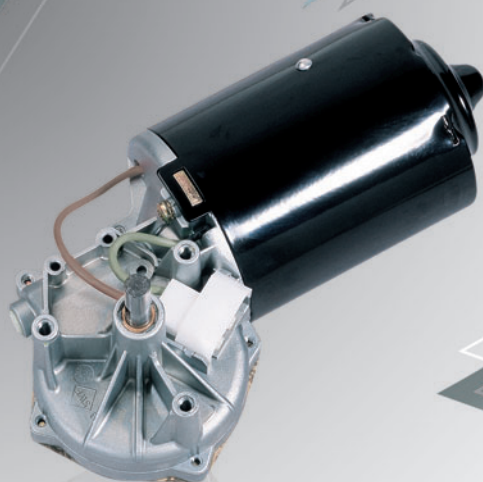
Notes

This image shows a blank sheet of white paper with horizontal ruling lines. The lines are evenly spaced and extend across the width of the page. There are no margins, text, or other markings on the paper.

This image shows a blank sheet of white paper with horizontal blue ruling lines. The lines are evenly spaced and run across the width of the page. There are no margins, text, or other markings on the paper.

0291 (SWMV)

••• DC MOTORS WITH WORM GEAR

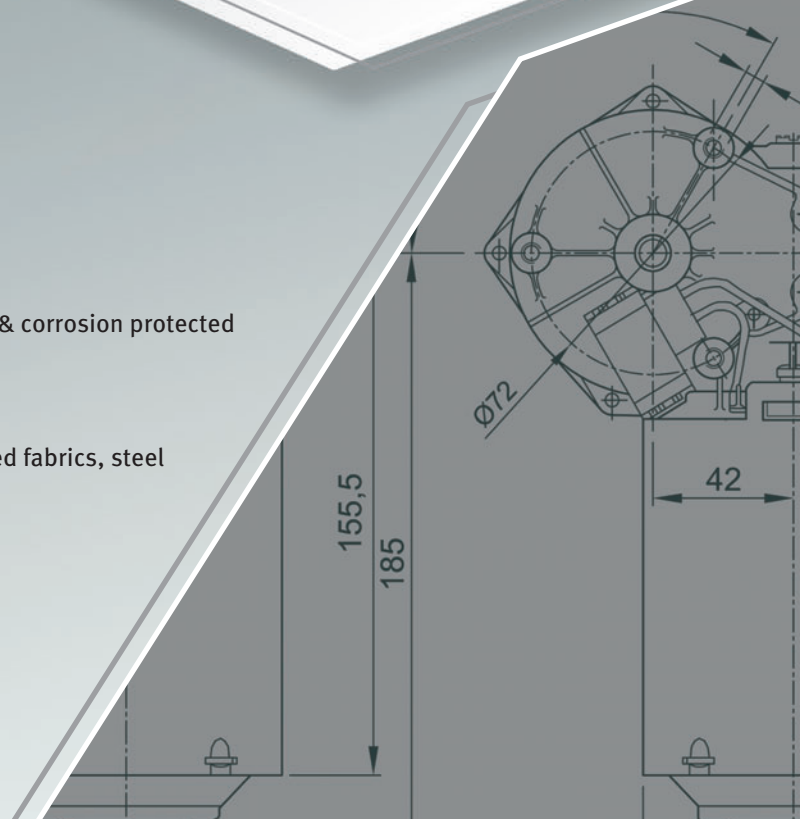


••• TECHNICAL DESCRIPTION

Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	zinc die cast
Gear wheel material:	plastic, resin bonded fabrics, steel
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	connector or leads
Sensor:	—
Thermal protection:	—
EMC suppression:	optional

••• INDUSTRIAL APPLICATION

Machine construction



Series SWMV

Motor type 402 523

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	6.00
No-load speed [min^{-1}]	n_0	67.0
Nominal power [W]	P_N	38.5
Nominal current [A]	I_N	5.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

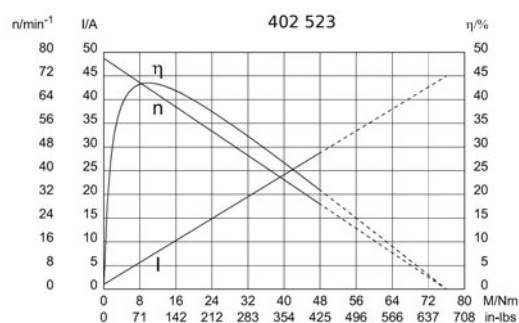
Pulses	0
Output channels	0

Other data

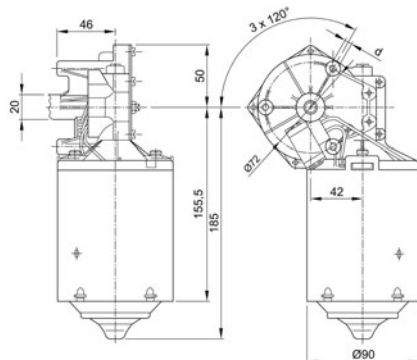
Gear ratio	46/1
Gear wheel material	Bronze
Suppression components	
Enclosure class	IP20
Weight [kg]	2.900

Remarks:

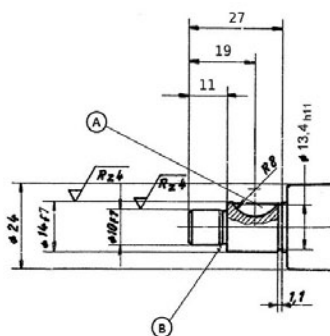
Characteristic curves



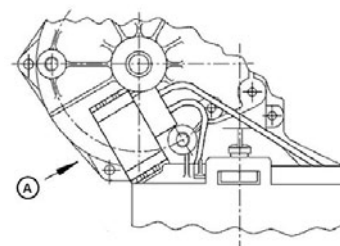
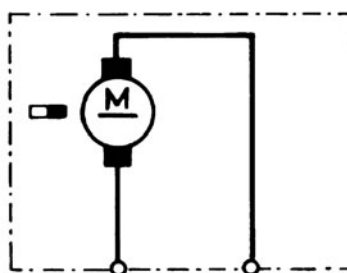
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 28



A: keyway 5 - P9 width tolerance
 B: undercut E 0.6 x 0.2 to DIN 509

A: spade ends 6.3 x 0.8 (according to DIN 46 244)

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	8.00
No-load speed [min^{-1}]	n_0	78.0
Nominal power [W]	P_N	58.5
Nominal current [A]	I_N	6.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

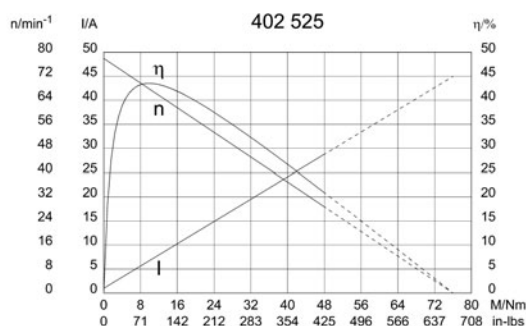
Pulses	0
Output channels	0

Other data

Gear ratio	46/1
Gear wheel material	Resinbonded fabric
Suppression components	
Enclosure class	IP 20
Weight [kg]	2.900

Remarks: d = M6x16mm

Characteristic curves

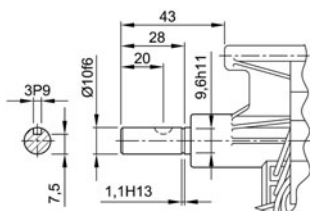


Motor picture

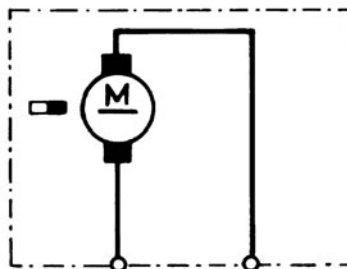


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

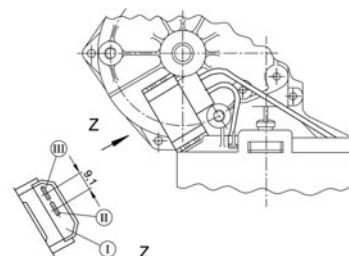
W 278



S 28



K 243



Flat plug 6.8x0.8 DIN 46244 mating with receptacle for tabs and connector housing 163 006-1, drwg C163006, www.tycoelectronics.com

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	12
Nominal torque [Nm]	M_N	6.00
No-load speed [min^{-1}]	n_0	52.0
Nominal power [W]	P_N	29.7
Nominal current [A]	I_N	6.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

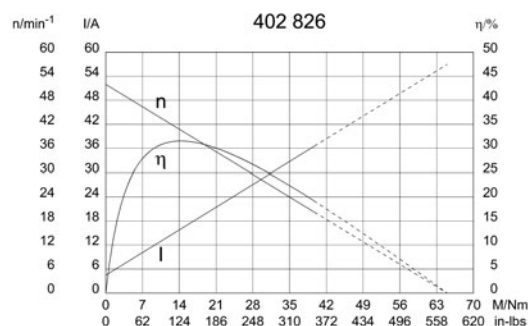
Pulses	0
Output channels	0

Other data

Gear ratio	59/1
Gear wheel material	Resinbonded fabric
Suppression components	
Enclosure class	IP 20
Weight [kg]	2.900

Remarks: d = M6x16mm

Characteristic curves

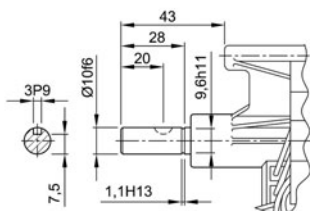


Motor picture

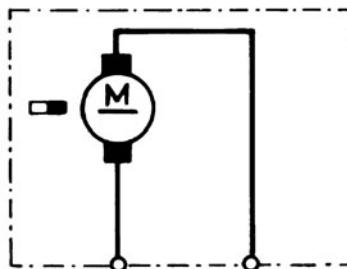


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

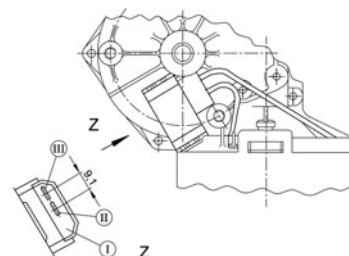
W 278



S 28



K 243



Flat plug 6,8x0,8 DIN 46244 mating with
 receptacle for tabs and connector housing 163
 006-1, drwg C163006, www.tycoelectronics.com

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	8.00
No-load speed [min^{-1}]	n_0	47.0
Nominal power [W]	P_N	34.9
Nominal current [A]	I_N	11.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

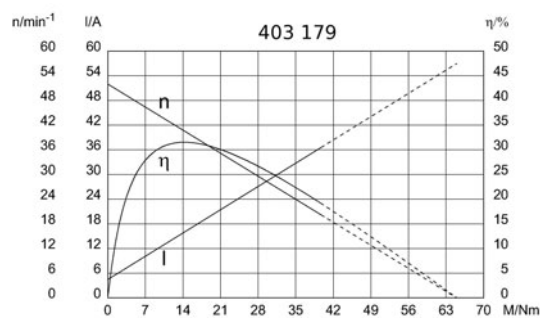
Pulses	0
Output channels	0

Other data

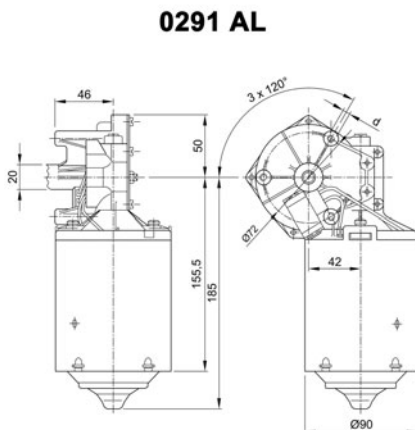
Gear ratio	59/1
Gear wheel material	Bronze
Suppression components	5.0 μ H
Enclosure class	IP20
Weight [kg]	2.900

Remarks:

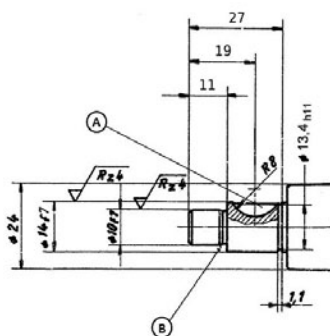
Characteristic curves



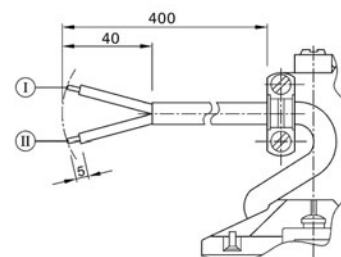
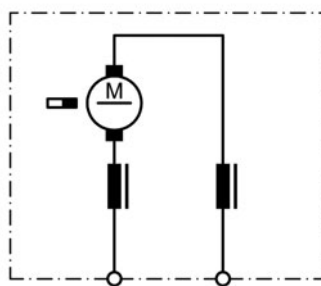
Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 27



A: keyway 5 - P9 width tolerance
 B: undercut E 0.6 x 0.2 to DIN 509

I: red
 II: green

Series SWMV

Motor type 403 334

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	3.00
No-load speed [min^{-1}]	n_0	220.0
Nominal power [W]	P_N	65.7
Nominal current [A]	I_N	8.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

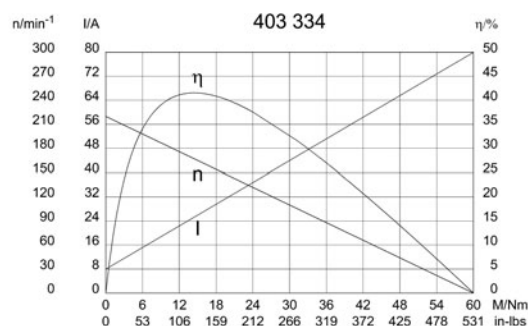
Pulses	0
Output channels	0

Other data

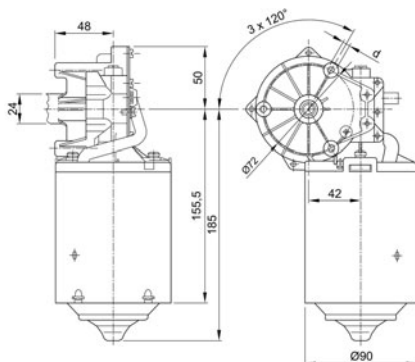
Gear ratio	44/2
Gear wheel material	plastic
Suppression components	6,5 μ H, 1nF
Enclosure class	IP 20
Weight [kg]	2.900

Remarks: d = M8 x 16 mm

Characteristic curves



0291 BL

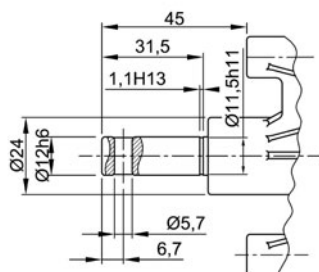


Motor picture

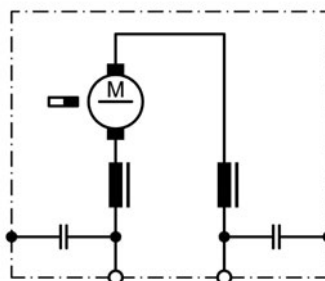


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

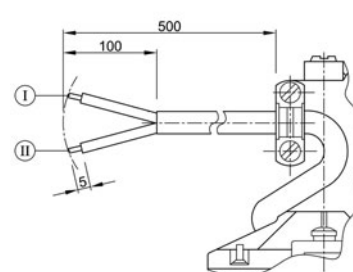
W 070



S 30



K 274



I red
 II green

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	5.00
No-load speed [min^{-1}]	n_0	52.0
Nominal power [W]	P_N	25.7
Nominal current [A]	I_N	5.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

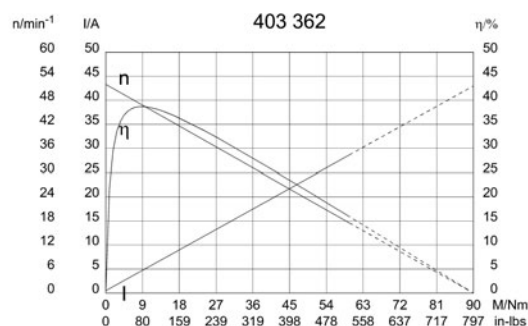
Pulses	0
Output channels	0

Other data

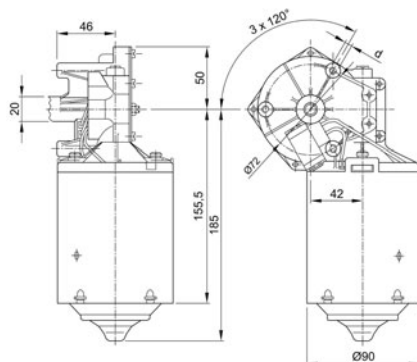
Gear ratio	59/1
Gear wheel material	Resinbonded fabric
Suppression components	
Enclosure class	IP 20
Weight [kg]	2.900

Remarks: d = M8 x 23mm

Characteristic curves



0291 AL

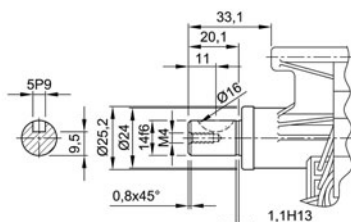


Motor picture

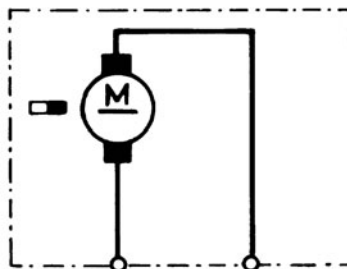


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

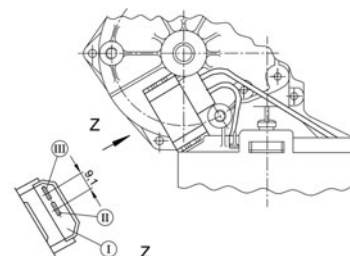
W 126



S 28



K 243



Flat plug 6.8x0.8 DIN 46244 mating with receptacle for tabs and connector housing 163 006-1, drwg C163006, www.tycoelectronics.com

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	8.00
No-load speed [min^{-1}]	n_0	48.0
Nominal power [W]	P_N	36.0
Nominal current [A]	I_N	7.0
Nominal force [kN]	F_N	0.00
Duty cycle	s1	

Sensor data

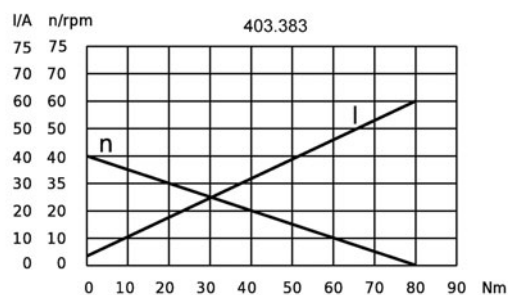
Pulses	0
Output channels	0

Other data

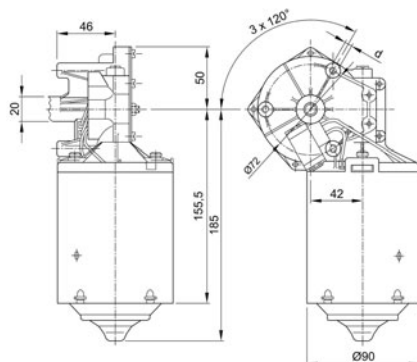
Gear ratio	46/1
Gear wheel material	bronze
Suppression components	
Enclosure class	IP20
Weight [kg]	2.900

Remarks: d=M8x23

Characteristic curves



0291 AL

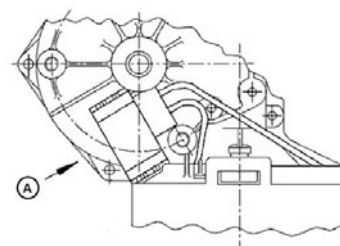
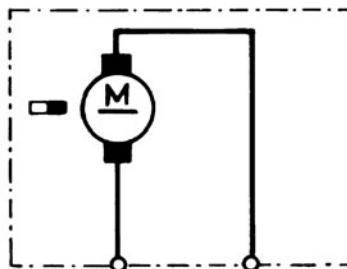
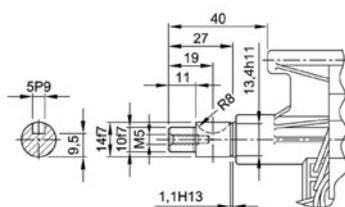


Motor picture



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

S 28



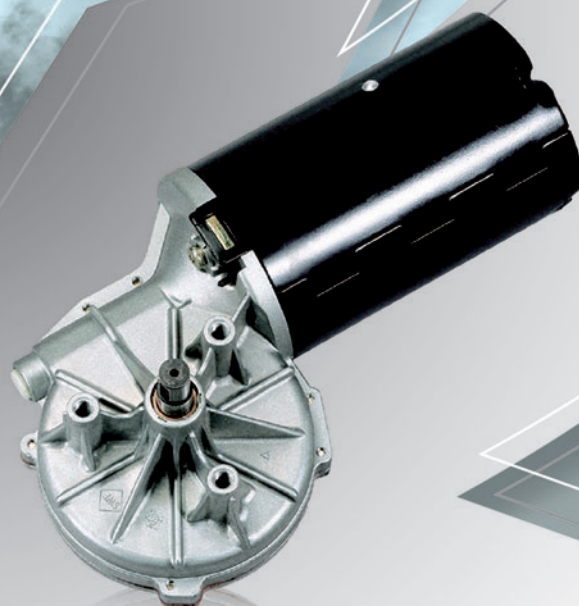
A: spade ends 6.3 x 0.8 (according to DIN 46 244)



NIDEC MOTORS & ACTUATORS ❖❖❖ MOTOR SERIES

0292 (SWMG)

❖❖❖ DC MOTORS WITH WORM GEAR

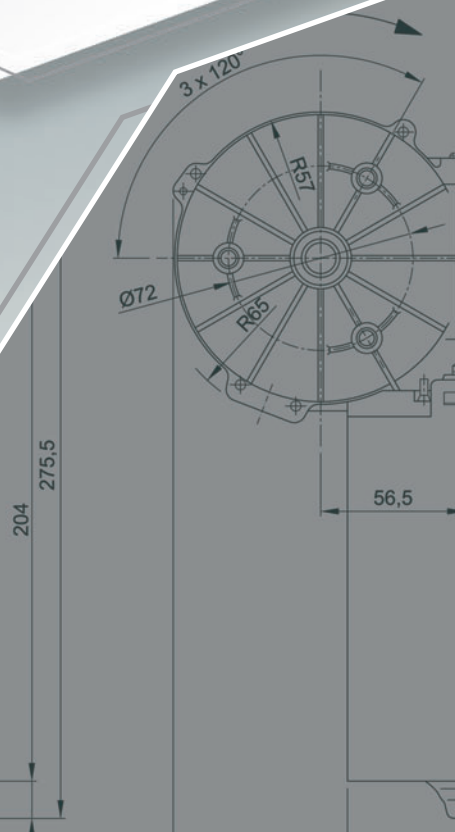


❖❖❖ TECHNICAL DESCRIPTION

Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	zinc die cast
Gear wheel material:	plastic, resin bonded fabrics, steel
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

❖❖❖ INDUSTRIAL APPLICATION

Machine construction



Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Ball

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	20.0
No-load speed [min^{-1}]	n_0	27.0
Nominal power [W]	P_N	44.0
Nominal current [A]	I_N	6.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

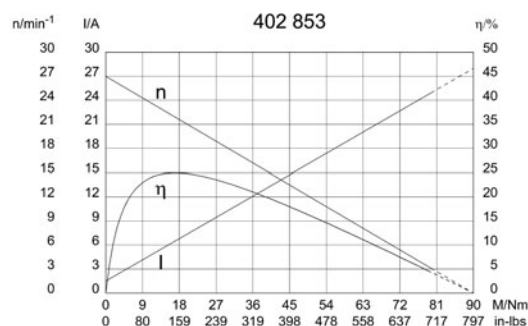
Pulses	0
Output channels	0

Other data

Gear ratio	50/1
Gear wheel material	plastic
Suppression components	
Enclosure class	IP 20
Weight [kg]	4.200

Remarks:

Characteristic curves

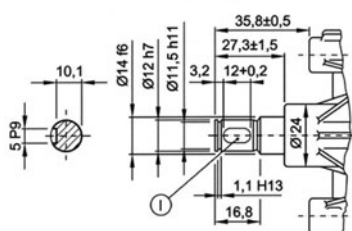


Motor picture

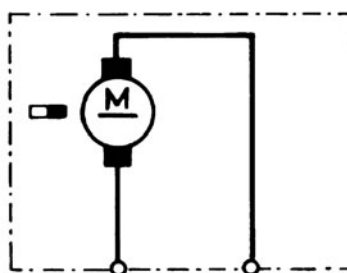


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

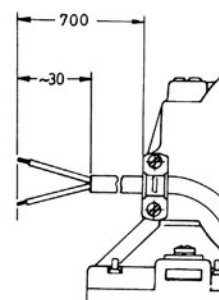
W 110



S 28



K 86



I Groove for feather key A 5x3x12 DIN 6885

Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data

Rated voltage [V]	U_N	24
Nominal torque [Nm]	M_N	10.0
No-load speed [min^{-1}]	n_0	165.0
Nominal power [W]	P_N	156
Nominal current [A]	I_N	5.0
Nominal force [kN]	F_N	0.00
Duty cycle		s1

Sensor data

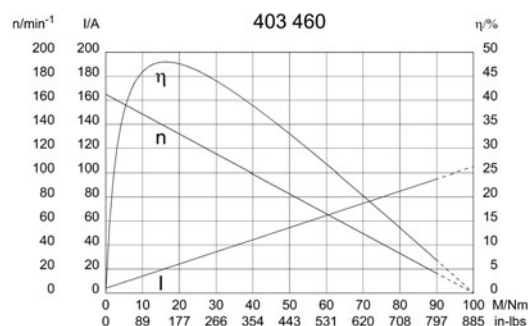
Pulses	0
Output channels	0

Other data

Gear ratio	43/3
Gear wheel material	plastic
Suppression components	
Enclosure class	IP 20
Weight [kg]	4.200

Remarks:

Characteristic curves

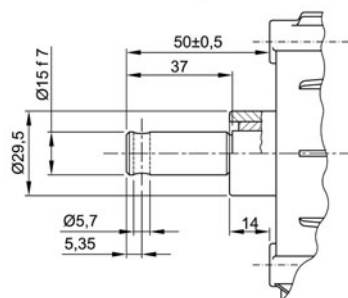


Motor picture

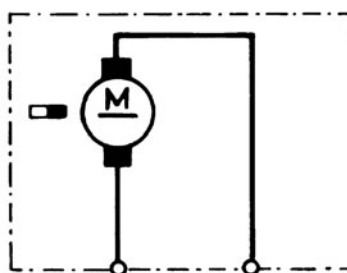


Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

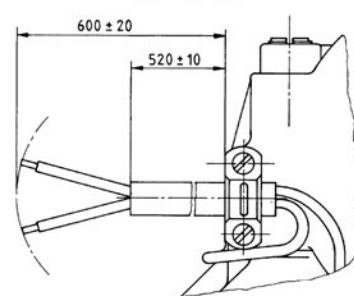
W 167



S 28



K 123



Notes

[illegible]

Notes

[illegible]

Notes

[illegible]

<i>Type No.</i>	<i>Page</i>	<i>Type No.</i>	<i>Page</i>	<i>Type No.</i>	<i>Page</i>
402 523	191	404 157	68	404 905	55
402 525	192	404 166	69	404 907	57
402 600	149	404 203	160	404 910	75
402 743	150	404 284	17	404 925	179
402 757	35	404 326	38	404 938	135
402 781	36	404 327	39	404 961	111
402 826	193	404 360	182	404 965	30
402 853	199	404 382	18	404 966	31
402 887	151	404 384	19	404 967	32
402 907	37	404 385	183	404 980	59
402 944	7	404 386	185	404 983	135
		404 465	41	404 987	112
403 179	194	404 469	25	404 988	114
403 187	8	404 476	9	404 990	116
403 194	79	404 536	26	404 991	118
403 279	80	404 596	27	404 992	137
403 280	81	404 603	70		
403 281	82	404 621	28	405 002	120
403 290	83	404 636	42	405 006	121
403 304	84	404 642	187	405 031	60
403 334	195	404 682	49	405 032	139
403 362	196	404 694	71	405 033	141
403 383	197	404 722	44	405 054	123
403 389	152	404 743	11	405 060	143
403 438	153	404 744	13	405 061	62
403 460	200	404 747	50	405 063	145
403 474	155	404 748	51	405 072	125
403 475	156	404 753	20	405 091	95
403 559	157	404 757	21	405 092	97
403 567	158	404 763	72	405 197	127
403 712	85	404 764	53	405 228	64
403 790	159	404 774	74	405 237	98
403 854	163	404 846	91	405 251	129
403 930	165	404 847	93	405 504	46
403 931	167	404 854	101		
403 933	169	404 864	103		
403 936	171	404 865	104		
403 939	172	404 866	106		
403 957	174	404 867	108		
403 958	176	404 868	109		
		404 872	110		
404 003	86	404 880	22		
404 127	88	404 885	133		
404 148	181	404 890	29		
404 156	67	404 904	54		

NIDEC MOTORS & ACTUATORS WORLDWIDE DISTRIBUTORS



Innovatech Solutions Pty Ltd.
19 Northwind Avenue
2250 Point Clare, NSW
Australia

Tel. +61 2 43 22 39 62
Fax +61 2 43 22 39 62
rkutter@innovatechsolutions.com.au
www.innovatechsolutions.com.au



Kwapil Co. GmbH
Kammelweg 9
1210 Wien
Austria

Tel. +43 12 78 85 85
Fax +43 12 78 85 86
verkauf@kwapil.com
www.kwapil.com



Eisses Import B.V.
Admiraal Trompstraat 11
3115 HK Schiedam
Holland

Tel. +31 1 02 46 00 18
Fax +31 1 02 46 00 19
info@eissesbv.nl
www.eissesbv.nl



Drive Systems Group
7150 Torbram Road, No 1 & 2
L4T 3Z8 Mississauga, ON
Canada

Tel. +1 90 54 05 03 10
Fax +1 90 54 05 03 13
georger@drivesystemsgroup.com
www.drivesystemsgroup.com



Opis Engineering k.s.
Selská 64
61400 Brno-Malomerice
Czech Republic

Tel. +42 05 43 33 00 55
Fax +42 05 43 24 26 53
cada@opis.cz
www.opis.cz



Bondy - LMT A&S
Grundtvigsalle 168
6400 Sønderborg
Denmark

Tel. +45 74 43 18 80
Fax +45 74 43 18 81
ej@lmttransmission.dk
www.lmttransmission.dk



Oy Movetec AB
Hannuksentie 1
02270 Espoo
Finland

Tel. +35 89 52 59 23 0
Fax +35 89 52 59 23 33
pasi.nyberg@movetec.fi
www.movetec.fi



Comotech Industries
6 rue des Blonnières
BP 82441 Haute Goulaine
44124 - VERTOU, France

Tel. +33 2 40 05 05 05
Fax +33 2 40 05 05 03
thierry.berthou@comotech.fr
www.comotech.fr



101 automation GmbH
Schallbruch 19-21
42781 Haan
Germany

Tel. +49 21 29 37 63 50
Fax +49 21 29 37 63 59
info@101automation.de
www.101automation.de



JBW GmbH
Bodenseestrasse 228
81243 München
Germany

Tel. +49 89 89 70 10 33
Fax +49 89 89 70 10 00
info@elektromotore.eu
www.elektromotore.eu



Ott GmbH & Co. KG
Baarstrasse 3
78652 Deisslingen
Germany

Tel. +49 74 20 93 99 0
Fax +49 74 20 93 99 25
info@ott-antriebe.de
www.ott-antriebe.de



Wald Antriebe GmbH
Hanns-Hoerbiger-Strasse 1
29664 Walsrode
Germany

Tel. +49 51 61 60 37 07
Fax +49 51 61 60 37 08
info@waldantriebe.de
www.waldantriebe.de



Electro Mechanical Systems Ltd
Eros House, Calleva Park, Aldermaston
Reading RG7 8LN
Great Britain

Tel. +44 11 89 81 73 91
Fax +44 11 89 81 76 13
pboughey@ems-ltd.com
www.ems-limited.co.uk



Eisses Import B.V.
Admiraal Trompstraat 11
3115 HK Schiedam
Holland

Tel. +31 1 02 46 00 18
Fax +31 1 02 46 00 19
info@eissesbv.nl
www.eissesbv.nl



Strategi Automation Solutions Pvt Ltd
Plot 25/B, Dodannakundi Indl Estate,
560048 Bangalore
India

Tel. +91 80 41 16 31 36/7
Fax +91 80 41 16 30 47
arun@strategiautomation.com
www.strategiautomation.com



Mechatronics Ltd.
P.O. Box 3818
49130 Petach-Tikva
Israel

Tel. +97 2 39 28 88 88
Fax +97 2 39 28 88 80
office@mechatronics.co.il
www.mechatronics.co.il



Motech s.r.l.
Via delle Nazioni, 87
41100 Modena
Italy

Tel. +39 59 45 42 96
Fax +39 59 45 16 93
m.coda@motech-italia.com
www.motech-italia.com



Nidec-Shimpo Corp
1 Terada Kohtari, Nagaokakyo City
617-0833 Kyoto
Japan

Tel. +81 7 59 58 38 86
Fax +81 7 59 58 36 48
shinichi.takahashi@nidec-shimpo.co.jp
www.nidec-shimpo.co.jp



Eisses Import B.V.
Admiraal Trompstraat 11
3115 HK Schiedam
Holland

Tel. +31 1 02 46 00 18
Fax +31 1 02 46 00 19
info@eissesbv.nl
www.eissesbv.nl



Aratron AS
Bjørnerudveien 17
1266 Oslo
Norway

Tel. +47 23 19 16 60
Fax +47 23 19 16 61
christer@aratron.no
www.aratron.no



Opis Engineering, s.r.o
Lucna 476
03202 Zavazna Poruba
Slovakia

Tel. +42 14 45 54 72 34
Fax +42 14 45 54 72 34
opis@opis.sk
www.opis.sk



Motech Iberica
Avda. de Las Cortes Valencianas, 41, 1º G
46015 Valencia
Spain

Tel. +34 9 63 45 54 05
Fax +34 9 63 46 59 31
jnavarro@motech.es
www.motech.es



KG Knutsson AB
Hammarbacken 8
19181 Sollentuna
Sweden

Tel. +46 8 92 30 20
Fax +46 8 92 33 66
dan.kimblad@kgk.se
www.kgk.se



Antrimon AG
Luzernerstrasse 91
5630 Muri (AG)
Switzerland

Tel. +41 5 66 75 40 30
Fax +41 5 66 75 40 31
info@antrimon.ch
www.antrimon.ch



S-MIKRON LTD. ŞTİ.
Nilüfer Ticaret Merkezi 66. Sokak No:8
16110 Nilüfer-BURSA
Turkey

Tel. +90 22 44 43 52 33 (Pbx)
Fax +90 22 44 43 52 42
info@s-mikron.com.tr
www.s-mikron.com.tr



Burns Controls Comp.
13735 Beta Road
Dallas TX 75244
USA

Tel. +1 97 22 33 67 12
Fax +1 97 22 33 80 39
burns@burnscontrols.com
www.burnscontrols.com



Power Electric
15300 25th Ave North, Suite 400
Plymouth MN 55447
USA

Tel. +1 76 35 53 10 90
Fax +1 76 35 53 12 42
nbohn@powerelectric.com
www.powerelectric.com

For current information, product downloads and up-to-date news and in-depth drive selection assistance, log on to our new website! Find your perfect drive with just one click: www.nidec-ma.com



- Comfortable seating thanks to the many adjuster motors in the seats.
- Motors in the sliding roof to let the sun in, and to move the roller sun blind, to keep it out.
- Electrically adjustable steering columns for optimum ergonomics.
- Adjustable spoiler for improved driving safety at higher speeds.
- Automatically controlled opening and closing of sliding doors, trunk lids or tailgates.
- Active Safety for driving and braking owing to motors in the ABS/ESP system.

**NIDEC Motors & Actuators for comfort and safety in the automobile.
We get things moving.**

